## Statistical Learning– MATH 6333 Set 6 (Tree-Based Methods)

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\* Last updated November 10, 2021

Classification and Regression Tree (CART)

- Another method for regression (Y is continuous) and classification (Y is categorical).
- It produces recursively a binary partition of the input space with constant predicted outputs c<sub>m</sub> for R<sub>m</sub>.
- The predicted regression surface

$$\hat{f}(x) = \sum_{m=1}^{5} \hat{c}_m I((X_1, X_2) \in R_m)$$



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If Y is continuous, then ĉ = {ĉ<sub>m</sub>, m = 1, 2, ..., M} could be found using the method of least squares by minimizing

$$RSS(c) = \sum_{i=1}^{N} (y_i - f(x_i))^2$$

► It results in

$$\hat{c}_m = average(y_i | x_i \in R_m) = \frac{1}{N_m} \sum_{i: x_i \in R_m} y_i$$

where  $N_m = |\{i: x_i \in R_m\}|$ 

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Recursive binary splitting

selecting variable X<sub>j</sub> and cut-off point s that define the two regions

$$R_1(j, s) = \{X : X_j \le s\}$$
 and  $R_2(j, s) = \{X : X_j > s\}$ 

Then find optimal j, s using that minimize RSS

$$\min_{j,s} \left[ \min_{c_1} \sum_{i:x_i \in R_1(j,s)} (y_i - c_1)^2 + \min_{c_2} \sum_{i:x_i \in R_2(j,s)} (y_i - c_2)^2 \right]$$

lnternally, for the optimal j, s,

$$\hat{c}_1 = average(y_i | x_i \in R_1(j, s))$$

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- The algorithm continues by
  - dividing one of the resulting regions into further two divided regions via similar optimization problem and then
  - further divide one of the resulting three regions and so on and so forth till there is no more than 5 observations in each region.
  - But, when to stop growing the tree? (Large trees lead to overfitting, and small trees are less effective.)
  - May be using a threshold for RSS below which the algorithm stops splitting. But early sub-optimal stopping is possible.

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The answer is by stopping and pruning trees.

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Tree Pruning

Stopping and pruning goes by

- growing a tree T<sub>0</sub> and stop splitting when a selected minimum node size is reached.
- Prune the tree using a cost-complexity pruning, *aka* weakest link pruning. (Pruning works backward by collapsing internal (non-terminal) nodes back to get a subtree *T* ⊂ *T*<sub>0</sub>.) Let |*T*| be the number of terminal nodes in *T*.
- Find tuning parameter  $\alpha \ge 0$  (by CV) and the subtree  $T_{\alpha} \subset T_0$  that minimize the cost complexity criterion

$$C_{\alpha}(T) = \sum_{m=1}^{|T|} + \alpha |T|$$

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where 
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**Tree Pruning** 

What happens when  $\alpha$  is small or large in

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Example (Hitters data)

To predict baseball player's Salary ( $Y = \log(Salary/1, 000)$ ) based on Years in a major league and previous year's number of Hits, etc., RT gives  $T_0$ 



Example (Hitters data)

A cross-validation will find the optimal tree size |T| = 3 (number of terminal nodes.)



Tree Size

# Example (Hitters data) $T_{\alpha}$ is



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▶ If *Y* is categorical with *K* classes, then the class proportion  $\hat{p} = {\hat{p}_{mk}, m = 1, 2, ..., M}$  and  $k = 1, 2, ..., K}$  could be found to be

$$\hat{p}_{mk} = \frac{1}{N_m} \sum_{i: x_i \in R_m} I(y_i = k)$$

$$k(m) = argmax_k \hat{p}_{mk}$$

- They are found by minimizing objective functions that include different measures of impurity Q<sub>m</sub>(T)
  - 1. Misclassification error:  $\frac{1}{N_m} \sum_{i:x_i \in R_m} l(y_i \neq k) = 1 \max_k \hat{p}_{mk}$ 2. Gini index (total variance):
    - $\sum_{k \neq k'} \hat{p}_{mk} \hat{p}_{mk'} = \sum_{k=1}^{\kappa} \hat{p}_{mk} (1 \hat{p}_{mk})$  as a measure of purity which is small if the mth node is pure.
  - Cross-entropy (deviance): -∑<sup>N</sup><sub>k=1</sub> p̂<sub>mk</sub> log(p̂<sub>mk</sub>) which is small if the mth node is pure.

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Two class impurity functions with scaled cross-entropy function to go through (.5, .5)



The functions are

- 1. Misclassification error: 1 max(p, 1 p)
- 2. Gini index (total variance): 2p(1-p)
- 3. Cross-entropy (deviance):  $-p \log(p) (1-p) \log(1-p)$

#### Example (Another Heart data)

To predict heart disease HD (Y =Yes or No) based on 13 predictors Age, Sex, Chol, Thal,ChestPain, etc., CT gives  $T_0$ 



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Example (Another Heart data)

A cross-validation will find the optimal tree size |T| = 6 (number of terminal nodes.)



Tree Size

## Example (Another Heart data)

 $T_{\alpha}$  is



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## Tree-based methods vs. Linear models

#### True linear decision boundary



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#### True non-linear decision boundary



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#### Trees

- ↑ easy to interpret
- ↑ visually re-presentable
- ↑ seem to resemble human decision making
- ↑ handle categorical variables without dummy variables

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- ↓ less predictive accuracy
- ↓ sensitive to slight changes in the data (not robust)

#### **DIY** in R

- 1. Carry out a regression tree for the prostate cancer data using library(tree)
- 2. Carry out a classification tree for the SA hearth disease data using library(tree)

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## Hierarchical Mixtures of Experts (HME)

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- where  $g_i(x, \gamma_i)$  is a softmax function in x with parameters  $\gamma_i$
- and g<sub>ℓ|j</sub>(x, γ<sub>jℓ</sub>) is another softmax function in x with parameters γ<sub>jℓ</sub>
- at the terminal the output  $Y \sim P(y|x, \theta_{j\ell})$ 
  - Regression: P is normal with its parameters
    Classification: P is the logistic CDE
- Then the mixture probability of the output is

$$P(y|x, \Psi) = \sum_{j=1}^{K} g_j(x, \gamma_j) \sum_{\ell=1}^{K} g_{\ell|j}(x, \gamma_{j\ell}) P(y|x, \theta_{j\ell})$$

• where  $\Psi = (\gamma_j, \gamma_{j\ell}, \theta_{j\ell})$  is estimated using maximum likelihood methods and EM algorithm.

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at the terminal the output Y ~ P(y|x, θ<sub>jℓ</sub>)
 Regression: P is normal with its parameter
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- where  $g_i(x, \gamma_i)$  is a softmax function in x with parameters  $\gamma_i$
- and g<sub>ℓ|j</sub>(x, γ<sub>jℓ</sub>) is another softmax function in x with parameters γ<sub>jℓ</sub>
- at the terminal the output  $Y \sim P(y|x, \theta_{j\ell})$ 
  - Regression: P is normal with its parameters
  - Classification: P is the logistic CDF
- Then the mixture probability of the output is

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## End of Set 6