# Statistical Learning- MATH 6333 Set 3 (Linear Methods for Regression) 

Tamer Oraby<br>UTRGV<br>tamer.oraby@utrgv.edu

*Last updated September 29, 2021

## Linear Regression Models and Least Squares

## Linear Regression Models and Least Squares

The linear regression model

$$
f(X)=E(Y \mid X)=\beta_{0}+\beta_{1} x_{1}+\cdots+\beta_{p} x_{p}
$$

For the training data $\mathcal{T}=\left\{\left(x_{i 1}, x_{i 2}, \ldots, x_{i p}, y_{i}\right): i=1,2, \ldots, N\right\}$

$$
y_{i}=\beta_{0}+\beta_{1} x_{i 1}+\cdots+\beta_{p} x_{i, p}+\epsilon_{i}
$$

for uncorrelated $\epsilon_{i}$ 's, of variance $\sigma^{2}$.
In matrix form

$$
y=X \beta+\epsilon
$$

where $X$ is a $N \times(p+1)$ matrix with ones in the first column.

## Linear Regression Models and Least Squares

Each input $X_{j}$ (for $j=1, \ldots, p$ ) could be one of several types: 1. quantitative variable, ex: age, sales, mileage.

3. as basis expansions, ex: in a polynomial


## Linear Regression Models and Least Squares

Each input $X_{j}$ (for $j=1, \ldots, p$ ) could be one of several types:

1. quantitative variable, ex: age, sales, mileage.
2. transformation of a quantitative variable, ex: $\log ($ age $)$, $\sqrt{\text { sales, }}$ mileage ${ }^{2}$
3. as basis expansions, ex: in a polynomial

## Linear Regression Models and Least Squares

Each input $X_{j}$ (for $j=1, \ldots, p$ ) could be one of several types:

1. quantitative variable, ex: age, sales, mileage.
2. transformation of a quantitative variable, ex: $\log (a g e)$, $\sqrt{\text { sales, }}$ mileage ${ }^{2}$
3. as basis expansions, ex: in a polynomial

$$
\beta_{0}+\beta_{1} X_{1}+\beta_{2} X_{1}^{2}+\beta_{3} X_{1}^{3}
$$

## Linear Regression Models and Least Squares

4. dummy variable (factor), ex: if $G$ takes one of the levels 0 , 1, or 2 , then take $X_{j}=I(G=j)$ for $j=1,2$ and so

$$
\beta_{0}+\beta_{1} X_{1}+\beta_{2} X_{2}= \begin{cases}\beta_{0} & \text { if } \mathrm{G}=0 \\ \beta_{0}+\beta_{1} & \text { if } \mathrm{G}=1 \\ \beta_{0}+\beta_{2} & \text { if } \mathrm{G}=2\end{cases}
$$

5. interaction between variables, ex: age x mileage

## Linear Regression Models and Least Squares

4. dummy variable (factor), ex: if $G$ takes one of the levels 0 , 1, or 2, then take $X_{j}=I(G=j)$ for $j=1,2$ and so

$$
\beta_{0}+\beta_{1} X_{1}+\beta_{2} X_{2}= \begin{cases}\beta_{0} & \text { if } \mathrm{G}=0 \\ \beta_{0}+\beta_{1} & \text { if } \mathrm{G}=1 \\ \beta_{0}+\beta_{2} & \text { if } \mathrm{G}=2\end{cases}
$$

5. interaction between variables, ex: age x mileage

## Linear Regression Models and Least Squares

The method of least squares finds $\beta$ 's that minimizes residual sums of squares

$$
\begin{aligned}
\operatorname{RSS}(\beta) & =\sum_{i=1}^{N}\left[y_{i}-\left(\beta_{0}+\beta_{1} x_{i 1}+\cdots+\beta_{p} x_{i, p}\right)\right]^{2} \\
& =\sum_{i=1}^{N}\left(y_{i}-x_{i}^{T} \beta\right)^{2} \\
& =(y-X \beta)^{T}(y-X \beta) \underbrace{Y}_{X_{1}}
\end{aligned}
$$

## Linear Regression Models and Least Squares

$$
\operatorname{minimize}_{\beta} R S S(\beta)=(y-X \beta)^{T}(y-X \beta)
$$

$$
\frac{\partial R S S(\beta)}{\partial \beta}=-2 X^{\top}(y-X \beta)=0 \Longrightarrow X^{\top} X \beta=X^{\top} y .
$$



- If $X$ is full column rank (columns are linearly independent), then $X^{\top} X$ is positive definite and so non-singular, then
- Predictions

$H$ is called the hat matrix or the (orthogonal) projection matrix.


## Linear Regression Models and Least Squares

$$
\operatorname{minimize}_{\beta} R S S(\beta)=(y-X \beta)^{T}(y-X \beta)
$$

$$
\frac{\partial R S S(\beta)}{\partial \beta}=-2 X^{\top}(y-X \beta)=0 \Longrightarrow X^{\top} X \beta=X^{\top} y .
$$

$$
-\frac{\partial^{2} R S S(\beta)}{\partial \beta \partial \beta^{T}}=2 X^{\top} X
$$

- If $X$ is full column rank (columns are linearly independent), then $X^{\top} X$ is positive definite and so non-singular, then


## - Predictions


$H$ is called the hat matrix or the (orthogonal) projection matrix.

## Linear Regression Models and Least Squares

minimize $_{\beta} R S S(\beta)=(y-X \beta)^{T}(y-X \beta)$

- $\frac{\partial \operatorname{RSS}(\beta)}{\partial \beta}=-2 X^{\top}(y-X \beta)=0 \Longrightarrow X^{\top} X \beta=X^{\top} y$.
- $\frac{\partial^{2} R S S(\beta)}{\partial \beta \partial \beta^{\top}}=2 X^{\top} X$
- If $X$ is full column rank (columns are linearly independent), then $X^{\top} X$ is positive definite and so non-singular, then

$$
\hat{\beta}=\left(X^{\top} X\right)^{-1} X^{\top} y
$$

$H$ is called the hat matrix or the (orthogonal) projection
matrix.

## Linear Regression Models and Least Squares

$\operatorname{minimize}_{\beta} R S S(\beta)=(y-X \beta)^{T}(y-X \beta)$

- $\frac{\partial \operatorname{RSS}(\beta)}{\partial \beta}=-2 X^{\top}(y-X \beta)=0 \Longrightarrow X^{\top} X \beta=X^{\top} y$.
- $\frac{\partial^{2} R S S(\beta)}{\partial \beta \partial \beta^{T}}=2 X^{\top} X$
- If $X$ is full column rank (columns are linearly independent), then $X^{\top} X$ is positive definite and so non-singular, then

$$
\hat{\beta}=\left(X^{\top} X\right)^{-1} X^{\top} y
$$

- Predictions

$$
\hat{y}=X \hat{\beta}=\underbrace{X\left(X^{\top} X\right)^{-1} X^{\top}}_{H} y
$$

$H$ is called the hat matrix or the (orthogonal) projection matrix.

## Linear Regression Models and Least Squares

- If $y_{i}$ 's are uncorrelated and have variance $\sigma^{2}$, then

$$
\operatorname{Var}(\hat{\beta})=\left(X^{\top} X\right)^{-1} \sigma^{2}
$$

if $x_{i}$ 's are fixed.
$\Rightarrow$ An unbiased estimator of $\sigma^{2}$ is


## Linear Regression Models and Least Squares

- If $y_{i}$ 's are uncorrelated and have variance $\sigma^{2}$, then

$$
\operatorname{Var}(\hat{\beta})=\left(X^{\top} X\right)^{-1} \sigma^{2}
$$

if $x_{i}$ 's are fixed.

- An unbiased estimator of $\sigma^{2}$ is

$$
\begin{aligned}
\widehat{\sigma^{2}} & =\frac{R S S(\hat{\beta})}{N-p-1} \\
& =\frac{(y-X \hat{\beta})^{T}(y-X \hat{\beta})}{N-p-1} \\
& =\frac{(y-\hat{y})^{T}(y-\hat{y})}{N-p-1} \\
& =\frac{1}{N-p-1} \sum_{i=1}^{N}\left(y_{i}-\hat{y}_{i}\right)^{2}
\end{aligned}
$$

## Linear Regression Models and Least Squares

What if columns are not linearly independent?
That is, what if they are perfectly correlated

$$
X_{i}=\text { constant } \times X_{j}
$$

for some $i$ and $j$.
Then, $\hat{\beta}$ is not uniquely defined.
Solutions:

## Linear Regression Models and Least Squares

What if columns are not linearly independent?
That is, what if they are perfectly correlated

$$
X_{i}=\text { constant } \times X_{j}
$$

for some $i$ and $j$.
Then, $\hat{\beta}$ is not uniquely defined.
Solutions:

- Re-code redundant qualitative inputs
$\Rightarrow$ If $p$ is much larger than $N$, then the number of inputs $p$ is reduced by filtering.


