Statistical Learning– MATH 6333 Set 9 (Unsupervised Learning)

Tamer Oraby UTRGV tamer.oraby@utrgv.edu

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* Last updated December 1, 2021

Training data: $T = \{(x_{i1}, x_{i2}, ..., x_{ip}) : i = 1, 2, ..., n\}$

Exploratory data analysis: No output and no model function f.

Goal of Unsup.L.: To describe the relationship between the $x_{i1}, x_{i2}, \ldots, x_{ip}$ of training data $\{(x_{i1}, x_{i2}, \ldots, x_{ip}) : i = 1, 2, \ldots, n\}$

Testing: To describe the relationship between the $x_{j1}, x_{j2}, \ldots, x_{jp}$ of testing data $\{(x_{j1}, x_{j2}, \ldots, x_{jp}) : j = 1, 2, \ldots, m\}$ of a known relationship.

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- Cluster Analysis
- Hierarchical Clustering
- Principal Component Analysis (PCA)

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- The idea is that some data points are clustered with each others more than other points.
- ► Those points can be described to be cluttered around a cluster centroid c_k for k = 1, 2, ..., K. They could be c_k = µ_k the mean in the K-means OR c_k = X_{i(k)} one of the data points in the K-medoid.
- Q How to measure the closeness to the centroid?
- A using the sum of squares of errors

$$SSE(\mathcal{C}) = \sum_{k=1}^{K} \sum_{X_i \in C_k} \underbrace{||X_i - \mu_k||^2}_{ ext{dissimilarity function}}$$

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Other distance functions or (dis)similarity functions are also available to be used in the error function.

Euclidean distance:

$$d_2(x,y) = ||x - y||_2$$

Manhattan distance:

$$d_1(x,y) = ||x - y||_1$$

Correlation (Pearson or Spearman)-based distance:

$$d_{corr}(x, y) = 1 - Corr(x, y)$$

If *x* and *y* are standardized then it is called Eisen-cosine correlation distance.

They are almost the same if the data is standardized which is advised to do at the beginning of the analyses.

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Jensen-Shannon divergence:

$$d_{JS}(x,y) = \frac{1}{2}(d_{KL}(x,y) + d_{KL}(y,x))$$

where

$$d_{KL}(x,y) = \sum_{i=1}^{n} x_i \log(\frac{x_i}{y_i})$$

is the Kullback-Leibler divergence (relative entropy) that measures the lost information when we use *x* to represent *y*.

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Brute-Force (exhaustive) Algorithm

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Brute-Force (exhaustive) Algorithm

• Generate all of the ($\sim K^n/K!$) possible partitions C.

For each possible partition, calculate $\{\mu_k, k = 1, 2, ..., K\}$

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- ► Calculate *SSE*(*C*), for all *C*'s
- ▶ The optimal cluster $C^* = argmin_C SSE(C)$

What do you think?

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K-means Clustering Algorithm

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K-means Clustering Algorithm

It is a recursive greedy algorithm to minimize SSE.

Initialize Start with a randomly generated centroids $\{\mu_k, k = 1, 2, \dots, K\}$

Iterative Assign X_i to cluster C_{k*} for which

 $k^* = \operatorname{argmin}_{1 \le k \le K} ||X_i - \mu_k||^2$

- After assigning all of the $X_i's$, update the centroids $\{\mu_k, k = 1, 2, ., K\}$ (averages)
- continue the iterations till $max_k ||\mu_k^{new} \mu_k^{old}|| < TOL$

Repeat the whole algorithm several times for randomly generated initial centroids (Monte Carlo alg.) and find the smallest

$$SSE(C) = \sum_{k=1}^{K} \sum_{X_i \in C_k} ||X_i - \mu_k||^2 = \sum_{k=1}^{K} \sum_{i=1}^{n} I(X_i \in C_k) ||X_i - \mu_k||^2$$

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Simulation Example: See code cluster.R



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Simulation Example: See code cluster.R



Example: See code cluster.R

kmeans(dataframe, centers, iter.max = 10, nstart = 1, algorithm = c("Hartigan-Wong", "Lloyd", "Forgy", "MacQueen"), trace=FALSE)



Kernel K-means Clustering Algorithm

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Kernels K-means Clustering Algorithm

Using kernels like $K(x, y) = h(x)^T h(y)$ so that

$$SSE(\mathcal{C}) = \sum_{k=1}^{K} \sum_{X_i \in C_k} ||h(X_i) - \mu_k^h||^2$$

where

$$\mu_k^h = \frac{1}{|C_k|} \sum_{X_j \in C_k} h(X_j)$$

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Kernels K-means Clustering Algorithm