## Linear Regression Models and Least Squares

What if columns are not linearly independent?
That is, what if they are perfectly correlated

$$
X_{i}=\text { constant } \times X_{j}
$$

for some $i$ and $j$.
Then, $\hat{\beta}$ is not uniquely defined.
Solutions:

- Re-code redundant qualitative inputs
- If $p$ is much larger than $N$, then the number of inputs $p$ is reduced by filtering.


## Statistical Inference for Linear Regression

## Statistical Inference for Linear Regression

If $\epsilon_{i}$ are iidrv such that $\epsilon_{i} \sim N\left(0, \sigma^{2}\right)$, then

$$
\begin{gathered}
\hat{\beta} \sim N\left(\beta,\left(X^{T} X\right)^{-1} \sigma^{2}\right) \\
c^{T} \hat{\beta}=\sum_{j=0}^{p} c_{j} \hat{\beta}_{j} \sim N\left(c^{T} \beta, c^{T}\left(X^{T} X\right)^{-1} c \sigma^{2}\right),
\end{gathered}
$$

for a non-zero vector $c$, and

$$
(N-p-1) \frac{\widehat{\sigma^{2}}}{\sigma^{2}} \sim \chi_{N-p-1}^{2}
$$

Moreover, $\widehat{\beta}$ and $\widehat{\sigma^{2}}$ are statistically independent. Thus, $\ldots$

## Statistical Inference for Linear Regression

$$
\frac{c^{T} \hat{\beta}-c^{T} \beta}{\hat{\sigma} \sqrt{c^{T}\left(X^{T} X\right)^{-1} c}} \sim T_{N-p-1}
$$

Example
If $\boldsymbol{c}=\boldsymbol{e}_{j}=(0, \ldots, 0, \underbrace{1}_{j^{t h}}, \ldots, 0)^{T}$, then $c^{T} \beta=\beta_{j}$ and

$$
c^{T}\left(X^{\top} X\right)^{-1} c=\left(\left(X^{\top} X\right)^{-1}\right)_{j j}=: v_{j j}
$$

the $j^{\text {th }}$ diagonal element of $\left(X^{T} X\right)^{-1}$. Therefore,

$$
\frac{\hat{\beta}_{j}-\beta_{j}}{\hat{\sigma} \sqrt{V_{j j}}} \sim T_{N-p-1}
$$

## Statistical Inference for Linear Regression

Example
If $c=(0, \ldots, 0, \underbrace{1}_{i t h}, 0, \ldots, 0, \underbrace{-1}_{j^{h h}}, \ldots, 0)^{T}$, then $c^{\top} \beta=\beta_{i}-\beta_{j}$
and

$$
c^{\top}\left(X^{\top} X\right)^{-1} c=v_{i i}+v_{j j}-v_{i j}-v_{j i}
$$

where $v_{i j}$ the $i j^{\text {th }}$ element of $\left(X^{\top} X\right)^{-1}$. Therefore,

$$
\frac{\left(\hat{\beta}_{i}-\hat{\beta}_{j}\right)-\left(\beta_{i}-\beta_{j}\right)}{\hat{\sigma} \sqrt{v_{i i}+v_{j j}-v_{i j}-v_{j i}}} \sim T_{N-p-1}
$$

## Statistical Inference for Linear Regression

Now, since

$$
\frac{c^{T} \hat{\beta}-c^{T} \beta}{\hat{\sigma} \sqrt{c^{T}\left(X^{T} X\right)^{-1} c}} \sim T_{N-p-1}
$$

then

## Statistical Inference for Linear Regression

Now, since

$$
\frac{c^{T} \hat{\beta}-c^{T} \beta}{\hat{\sigma} \sqrt{c^{T}\left(X^{T} X\right)^{-1} c}} \sim T_{N-p-1}
$$

then

- $\mathrm{A}(1-\alpha) \mathbf{1 0 0 \%}$ confidence interval for $c^{T} \beta$ is given by

$$
c^{T} \hat{\beta} \pm t_{\alpha / 2, N-p-1} \hat{\sigma} \sqrt{c^{T}\left(X^{T} X\right)^{-1} c}
$$

- To test

use a test statistic



## Statistical Inference for Linear Regression

Now, since

$$
\frac{c^{T} \hat{\beta}-c^{T} \beta}{\hat{\sigma} \sqrt{c^{T}\left(X^{T} X\right)^{-1} c}} \sim T_{N-p-1}
$$

then

- $\mathrm{A}(1-\alpha) 100 \%$ confidence interval for $c^{\top} \beta$ is given by

$$
c^{T} \hat{\beta} \pm t_{\alpha / 2, N-p-1} \hat{\sigma} \sqrt{c^{T}\left(X^{T} X\right)^{-1} c}
$$

- To test

$$
H_{0}: c^{T} \beta=d_{0} \text { vs } H_{A}: c^{T} \beta \neq d_{0}, c^{T} \beta<d_{0}, \text { or } c^{T} \beta>d_{0}
$$

use a test statistic

$$
t=\frac{c^{T} \hat{\beta}-d_{0}}{\hat{\sigma} \sqrt{c^{T}\left(X^{T} X\right)^{-1} c}}
$$

and p -value calculated using $T_{N-p-1}$ distribution.

## Statistical Inference for Linear Regression

Example
To test

$$
H_{0}: \beta_{j}=0 \text { vs } H_{A}: \beta_{j} \neq 0
$$

use a test statistic

$$
t=\frac{\hat{\beta}_{j}}{\hat{\sigma} \sqrt{V_{j j}}}
$$

and p -value calculated using $T_{N-p-1}$ distribution.

## Statistical Inference for Linear Regression

Example
To test

$$
H_{0}: \beta_{i}=\beta_{j} \text { vs } H_{A}: \beta_{i} \neq \beta_{j}
$$

use a test statistic

$$
t=\frac{\hat{\beta}_{i}-\hat{\beta}_{j}}{\hat{\sigma} \sqrt{v_{i i}+v_{j j}-v_{i j}-v_{j i}}}
$$

and p -value calculated using $T_{N-p-1}$ distribution.

# Inference for mean response and prediction 

## Inference for mean response and prediction

To make a prediction for a new input vector $x_{*}=\left(x_{* 1}, \ldots, x_{* p}\right)^{T}$, then

## Inference for mean response and prediction

To make a prediction for a new input vector $x_{*}=\left(x_{* 1}, \ldots, x_{* p}\right)^{T}$, then

- A point estimate is $\hat{y}=x_{*}^{T} \hat{\beta}$.

A $(1-\alpha) 100 \%$ confidence interval for the mean response
$E\left(y \mid x_{*}\right)=x_{*}^{\top} \beta$ is given by

- $\mathrm{A}(1-\alpha) 100 \%$ confidence interval for predicted response $y$ at $x_{*}$ is given by


## Inference for mean response and prediction

To make a prediction for a new input vector $x_{*}=\left(x_{* 1}, \ldots, x_{* p}\right)^{T}$, then

- A point estimate is $\hat{y}=x_{*}^{T} \hat{\beta}$.
- $\mathrm{A}(1-\alpha) 100 \%$ confidence interval for the mean response $E\left(y \mid x_{*}\right)=x_{*}^{T} \beta$ is given by

$$
x_{*}^{T} \hat{\beta} \pm t_{\alpha / 2, N-p-1} \hat{\sigma} \sqrt{x_{*}^{T}\left(X^{T} X\right)^{-1} X_{*}}
$$

- $\mathrm{A}(1-\alpha) 100 \%$ confidence interval for predicted response $y$ at $x_{*}$ is given by


## Inference for mean response and prediction

To make a prediction for a new input vector $x_{*}=\left(x_{* 1}, \ldots, x_{* p}\right)^{T}$, then

- A point estimate is $\hat{y}=x_{*}^{T} \hat{\beta}$.
- A $(1-\alpha) 100 \%$ confidence interval for the mean response $E\left(y \mid x_{*}\right)=x_{*}^{T} \beta$ is given by

$$
x_{*}^{T} \hat{\beta} \pm t_{\alpha / 2, N-p-1} \hat{\sigma} \sqrt{x_{*}^{T}\left(X^{T} X\right)^{-1} X_{*}}
$$

- A $(1-\alpha) 100 \%$ confidence interval for predicted response $y$ at $x_{*}$ is given by

$$
x_{*}^{T} \hat{\beta} \pm t_{\alpha / 2, N-p-1} \hat{\sigma} \sqrt{1+X_{*}^{T}\left(X^{T} X\right)^{-1} X_{*}}
$$

## Model evaluation

## Model evaluation

To test

$$
H_{0}: \beta_{j_{1}}=\beta_{j_{2}}=\cdots=\beta_{j_{k}}=0 \text { (restricted model } M_{0} \text { ) vs }
$$

$H_{A}$ : At least one $\beta_{j_{i}} \neq 0 ;$ for $i=1,2, \ldots, k$
use a test statistic

and $p-$ value $=P(F>f)$ using the $F$-distribution with degrees of freedom $d f_{1}=k$ and $d f_{2}=N-p-1$.

Note: $R S S\left(\hat{\beta}_{\text {restricted }}\right)$ is the residuals sum of squares of the (nested) model restricted to $\beta_{j_{1}}=\beta_{j_{2}}=\cdots=\beta_{j_{k}}=0$

## Model evaluation

To test

$$
H_{0}: \beta_{j_{1}}=\beta_{j_{2}}=\cdots=\beta_{j_{k}}=0 \text { (restricted model } M_{0} \text { ) vs }
$$

$H_{A}$ : At least one $\beta_{j_{i}} \neq 0 ;$ for $i=1,2, \ldots, k$
use a test statistic

$$
f=\frac{\left(R S S\left(\hat{\beta}_{\text {restricted }}\right)-R S S\left(\hat{\beta}_{\text {full }}\right)\right) / k}{R S S\left(\hat{\beta}_{\text {full }}\right) /(N-p-1)}
$$

and $p-$ value $=P(F>f)$ using the $F$-distribution with degrees of freedom $d f_{1}=k$ and $d f_{2}=N-p-1$.

Note: $R S S\left(\hat{\beta}_{\text {restricted }}\right)$ is the residuals sum of squares of the
(nested) model restricted to $\beta_{j_{1}}=\beta_{j_{2}}=\cdots=\beta_{j_{k}}=0$

## Model evaluation

To test

$$
H_{0}: \beta_{j_{1}}=\beta_{j_{2}}=\cdots=\beta_{j_{k}}=0 \text { (restricted model } M_{0} \text { ) vs }
$$

$H_{A}$ : At least one $\beta_{j_{i}} \neq 0 ;$ for $i=1,2, \ldots, k$
use a test statistic

$$
f=\frac{\left(R S S\left(\hat{\beta}_{\text {restricted }}\right)-R S S\left(\hat{\beta}_{\text {full }}\right)\right) / k}{R S S\left(\hat{\beta}_{\text {full }}\right) /(N-p-1)}
$$

and $p-$ value $=P(F>f)$ using the $F$-distribution with degrees of freedom $d f_{1}=k$ and $d f_{2}=N-p-1$.
Note: $R S S\left(\hat{\beta}_{\text {restricted }}\right)$ is the residuals sum of squares of the (nested) model restricted to $\beta_{j_{1}}=\beta_{j_{2}}=\cdots=\beta_{j_{k}}=0$

## Model diagnostics

## Model diagnostics

1. The coefficient of determination

$$
R^{2}=1-\frac{S S E}{S S T}=\frac{S S R}{S S T}
$$

where the sums of squares of error is
and the total sums of squares in


The regression sums of squares


## Model diagnostics

1. The coefficient of determination

$$
R^{2}=1-\frac{S S E}{S S T}=\frac{S S R}{S S T}
$$

where the sums of squares of error is

$$
S S E=R S S(\hat{\beta})=\sum_{i=1}^{N}\left(y_{i}-\hat{y}_{i}\right)^{2}
$$

and the total sums of squares in


The regression sums of squares

## Model diagnostics

1. The coefficient of determination

$$
R^{2}=1-\frac{S S E}{S S T}=\frac{S S R}{S S T}
$$

where the sums of squares of error is

$$
S S E=R S S(\hat{\beta})=\sum_{i=1}^{N}\left(y_{i}-\hat{y}_{i}\right)^{2}
$$

and the total sums of squares in

$$
S S T=\sum_{i=1}^{N}\left(y_{i}-\bar{y}\right)^{2}
$$

The regression sums of squares

## Model diagnostics

1. The coefficient of determination

$$
R^{2}=1-\frac{S S E}{S S T}=\frac{S S R}{S S T}
$$

where the sums of squares of error is

$$
S S E=R S S(\hat{\beta})=\sum_{i=1}^{N}\left(y_{i}-\hat{y}_{i}\right)^{2}
$$

and the total sums of squares in

$$
S S T=\sum_{i=1}^{N}\left(y_{i}-\bar{y}\right)^{2}
$$

The regression sums of squares

$$
S S R=S S T-S S E=\sum_{i=1}^{N}\left(\hat{y}_{i}-\bar{y}\right)^{2}
$$

## Model diagnostics

2. The adjusted coefficient of determination

$$
R_{a d j}^{2}=1-\left(1-R^{2}\right) \frac{N-1}{N-p-1}=1-\frac{M S E}{M S T}
$$

where the mean sums of squares of error is

and the mean total sums of squares in

The closer $R^{2}$ and $R_{a d j}^{2}$ are to one (or $100 \%$ ), the better the fit is. (Note: $R_{a d j}^{2} \leq R^{2}$.)

## Model diagnostics

2. The adjusted coefficient of determination

$$
R_{a d j}^{2}=1-\left(1-R^{2}\right) \frac{N-1}{N-p-1}=1-\frac{M S E}{M S T}
$$

where the mean sums of squares of error is

$$
M S E=\frac{S S E}{N-p-1}=\widehat{\sigma^{2}}
$$

and the mean total sums of squares in


The closer $R^{2}$ and $R_{a d j}^{2}$ are to one (or $100 \%$ ), the better the fit is. (Note: $R_{a d j}^{2} \leq R^{2}$.)

## Model diagnostics

2. The adjusted coefficient of determination

$$
R_{a d j}^{2}=1-\left(1-R^{2}\right) \frac{N-1}{N-p-1}=1-\frac{M S E}{M S T}
$$

where the mean sums of squares of error is

$$
M S E=\frac{S S E}{N-p-1}=\widehat{\sigma^{2}}
$$

and the mean total sums of squares in

$$
M S T=\frac{S S T}{N-1}
$$

The closer $R^{2}$ and $R_{a d j}^{2}$ are to one (or $100 \%$ ), the better the fit is. (Note: $R_{a d j}^{2} \leq R^{2}$.)

## Model diagnostics

2. The adjusted coefficient of determination

$$
R_{a d j}^{2}=1-\left(1-R^{2}\right) \frac{N-1}{N-p-1}=1-\frac{M S E}{M S T}
$$

where the mean sums of squares of error is

$$
M S E=\frac{S S E}{N-p-1}=\widehat{\sigma^{2}}
$$

and the mean total sums of squares in

$$
M S T=\frac{S S T}{N-1}
$$

The closer $R^{2}$ and $R_{a d j}^{2}$ are to one (or 100\%), the better the fit is. (Note: $R_{a d j}^{2} \leq R^{2}$.)

## Model diagnostics

3. Residual analyses to make sure of the homogeneity (to see no pattern in scatter plots of residuals vs fitted values) and normality of the residuals using Normal Q-Q plot and Shapiro-Wilk test.
4. Tests of outliers (points standing far away from the bulk of the data) and influential points (which if removed, result in significant change to the model).

## Model diagnostics

3. Residual analyses to make sure of the homogeneity (to see no pattern in scatter plots of residuals vs fitted values) and normality of the residuals using Normal Q-Q plot and Shapiro-Wilk test.
4. Tests of outliers (points standing far away from the bulk of the data) and influential points (which if removed, result in significant change to the model).