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$$h(X_i) - \mu_k^h = h(X_i) - rac{1}{|C_k|} \sum_{X_j \in C_k} h(X_j)$$

 $= rac{1}{|C_k|} \sum_{X_j \in C_k} (h(X_i) - h(X_j))$

and

$$\begin{split} ||h(X_i) - \mu_k^h||^2 &= (h(X_i) - \mu_k^h)^T (h(X_i) - \mu_k^h) \\ &= \frac{1}{|C_k|^2} \sum_{X_j \in C_k} \sum_{X_\ell \in C_k} (h(X_i) - h(X_j))^T (h(X_i) - h(X_\ell)) \\ &= \frac{1}{|C_k|^2} \sum_{X_j \in C_k} \sum_{X_\ell \in C_k} (K(X_i, X_i) - 2K(X_i, X_j) + K(X_j, X_\ell)) \end{split}$$

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K-means and Kernel K-means Clustering Algorithm

DIY in R

- 1. Carry out K-means Cluster analysis using *kmeans* on the gene data. Use different maximum number of iterations *iter.max* and different number of initial points *nstart*.
- 2. Carry out kernel K-means Cluster analysis using *kkmeans* in the library *kernlab* on the gene data.

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- At the top, there is one cluster that contains all of the data points which sequentially divides up till it ends with n clusters that contain one observation at the bottom.
- Two approaches: divisive (top-bottom) and agglomerative (bottom-up)

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Results are represented Using a dendrogram

Agglomerative (bottom-up)

Example



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Agglomerative (bottom-up)

Example



Agglomerative (bottom-up)

- Initially start with n clusters with one of the observations in each one of them.
- At each step, merge the closest two clusters to reduce the number of clusters by one.

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Closeness is measured using a dissimilarity function.

Divisive (top-bottom)

- Initially start with 1 cluster with the n observations in it.
- At each step, divide the farthest two clusters to increase the number of clusters by one.
- Distances are measured using a dissimilarity function.

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Agglomerative (bottom-up)

Example

Algorithm 12.3 Hierarchical Clustering

- 1. Begin with n observations and a measure (such as Euclidean distance) of all the $\binom{n}{2} = n(n-1)/2$ pairwise dissimilarities. Treat each observation as its own cluster.
- 2. For $i = n, n 1, \dots, 2$:
 - (a) Examine all pairwise inter-cluster dissimilarities among the *i* clusters and identify the pair of clusters that are least dissimilar (that is, most similar). Fuse these two clusters. The dissimilarity between these two clusters indicates the height in the dendrogram at which the fusion should be placed.
 - (b) Compute the new pairwise inter-cluster dissimilarities among the i-1 remaining clusters.

Agglomerative (bottom-up)

Example



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Agglomerative (bottom-up)

Example



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Agglomerative (bottom-up)

Example



 X_1

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Types of dissimilarities (linkage) between clusters

Single linkage:

$$d_{single}(C_1, C_2) = \min_{i \in C_1, j \in C_2} d(x_i, x_j)$$

But, resulting clusters could be highly spread out points (non-compact).

Complete linkage:

$$d_{complete}(C_1, C_2) = \max_{i \in C_1, j \in C_2} d(x_i, x_j)$$

But, resulting clusters could be compact but not enough far apart.

Average linkage:

$$d_{single}(C_1, C_2) = rac{1}{|C_1| |C_2|} \sum_{i \in C_1, j \in C_2} d(x_i, x_j)$$

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It strikes a balance between both.

Agglomerative (bottom-up)

Example



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Agglomerative (bottom-up)

Example



Agglomerative (bottom-up)

Example



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- Goal: To find the best *q* linear approximations to a set of data *x_i* ∈ ℝ^p for *i* = 1, 2, ..., *N*, where *q* ≤ *p*.
- Assume that x_i is centered; that is, x
 _i = 0. (Actually, it must be standardized.)
- The presentation of

$$x_i = f(\lambda) = \mu + V_q \lambda$$

where V_q is a $p \times q$ orthogonal matrix ($V_q^T V_q = I_q$), λ is $q \times 1$ parameter vector, and μ is $p \times 1$ parameter vector, could be found by minimizing the recostruction error

$$\min_{\mu,\{\lambda_i\},V}\sum_{i=1}^N ||x_i - \mu - V_q\lambda_i||^2$$

Assuming V_q is given, then $\hat{\mu} = \bar{x} = 0$ and $\hat{\lambda}_i = V_q^T(x_i - \bar{x}) = V_q^T x_i$, and the the problem becomes

$$\min_{V_q} \sum_{i=1}^{N} ||x_i - H_q x_i||^2$$

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where $H_q = V_q V_q^T$ is a projection matrix.