## Example

## Example: Prostate Cancer



## Example: Prostate Cancer

$$
N=67 \text { and } p=8
$$

|  | lcavol | lweight | age | lbph | svi | lcp | gleason |
| ---: | ---: | ---: | :---: | :---: | :---: | :---: | ---: |
| lweight | 0.300 |  |  |  |  |  |  |
| age | 0.286 | 0.317 |  |  |  |  |  |
| lbph | 0.063 | 0.437 | 0.287 |  |  |  |  |
| svi | 0.593 | 0.181 | 0.129 | -0.139 |  |  |  |
| lcp | 0.692 | 0.157 | 0.173 | -0.089 | 0.671 |  |  |
| gleason | 0.426 | 0.024 | 0.366 | 0.033 | 0.307 | 0.476 |  |
| pgg45 | 0.483 | 0.074 | 0.276 | -0.030 | 0.481 | 0.663 | 0.757 |

## Example: Prostate Cancer

| Term | Coefficient | Std. Error | $Z$ Score |
| ---: | ---: | ---: | ---: |
| Intercept | 2.46 | 0.09 | 27.60 |
| lcavol | 0.68 | 0.13 | 5.37 |
| lweight | 0.26 | 0.10 | 2.75 |
| age | -0.14 | 0.10 | -1.40 |
| lbph | 0.21 | 0.10 | 2.06 |
| svi | 0.31 | 0.12 | 2.47 |
| lcp | -0.29 | 0.15 | -1.87 |
| gleason | -0.02 | 0.15 | -0.15 |
| pgg45 | 0.27 | 0.15 | 1.74 |

## Example: Prostate Cancer

Dropping the least significant inputs: age, Icp, gleason, and pgg45, leads to F test statistics

$$
f=\frac{(32.81-29.43) / 4}{29.43 /(67-8-1)}=1.67
$$

with $p-$ value $=P\left(F_{4,58}>1.67\right)=.17$ which is not significant. Thus, it is concluded to remove those inputs.

## Is LS the best method for prediction?

## The Gauss-Markov Theorem

Recall: $c^{T} \hat{\beta}=c^{T}\left(X^{T} X\right)^{-1} X^{T} y=: c_{0}^{T} y$ is unbiased (linear) estimator of $c^{T} \beta$ and $\operatorname{Var}\left(c^{T} \hat{\beta}\right)=c^{T}\left(X^{\top} X\right)^{-1} c \sigma^{2}$.

Theorem (The Gauss-Markov Theorem)
Let $c_{1}^{T} y$ be another unbiased (linear) estimator of $c^{T} \beta$, then

$$
\operatorname{Var}\left(c^{\top} \hat{\beta}\right) \leq \operatorname{Var}\left(c_{1}^{\top} y\right)
$$

In general, the mean squared error

$$
\begin{aligned}
\operatorname{MSE}(\hat{\theta}) & =E(\hat{\theta}-\theta)^{2} \\
& =\operatorname{Var}(\hat{\theta})+[\underbrace{[E(\hat{\theta})-\theta}_{\operatorname{Bias}(\hat{\theta})}]^{2}
\end{aligned}
$$

## The Gauss-Markov Theorem

Recall: $c^{T} \hat{\beta}=c^{T}\left(X^{T} X\right)^{-1} X^{T} y=: c_{0}^{T} y$ is unbiased (linear) estimator of $c^{\top} \beta$ and $\operatorname{Var}\left(c^{T} \hat{\beta}\right)=c^{T}\left(X^{\top} X\right)^{-1} c \sigma^{2}$.

Theorem (The Gauss-Markov Theorem)
Let $c_{1}^{T} y$ be another unbiased (linear) estimator of $c^{T} \beta$, then

$$
\operatorname{Var}\left(c^{T} \hat{\beta}\right) \leq \operatorname{Var}\left(c_{1}^{T} y\right)
$$

In general, the mean squared error

$$
M S E(\hat{\theta})=E(\hat{\theta}-\theta)^{2}
$$



## The Gauss-Markov Theorem

Recall: $c^{T} \hat{\beta}=c^{T}\left(X^{T} X\right)^{-1} X^{T} y=: c_{0}^{T} y$ is unbiased (linear) estimator of $c^{T} \beta$ and $\operatorname{Var}\left(c^{T} \hat{\beta}\right)=c^{T}\left(X^{\top} X\right)^{-1} c \sigma^{2}$.
Theorem (The Gauss-Markov Theorem)
Let $c_{1}^{T} y$ be another unbiased (linear) estimator of $c^{T} \beta$, then

$$
\operatorname{Var}\left(c^{\top} \hat{\beta}\right) \leq \operatorname{Var}\left(c_{1}^{\top} y\right)
$$

In general, the mean squared error

$$
\begin{aligned}
\operatorname{MSE}(\hat{\theta}) & =E(\hat{\theta}-\theta)^{2} \\
& =\operatorname{Var}(\hat{\theta})+[\underbrace{E(\hat{\theta})-\theta}_{\operatorname{Bias}(\hat{\theta})}]^{2}
\end{aligned}
$$

## The Gauss-Markov Theorem

How is it related to the expected prediction error (EPE) for $Y_{*}=f\left(x_{*}\right)+\epsilon_{*}$ ?

$$
\begin{aligned}
E P E & =E\left(Y_{*}-\hat{f}\left(x_{*}\right)\right)^{2} \\
& =E\left(\hat{f}\left(x_{*}\right)-f\left(x_{*}\right)\right)^{2}+\sigma^{2} \\
& =\operatorname{MSE}\left(\hat{f}\left(x_{*}\right)\right)+\sigma^{2} \\
& =\operatorname{MSE}\left(x_{*}^{T} \hat{\beta}\right)+\sigma^{2}
\end{aligned}
$$

Thus, a small $\operatorname{MSE}\left(x_{*}^{\top} \hat{\beta}\right)$ is better for prediction, even when $\operatorname{Bias}\left(X_{*}^{\top} \hat{\beta}\right)>0$.
So, smaller number of predictors (shrinking) might be advised over a more detailed model. Also, a method other than OLS with smaller MSE, is more advisable for prediction.

## The Gauss-Markov Theorem

How is it related to the expected prediction error (EPE) for $Y_{*}=f\left(x_{*}\right)+\epsilon_{*}$ ?

$$
\begin{aligned}
E P E & =E\left(Y_{*}-\hat{f}\left(x_{*}\right)\right)^{2} \\
& =E\left(\hat{f}\left(x_{*}\right)-f\left(x_{*}\right)\right)^{2}+\sigma^{2} \\
& =\operatorname{MSE}\left(\hat{f}\left(x_{*}\right)\right)+\sigma^{2} \\
& =\operatorname{MSE}\left(x_{*}^{T} \hat{\beta}\right)+\sigma^{2}
\end{aligned}
$$

Thus, a small $\operatorname{MSE}\left(x_{*}^{T} \hat{\beta}\right)$ is better for prediction, even when $\operatorname{Bias}\left(X_{*}^{T} \hat{\beta}\right)>0$.
So, smaller number of predictors (shrinking) might be advised
over a more detailed model. Also, a method other than OLS
with smaller MSE, is more advisable for prediction.

## The Gauss-Markov Theorem

How is it related to the expected prediction error (EPE) for $Y_{*}=f\left(X_{*}\right)+\epsilon_{*}$ ?

$$
\begin{aligned}
E P E & =E\left(Y_{*}-\hat{f}\left(x_{*}\right)\right)^{2} \\
& =E\left(\hat{f}\left(x_{*}\right)-f\left(x_{*}\right)\right)^{2}+\sigma^{2} \\
& =\operatorname{MSE}\left(\hat{f}\left(x_{*}\right)\right)+\sigma^{2} \\
& =\operatorname{MSE}\left(x_{*}^{\top} \hat{\beta}\right)+\sigma^{2}
\end{aligned}
$$

Thus, a small $\operatorname{MSE}\left(x_{*}^{\top} \hat{\beta}\right)$ is better for prediction, even when $\operatorname{Bias}\left(x_{*}^{\top} \hat{\beta}\right)>0$.
So, smaller number of predictors (shrinking) might be advised over a more detailed model. Also, a method other than OLS with smaller MSE, is more advisable for prediction.

## Subset (Variable) Selection

## Subset (Variable) Selection

- Part of model selection.


## Dbjective: select one of the $2^{P}$ possible subsets of variables/models (including the null regression). - Methods:

Example (Prostate Cancer)

## Subset (Variable) Selection

- Part of model selection.
- Objective: select one of the $2^{p}$ possible subsets of variables/models (including the null regression).