▶ where the rank-*q* reconstruction $H_q x_i$ is the orthogonal projection of $x_i \in \mathbb{R}^p$ into the space spanned by the columns of V_q

- Consider the $N \times p$ data matrix X
- Using SVD of X = U_{N×p} D_p V^T_{p×p} with diagonal matrix D_p with elements (singular values) d₁ ≥ d₂ ≥ d₃ ≥ ··· ≥ d_p ≥ 0, and
- $U^T U = I_p$ where column u_j is called left singular vector
- V^T V = I_p where column v_j is called right singular (loadings) vector
- V_q is the first *q* columns of *V*
- principal components of X are the columns of UD

- The *N* optimal $\hat{\lambda}_i = V_q^T x_i$ are the rows of *UD* which are the first *q* principal components.
- Xv₁ has the highest variance among all linear combinations of the features and Xv₂ has the highest variance among all linear combinations Xv of the features such that v is orthogonal to v₁.
- Elements of Xv_j are called the scores of the jth principal component.



FIGURE 14.20. The first linear principal component of a set of data. The line minimizes the total squared distance from each point to its orthogonal projection onto the line.

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FIGURE 14.21. The best rank-two linear approximation to the half-sphere data. The right panel shows the projected points with coordinates given by U_2D_2 , the first two principal components of the data.

Example: Arrest Data

N = 50 states with p = 4 features: Assault, Murder, and Rape as well as UrbanPop. First standardize them.



(≣)

Example: Arrest Data

N = 50 states with p = 4 features: Assault, Murder, and Rape as well as UrbanPop. First standardize them.

	PC1	PC2
Murder	0.5358995	-0.4181809
Assault	0.5831836	-0.1879856
UrbanPop	0.2781909	0.8728062
Rape	0.5434321	0.1673186

TABLE 12.1. The principal component loading vectors, ϕ_1 and ϕ_2 , for the **USArrests** data. These are also displayed in Figure 12.1.

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Example: Arrest Data

N = 50 states with p = 4 features: Assault, Murder, and Rape as well as UrbanPop. First standardize them.



FIGURE 12.3. Left: a scree plot depicting the proportion of variance explained by each of the four principal components in the USArrests data. Right: the cumulative proportion of variance explained by the four principal components in the USArrests data.

Example: Arrest Data

N = 50 states with p = 4 features: Assault, Murder, and Rape as well as UrbanPop. First standardize them.



FIGURE 12.4. Two principal component biplots for the USArrests data. Left: the same as Figure 12.1, with the variables scaled to have unit standard deviations. Right: principal components using unscaled data. Assault has by far the largest loading on the first principal component because it has the highest variance among the four variables. In general, scaling the variables to have standard deviation one is recommended.
Example: Handwriting digits

- The pictures digitized into 16x16 gray scale images and images of 658 handwritten 3's are the x_i 's in \mathbb{R}^{256} . SVD is calculated for the 658x256 matrix *X*.
- Twelve of the 256 possible principal components account for 63%
- Fifty of the 256 possible principal components account for 90%

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Example: Handwriting digits



FIGURE 14.22. A sample of 130 handwritten 3's shows a variety of writing styles.

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Example: Handwriting digits

The first component v_1 is due to the horizontal movement. It accounts for the lengthening of the lower tail of the 3,

The second component v_2 is due to the vertical movement. It accounts for the thickness of the 3



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Example: Handwriting digits



FIGURE 14.23. (Left panel:) the first two principal components of the handwritten threes. The circled points are the closest projected images to the vertices of a grid, defined by the marginal quantiles of the principal components. (Right panel:) The images corresponding to the circled points. These show the nature of the first two principal components.

Example: Procrustes Transformations and Shape Averaging

The S letter in a signature Suresh



FIGURE 14.25. (Left panel:) Two different digitized handwritten Ss, each represented by 96 corresponding points in \mathbb{R}^2 . The green S has been deliberately rotated and translated for visual effect. (Right panel:) A Procrustes transformation applies a translation and rotation to best match up the two set of points.

Please read the example in ESL

Example: Procrustes Transformations and Shape Averaging

The S letter in a signature Suresh



FIGURE 14.26. The Procrustes average of three versions of the leading S in Suresh's signatures. The left panel shows the preshape average, with each of the shapes \mathbf{X}'_{ℓ} in preshape space superimposed. The right three panels map the preshape **M** separately to match each of the original S's.

Please read the example in ESL.

End of Set 9