Example (Prostate Cancer)

## Subset (Variable) Selection

- Part of model selection.
- Objective: select one of the $2^{p}$ possible subsets of variables/models (including the null regression).
- Methods:
> all of the $2^{p}$ models. Note: $R S S\left(\hat{\beta}_{\text {full }}\right)<R S S\left(\hat{\beta}_{\text {subset }}\right)$.

Examule (Prostate Cancer)

## Subset (Variable) Selection

- Part of model selection.
- Objective: select one of the $2^{p}$ possible subsets of variables/models (including the null regression).
- Methods:

1. Best Subset method: search for the smallest RSS among all of the $2^{p}$ models. Note: $R S S\left(\hat{\beta}_{\text {full }}\right)<R S S\left(\hat{\beta}_{\text {subset }}\right)$.
Example (Prostate Cancer)

## Subset (Variable) Selection

- Part of model selection.
- Objective: select one of the $2^{p}$ possible subsets of variables/models (including the null regression).
- Methods:

1. Best Subset method: search for the smallest RSS among all of the $2^{p}$ models. Note: $R S S\left(\hat{\beta}_{\text {full }}\right)<R S S\left(\hat{\beta}_{\text {subset }}\right)$.
Example (Prostate Cancer)

## Subset (Variable) Selection

- Part of model selection.
- Objective: select one of the $2^{p}$ possible subsets of variables/models (including the null regression).
- Methods:

1. Best Subset method: search for the smallest RSS among all of the $2^{p}$ models. Note: $R S S\left(\hat{\beta}_{\text {full }}\right)<R S S\left(\hat{\beta}_{\text {subset }}\right)$.
Example (Prostate Cancer)


## Subset (Variable) Selection

2. Leaps and bounds (good for $p \leq 40$, minimizes RSS). Also, Branch and Bounds.

## Subset (Variable) Selection

## 2. Leaps and bounds (good for $p \leq 40$, minimizes RSS). Also, Branch and Bounds.

TECHNOMETRICSO, VOL. 16, NO. 4, NOVEMBER 1974

Regressions by Leaps and Bounds

George M. Furnival<br>School of Forestry, Yale University<br>New Haven, Connecticut

and

Robert W. Wilson, Jr.<br>USDA Forest Service Northeastern Forest Experiment Station

This paper describes several algorithms for computing the residual sums of squares for all possible regressions with what appears to be a minimum of arithmetic (less than six floating-point operations per regression) and shows how two of these algorithms can be combined to form a simple leap and bound technique for finding the best subsets without examining all possible subsets. The result is a reduction of several orders of magnitude in the number of operations required to find the best subsets.

## Subset (Variable) Selection

2. Leaps and bounds (good for $p \leq 40$, minimizes RSS). Also, Branch and Bounds.


## Subset (Variable) Selection

2. Leaps and bounds (good for $p \leq 40$, minimizes RSS). Also, Branch and Bounds.


TECHNOMETRICSQ, VOL. 16, NO. 4, NOVEMBER 1974

## Subset (Variable) Selection

3. Stepwise (Forward or Backward) Selection (when $p>40$ ).
> - Forward-stepwise selection (is a greedy algorithm): start with a null model (just the intercept $\hat{\beta}_{0}=\bar{y}$ ) and then sequentially adds predictors that improves the fit. Models on the steps forward are nested. Good at all cases.
> - Backward-stepwise selection: start with a full model (all the predictors) and then sequentially removes predictors that do not alter the fit (smallest t- or z- score). Use only when $N>p$.

## Subset (Variable) Selection

3. Stepwise (Forward or Backward) Selection (when $p>40$ ).

- Forward-stepwise selection (is a greedy algorithm): start with a null model (just the intercept $\hat{\beta}_{0}=\bar{y}$ ) and then sequentially adds predictors that improves the fit. Models on the steps forward are nested. Good at all cases.
predictors) and then sequentially removes predictors that do not alter the fit (smallest t- or z-score). Use only when $N>p$.


## Subset (Variable) Selection

3. Stepwise (Forward or Backward) Selection (when $p>40$ ).

- Forward-stepwise selection (is a greedy algorithm): start with a null model (just the intercept $\hat{\beta}_{0}=\bar{y}$ ) and then sequentially adds predictors that improves the fit. Models on the steps forward are nested. Good at all cases.
- Backward-stepwise selection: start with a full model (all the predictors) and then sequentially removes predictors that do not alter the fit (smallest t- or z-score). Use only when $N>p$.


## Subset (Variable) Selection

4. Forward-Stagewise Regression:

> Stage 0: Start with $\hat{\beta}_{0,0}=\bar{y}$ and $\hat{\beta}_{j, 0}=0$ for $j=1,2, \ldots, p$.
> Stage $k$ : Find the most correlated variable, say $X_{j}$, with the residuals of the model in Stage $k-1$ and find the slope $\left(b_{j}\right)$ of the simple linear regression between the residuals and that variable $X_{j}$.

$$
\hat{\beta}_{j, k}=\hat{\beta}_{j, k-1}+b_{j}
$$

Until: there is no correlation between the residuals and any variable.
$\Downarrow$ Slow and might need more than p stages till converge. $\Uparrow$ Good for high dimensional problems.

## Subset (Variable) Selection

4. Forward-Stagewise Regression:

Stage 0: Start with $\hat{\beta}_{0,0}=\bar{y}$ and $\hat{\beta}_{j, 0}=0$ for $j=1,2, \ldots, p$.
Stage k: Find the most correlated variable, say $X_{j}$, with the residuals of the model in Stage $k-1$ and find the slope $\left(b_{j}\right)$ of the simple linear regression between the residuals and that variable $X_{j}$.

$$
\hat{\beta}_{j, k}=\hat{\beta}_{j, k-1}+b_{j}
$$

Until: there is no correlation between the residuals and any variable.
$\Downarrow$ Slow and might need more than $p$ stages till converge. $\Uparrow$ Good for high dimensional problems.

## Subset (Variable) Selection

4. Forward-Stagewise Regression:

Stage 0: Start with $\hat{\beta}_{0,0}=\bar{y}$ and $\hat{\beta}_{j, 0}=0$ for $j=1,2, \ldots, p$.
Stage $k$ : Find the most correlated variable, say $X_{j}$, with the residuals of the model in Stage $k-1$ and find the slope $\left(b_{j}\right)$ of the simple linear regression between the residuals and that variable $X_{j}$.

Until: there is no correlation between the residuals and any variable.
$\Downarrow$ Slow and might need more than $p$ stages till converge. $\Uparrow$ Good for high dimensional problems.

## Subset (Variable) Selection

4. Forward-Stagewise Regression:

Stage 0: Start with $\hat{\beta}_{0,0}=\bar{y}$ and $\hat{\beta}_{j, 0}=0$ for $j=1,2, \ldots, p$.
Stage $k$ : Find the most correlated variable, say $X_{j}$, with the residuals of the model in Stage $k-1$ and find the slope $\left(b_{j}\right)$ of the simple linear regression between the residuals and that variable $X_{j}$.

$$
\hat{\beta}_{j, k}=\hat{\beta}_{j, k-1}+b_{j}
$$

Until: there is no correlation between the residuals and any
variable.
$\Downarrow$ Slow and might need more than $p$ stages till converge. $\Uparrow$ Good for high dimensional problems.

## Subset (Variable) Selection

## 4. Forward-Stagewise Regression:

Stage 0: Start with $\hat{\beta}_{0,0}=\bar{y}$ and $\hat{\beta}_{j, 0}=0$ for $j=1,2, \ldots, p$.
Stage $k$ : Find the most correlated variable, say $X_{j}$, with the residuals of the model in Stage $k-1$ and find the slope $\left(b_{j}\right)$ of the simple linear regression between the residuals and that variable $X_{j}$.

$$
\hat{\beta}_{j, k}=\hat{\beta}_{j, k-1}+b_{j}
$$

Until: there is no correlation between the residuals and any variable.
$\Downarrow$ Slow and might need more than $p$ stages till converge. $\Uparrow$ Good for high dimensional problems.

## Subset (Variable) Selection

## 4. Forward-Stagewise Regression:

Stage 0: Start with $\hat{\beta}_{0,0}=\bar{y}$ and $\hat{\beta}_{j, 0}=0$ for $j=1,2, \ldots, p$.
Stage $k$ : Find the most correlated variable, say $X_{j}$, with the residuals of the model in Stage $k-1$ and find the slope $\left(b_{j}\right)$ of the simple linear regression between the residuals and that variable $X_{j}$.

$$
\hat{\beta}_{j, k}=\hat{\beta}_{j, k-1}+b_{j}
$$

Until: there is no correlation between the residuals and any variable.
$\Downarrow$ Slow and might need more than $p$ stages till converge. $\Uparrow$ Good for high dimensional problems.

## Subset (Variable) Selection

## 4. Forward-Stagewise Regression:

Stage 0: Start with $\hat{\beta}_{0,0}=\bar{y}$ and $\hat{\beta}_{j, 0}=0$ for $j=1,2, \ldots, p$.
Stage $k$ : Find the most correlated variable, say $X_{j}$, with the residuals of the model in Stage $k-1$ and find the slope $\left(b_{j}\right)$ of the simple linear regression between the residuals and that variable $X_{j}$.

$$
\hat{\beta}_{j, k}=\hat{\beta}_{j, k-1}+b_{j}
$$

Until: there is no correlation between the residuals and any variable.
$\Downarrow$ Slow and might need more than $p$ stages till converge.
$\Uparrow$ Good for high dimensional problems.

## Subset (Variable) Selection

In a simulation study, with $N=300$ and $p=31$.


## Subset (Variable) Selection

Measures of selection

1. Largest $R^{2}$ or $R_{\text {adj }}^{2}$.
2. Smallest RSS.
3. Smallest CV or GCV.
4. Smallest Mallow's $C_{n}$ :

$$
C_{p}=\frac{R S S_{\text {subset of } k}}{R S S\left(\hat{\beta}_{\text {full }}\right) /(N-p-1)}-(N-2 k)
$$

## Subset (Variable) Selection

Measures of selection

1. Largest $R^{2}$ or $R_{\text {adj }}^{2}$.
2. Smallest RSS.
3. Smallest CV or GCV.
4. Smallest Mallow's $C_{p}$ :

$$
C_{p}=\frac{n S S_{\text {subset of } k}}{\operatorname{RSS}\left(\hat{\beta}_{\text {full }}\right) /(N-p-1)}-(N-2 k)
$$

## Subset (Variable) Selection

Measures of selection

1. Largest $R^{2}$ or $R_{\text {adj }}^{2}$.
2. Smallest RSS.
3. Smallest $C V$ or $G C V$.
4. Smallest Mallow's $C_{p}$ :

$$
C_{p}=\frac{R S S_{\text {subset of } k}}{R S S\left(\hat{\beta}_{\text {full }}\right) /(N-p-1)}-(N-2 k)
$$

## Subset (Variable) Selection

Measures of selection

1. Largest $R^{2}$ or $R_{a d j}^{2}$.
2. Smallest RSS.
3. Smallest CV or GCV.
4. Smallest Mallow's $C_{p}$ :

$$
C_{p}=\frac{R S S_{\text {subset of } k}}{R S S\left(\hat{\beta}_{\text {full }}\right) /(N-p-1)}-(N-2 k)
$$

## Subset (Variable) Selection

More measures of selection: (For general classes of models.) Let $L$ be the likelihood function. $\hat{\beta}_{M L E, k}$ is the maximum likelihood estimator of size $k$.

1. Smallest

$$
\text { deviance }=-2 \log L\left(\hat{\beta}_{M L E, k}\right)
$$

2. Smallest Akaike's Information Criterion

$$
A I C_{k}=-2 \log L\left(\hat{\beta}_{M L E, k}\right)+2 k
$$

3. Smallest Bayes' Information Criterion

$$
B I C_{K}=-2 \log L\left(\hat{\beta}_{M L E, K}\right)+2 k \log (N)
$$

## Subset (Variable) Selection

More measures of selection: (For general classes of models.) Let $L$ be the likelihood function. $\hat{\beta}_{M L E, k}$ is the maximum likelihood estimator of size $k$.

1. Smallest

$$
\text { deviance }=-2 \log L\left(\hat{\beta}_{M L E, k}\right)
$$

2. Smallest Akaike's Information Criterion

$$
A I C_{k}=-2 \log L\left(\hat{\beta}_{M L E, k}\right)+2 k
$$

3. Smallest Bayes' Information Criterion

## Subset (Variable) Selection

More measures of selection: (For general classes of models.)
Let $L$ be the likelihood function. $\hat{\beta}_{M L E, k}$ is the maximum
likelihood estimator of size $k$.

1. Smallest

$$
\text { deviance }=-2 \log L\left(\hat{\beta}_{M L E, k}\right)
$$

2. Smallest Akaike's Information Criterion

$$
A I C_{k}=-2 \log L\left(\hat{\beta}_{M L E, k}\right)+2 k
$$

3. Smallest Bayes' Information Criterion

$$
B I C_{k}=-2 \log L\left(\hat{\beta}_{M L E, k}\right)+2 k \log (N)
$$

## Subset (Variable) Selection

## Example (Prostate Cancer)

## All Subsets



## Shrinkage (regularization,constraints)

## Shrinkage

- It includes subset selection. But, it is continuous selection rather than discrete.
- Objective: To include all of the p inputs but shrinking their coefficients towards zero. If some of them become zero, then it results in a subset. (Note: Intercept is not included in that objective.)
- It reduces variance of the estimates.


## Shrinkage

- It includes subset selection. But, it is continuous selection rather than discrete.
- Objective: To include all of the $p$ inputs but shrinking their coefficients towards zero. If some of them become zero, then it results in a subset. (Note: Intercept is not included in that objective.)
- It reduces variance of the estimates.


## Shrinkage

- It includes subset selection. But, it is continuous selection rather than discrete.
- Objective: To include all of the $p$ inputs but shrinking their coefficients towards zero. If some of them become zero, then it results in a subset. (Note: Intercept is not included in that objective.)
- It reduces variance of the estimates.


## Shrinkage

To find $\hat{\beta}^{\text {shrunk }}$ that

$$
\operatorname{minimize}_{\beta} R S S(\beta)=\sum_{i=1}^{N}\left[y_{i}-\left(\beta_{0}+\beta_{1} x_{i 1}+\cdots+\beta_{p} x_{i, p}\right)\right]^{2}
$$

$$
\text { subject to } \sum_{j=1}^{p} G\left(\beta_{j}\right) \leq t \text { (size constraint) }
$$

OR $\hat{\beta}^{\text {shrunk }}=$

for some positive function $G$. The term $\lambda \sum_{j=1}^{p} G\left(\beta_{j}\right)$ is called shrinkage penalty.

## Shrinkage

To find $\hat{\beta}^{\text {shrunk }}$ that

$$
\begin{gathered}
\operatorname{minimize}_{\beta} R S S(\beta)=\sum_{i=1}^{N}\left[y_{i}-\left(\beta_{0}+\beta_{1} x_{i 1}+\cdots+\beta_{p} x_{i, p}\right)\right]^{2} \\
\text { subject to } \sum_{j=1}^{p} G\left(\beta_{j}\right) \leq t \text { (size constraint) }
\end{gathered}
$$

OR $\hat{\beta}^{\text {shrunk }}=$

$$
\operatorname{argmin}_{\beta}\left[\sum_{i=1}^{N}\left[y_{i}-\left(\beta_{0}+\beta_{1} x_{i 1}+\cdots+\beta_{p} x_{i, p}\right)\right]^{2}+\lambda \sum_{j=1}^{p} G\left(\beta_{j}\right)\right]
$$

for some positive function $G$. The term $\lambda \sum_{j=1}^{p} G\left(\beta_{j}\right)$ is called shrinkage penalty.

## Shrinkage

- Some methods:

1. Ridge regression, $G(x)=x^{2}$. (An $L_{2}$ shrinkage method.)
2. Least absolute shrinkage and selection operator (lasso), $G(x)=|x|$. (An $L_{1}$ shrinkage method.)
3. Bridge shrinkage,

$$
G(x)= \begin{cases}|x|^{q} & \text { if } q>0, \\ I(x \neq 0) & \text { if } q=0 .\end{cases}
$$

(An $L_{q}$ shrinkage method.) It includes both ridge and lasso.

## Shrinkage

- Some methods:

1. Ridge regression, $G(x)=x^{2}$. (An $L_{2}$ shrinkage method.)
2. Least absolute shrinkage and selection operator (lasso), $G(x)=|x|$. (An $L_{1}$ shrinkage method.)
3. Bridge shrinkage,

(An $L_{q}$ shrinkage method.) It includes both ridge and lasso.

## Shrinkage

- Some methods:

1. Ridge regression, $G(x)=x^{2}$. (An $L_{2}$ shrinkage method.)
2. Least absolute shrinkage and selection operator (lasso), $G(x)=|x|$. (An $L_{1}$ shrinkage method.)
3. Bridge shrinkage,

$$
G(x)= \begin{cases}|x|^{q} & \text { if } q>0, \\ l(x \neq 0) & \text { if } q=0 .\end{cases}
$$

(An $L_{q}$ shrinkage method.) It includes both ridge and lasso.

## Shrinkage

Example (Prostate Cancer)



## Shrinkage

Example (Prostate Cancer)
Estimated coefficients are

| Term | LS | Best Subset | Ridge | Lasso |
| ---: | ---: | ---: | ---: | ---: |
| Intercept | 2.465 | 2.477 | 2.452 | 2.468 |
| lcavol | 0.680 | 0.740 | 0.420 | 0.533 |
| lweight | 0.263 | 0.316 | 0.238 | 0.169 |
| age | -0.141 |  | -0.046 |  |
| lbph | 0.210 |  | 0.162 | 0.002 |
| svi | 0.305 |  | 0.227 | 0.094 |
| lcp | -0.288 |  | 0.000 |  |
| gleason | -0.021 |  | 0.040 |  |
| pgg45 | 0.267 |  | 0.133 |  |
| Test Error | 0.521 | 0.492 | 0.492 | 0.479 |
| Std Error | 0.179 | 0.143 | 0.165 | 0.164 |

## Ridge Regression

## Ridge Regression

To find $\hat{\beta}^{\text {ridge }}$ that

$$
\begin{gathered}
\operatorname{minimize}_{\beta} R S S(\beta)=\sum_{i=1}^{N}\left[y_{i}-\left(\beta_{0}+\beta_{1} x_{i 1}+\cdots+\beta_{p} x_{i, p}\right)\right]^{2} \\
\text { subject to } \sum_{j=1}^{p} \beta_{j}^{2} \leq t \text { (size constraint) }
\end{gathered}
$$

OR in the Lagrangian form

## Ridge Regression

To find $\hat{\beta}^{\text {ridge }}$ that

$$
\begin{gathered}
\operatorname{minimize}_{\beta} R S S(\beta)=\sum_{i=1}^{N}\left[y_{i}-\left(\beta_{0}+\beta_{1} x_{i 1}+\cdots+\beta_{p} x_{i, p}\right)\right]^{2} \\
\text { subject to } \sum_{j=1}^{p} \beta_{j}^{2} \leq t \text { (size constraint) }
\end{gathered}
$$

OR in the Lagrangian form
$\hat{\beta}^{\text {ridge }}=\operatorname{argmin}_{\beta}\left[\sum_{i=1}^{N}\left[y_{i}-\left(\beta_{0}+\beta_{1} x_{i 1}+\cdots+\beta_{p} x_{i, p}\right)\right]^{2}+\lambda \sum_{j=1}^{p} \beta_{j}^{2}\right]$

## Ridge Regression

- The decay/tuning parameter $\lambda \geq 0$ is determined first through CV then the parameters are estimated.
- What does happen when $\lambda$ increase?


## Ridge Regression

Better, start with standardized data:

$$
\sum_{i=1}^{N} x_{i j}=0, \sum_{i=1}^{N} x_{i j}^{2}=1
$$

which results in removing $\hat{\beta}_{0}$ from the optimization problem as its value would be $\bar{y}$. We are now left with a $p \times p$ matrix $X$.

## Ridge Regression

The problem is now equivalent to find $\hat{\beta}^{\text {ridge }}$ that

$$
\begin{gathered}
\operatorname{minimize}_{\beta} \operatorname{RSS}(\beta)=(y-X \beta)^{T}(y-X \beta) \\
\text { subject to } \beta^{T} \beta \leq t
\end{gathered}
$$

$\hat{\beta}^{\text {ridge }}=\operatorname{argmin}_{\beta}$

$$
\operatorname{RSS}_{\lambda}(\beta):=(y-X \beta)^{T}(y-X \beta)+\lambda \beta^{T} \beta
$$

## Ridge Regression

The problem is now equivalent to find $\hat{\beta}^{\text {ridge }}$ that

$$
\begin{gathered}
\operatorname{minimize}_{\beta} \operatorname{RSS}(\beta)=(y-X \beta)^{T}(y-X \beta) \\
\text { subject to } \beta^{T} \beta \leq t
\end{gathered}
$$

OR

$$
\hat{\beta}^{\text {ridge }}=\operatorname{argmin}_{\beta}\left[(y-X \beta)^{T}(y-X \beta)+\lambda \beta^{T} \beta\right]
$$

## Ridge Regression

The problem is now equivalent to find $\hat{\beta}^{\text {ridge }}$ that

$$
\begin{gathered}
\operatorname{minimize}_{\beta} \operatorname{RSS}(\beta)=(y-X \beta)^{T}(y-X \beta) \\
\text { subject to } \beta^{T} \beta \leq t
\end{gathered}
$$

OR

$$
\hat{\beta}^{\text {ridge }}=\operatorname{argmin}_{\beta}\left[(y-X \beta)^{T}(y-X \beta)+\lambda \beta^{T} \beta\right]
$$

Call:

$$
\operatorname{RSS}_{\lambda}(\beta):=(y-X \beta)^{T}(y-X \beta)+\lambda \beta^{T} \beta
$$

## Ridge Regression

- $\frac{\partial R S S_{\lambda}(\beta)}{\partial \beta}=-2 X^{T}(y-X \beta)+2 \lambda \beta=0$

$$
\left(X^{T} X+\lambda I_{p}\right) \beta=X^{T} y
$$

where $I_{p}$ is the $p \times p$ identity matrix.


- Even when $X$ is not a full column rank, $X^{\top} X+\lambda I_{p}$ is positive definite for $\lambda>0$ and so non-singular, then

- Predictions



## Ridge Regression

$-\frac{\partial R S S_{\lambda}(\beta)}{\partial \beta}=-2 X^{T}(y-X \beta)+2 \lambda \beta=0 \Longrightarrow$

$$
\left(X^{\top} X+\lambda I_{p}\right) \beta=X^{T} y
$$

where $I_{p}$ is the $p \times p$ identity matrix.
$-\frac{\partial^{2} R S S_{\lambda}(\beta)}{\partial \beta \partial \beta^{T}}=2 X^{\top} X+2 \lambda I_{p}$
Even when $X$ is not a full column rank, $X^{\top} X+\lambda I_{p}$ is positive definite for $\lambda>0$ and so non-singular, then

- Predictions


## Ridge Regression

- $\frac{\partial \text { RSS }_{\lambda}(\beta)}{\partial \beta}=-2 X^{\top}(y-X \beta)+2 \lambda \beta=0 \Longrightarrow$

$$
\left(X^{\top} X+\lambda I_{p}\right) \beta=X^{\top} y
$$

where $I_{p}$ is the $p \times p$ identity matrix.

- $\frac{\partial^{2} R S S_{\lambda}(\beta)}{\partial \beta \partial \beta^{T}}=2 X^{\top} X+2 \lambda I_{p}$
- Even when $X$ is not a full column rank, $X^{\top} X+\lambda I_{p}$ is positive definite for $\lambda>0$ and so non-singular, then

$$
\hat{\beta}_{\lambda}^{\text {ridge }}=\left(X^{\top} X+\lambda / p\right)^{-1} X^{\top} y
$$

- Predictions


## Ridge Regression

- $\frac{\partial R S S_{\lambda}(\beta)}{\partial \beta}=-2 X^{T}(y-X \beta)+2 \lambda \beta=0 \Longrightarrow$

$$
\left(X^{\top} X+\lambda I_{p}\right) \beta=X^{T} y
$$

where $I_{p}$ is the $p \times p$ identity matrix.
$-\frac{\partial^{2} R S S_{\lambda}(\beta)}{\partial \beta \partial \beta^{T}}=2 X^{\top} X+2 \lambda I_{p}$

- Even when $X$ is not a full column rank, $X^{T} X+\lambda I_{p}$ is positive definite for $\lambda>0$ and so non-singular, then

$$
\hat{\beta}_{\lambda}^{\text {ridge }}=\left(X^{\top} X+\lambda I_{p}\right)^{-1} X^{\top} y
$$

- Predictions

$$
\hat{y}_{\lambda}=X \hat{\beta}_{\lambda}^{\text {ridge }}=\underbrace{X\left(X^{\top} X+\lambda I_{p}\right)^{-1} X^{\top}}_{\text {the } \lambda \text {-hat matrix } H_{\lambda}} y
$$

## Ridge Regression

Again, the solution is

$$
\hat{\beta}_{\lambda}^{\text {ridge }}=\left(X^{\top} X+\lambda I_{p}\right)^{-1} X^{\top} y
$$

- What does happen when $\lambda$ decreases to zero?
- If columns of $X$ are orthonormal ( $X^{\top} X=I$ ), then

- In general, $\beta_{\lambda}^{\text {ridge }}$ is a biased estimator of $\beta$. (Good problem to prove it, hint: $E(A z)=A E(z)$.)
- Yet, it has smaller variance than that of the OLS's. (Another good problem, hint: $\operatorname{Var}(A z)=A \operatorname{Var}(z) A^{\top}$.)


## Ridge Regression

Again, the solution is

$$
\hat{\beta}_{\lambda}^{\text {ridge }}=\left(X^{\top} X+\lambda I_{p}\right)^{-1} X^{\top} y
$$

- What does happen when $\lambda$ decreases to zero?
- If columns of $X$ are orthonormal ( $X^{\top} X=l$ ), then

$$
\hat{\beta}_{\lambda}^{\text {ridge }}=\frac{1}{1+\lambda} \hat{\beta}^{o l s}
$$

- In general, $\hat{\beta}_{\lambda}^{\text {ridge }}$ is a biased estimator of $\beta$. (Good problem to prove it, hint: $E(A z)=A E(z)$.)
- Yet, it has smaller variance than that of the OLS's. (Another good problem, hint: $\operatorname{Var}(A z)=A \operatorname{Var}(z) A^{\top}$.)


## Ridge Regression

Again, the solution is

$$
\hat{\beta}_{\lambda}^{\text {ridge }}=\left(X^{\top} X+\lambda I_{p}\right)^{-1} X^{\top} y
$$

- What does happen when $\lambda$ decreases to zero?
- If columns of $X$ are orthonormal ( $X^{\top} X=I$ ), then

$$
\hat{\beta}_{\lambda}^{\text {ridge }}=\frac{1}{1+\lambda} \hat{\beta}^{o l s}
$$

- In general, $\hat{\beta}_{\lambda}^{\text {ridge }}$ is a biased estimator of $\beta$. (Good problem to prove it, hint: $E(A z)=A E(z)$.)
- Yet, it has smaller variance than that of the OLS's. (Another good problem, hint: $\operatorname{Var}(A z)=A \operatorname{Var}(z) A^{\top}$.)


## Ridge Regression

Again, the solution is

$$
\hat{\beta}_{\lambda}^{\text {ridge }}=\left(X^{\top} X+\lambda / p\right)^{-1} X^{\top} y
$$

- What does happen when $\lambda$ decreases to zero?
- If columns of $X$ are orthonormal ( $X^{\top} X=I$ ), then

$$
\hat{\beta}_{\lambda}^{\text {ridge }}=\frac{1}{1+\lambda} \hat{\beta}^{o l s}
$$

- In general, $\hat{\beta}_{\lambda}^{\text {ridge }}$ is a biased estimator of $\beta$. (Good problem to prove it, hint: $E(A z)=A E(z)$.)
- Yet, it has smaller variance than that of the OLS's. (Another good problem, hint: $\operatorname{Var}(A z)=A \operatorname{Var}(z) A^{T}$.)


## Ridge Regression

It handles very well the case of collinearity, as

- Originally, When a coefficient of a variable becomes large, coefficient of any correlated variables balance up with a very small and negative value. But placing a bound resolves that issue.
- It fixes the problem that $X$ is not column full-rank.


## Ridge Regression

It handles very well the case of collinearity, as

- Originally, When a coefficient of a variable becomes large, coefficient of any correlated variables balance up with a very small and negative value. But placing a bound resolves that issue.
- It fixes the problem that $X$ is not column full-rank.


## Ridge Regression

Using singular values decomposition (SVD):

$$
X=U D V^{T}
$$

Where $U$ and $V$ are two orthogonal matrices, $U^{T} U=I_{p}$ and $V^{\top} V=I_{p}$. The columns $u_{j}$ and $v_{j}$ of the $N \times p$ matrix $U$ and the $p \times p$ matrix $V$ are spanning the columns and rows of $X$, respectively. $D$ is a $p \times p$ diagonal matrix of singular values $d_{1} \geq \ldots \geq d_{p} \geq 0$ (some might be possible 0 ).

## Ridge Regression

Using singular values decomposition (SVD):

$$
X=U D V^{T}
$$

Where $U$ and $V$ are two orthogonal matrices, $U^{T} U=I_{p}$ and $V^{\top} V=I_{p}$. The columns $u_{j}$ and $v_{j}$ of the $N \times p$ matrix $U$ and the $p \times p$ matrix $V$ are spanning the columns and rows of $X$, respectively. $D$ is a $p \times p$ diagonal matrix of singular values $d_{1} \geq \ldots \geq d_{p} \geq 0$ (some might be possible 0 ). Then ...

## Ridge Regression

Then ...

$$
\begin{aligned}
\hat{\beta}_{\lambda}^{\text {ridge }} & =\left(X^{\top} X+\lambda I_{p}\right)^{-1} X^{\top} y \\
& =\left(\left(U D V^{\top}\right)^{\top}\left(U D V^{\top}\right)+\lambda I_{p}\right)^{-1}\left(U D V^{\top}\right)^{\top} y \\
& =\left(V D^{2} V^{\top}+\lambda V V^{\top}\right)^{-1} V D U^{\top} y \\
& =V \Delta_{\lambda} U^{\top} y
\end{aligned}
$$

where $\Delta_{\lambda}$ is a diagonal matrix with elements $d_{j} /\left(d_{j}^{2}+\lambda\right)$, for $j=1, \ldots, p$.

## Ridge Regression

Then ...

$$
\begin{aligned}
\hat{\beta}_{\lambda}^{\text {ridge }} & =\left(X^{\top} X+\lambda I_{p}\right)^{-1} X^{\top} y \\
& =\left(\left(U D V^{\top}\right)^{T}\left(U D V^{\top}\right)+\lambda I_{p}\right)^{-1}\left(U D V^{\top}\right)^{T} y \\
& =\left(V D^{2} V^{\top}+\lambda V V^{\top}\right)^{-1} V D U^{\top} y \\
& =V \Delta_{\lambda} U^{\top} y
\end{aligned}
$$

where $\Delta_{\lambda}$ is a diagonal matrix with elements $d_{j} /\left(d_{j}^{2}+\lambda\right)$, for

## Ridge Regression

Then ...

$$
\begin{aligned}
\hat{\beta}_{\lambda}^{\text {ridge }} & =\left(X^{\top} X+\lambda I_{p}\right)^{-1} X^{\top} y \\
& =\left(\left(U D V^{\top}\right)^{T}\left(U D V^{\top}\right)+\lambda I_{p}\right)^{-1}\left(U D V^{\top}\right)^{T} y \\
& =\left(V D^{2} V^{\top}+\lambda V V^{\top}\right)^{-1} V D U^{\top} y
\end{aligned}
$$

where $\Delta_{\lambda}$ is a diagonal matrix with elements $d_{j} /\left(d_{j}^{2}+\lambda\right)$, for

## Ridge Regression

Then ...

$$
\begin{aligned}
\hat{\beta}_{\lambda}^{\text {ridge }} & =\left(X^{T} X+\lambda I_{p}\right)^{-1} X^{T} y \\
& =\left(\left(U D V^{T}\right)^{T}\left(U D V^{T}\right)+\lambda I_{p}\right)^{-1}\left(U D V^{T}\right)^{T} y \\
& =\left(V D^{2} V^{T}+\lambda V V^{T}\right)^{-1} V D U^{T} y \\
& =V \Delta_{\lambda} U^{T} y
\end{aligned}
$$

where $\Delta_{\lambda}$ is a diagonal matrix with elements $d_{j} /\left(d_{j}^{2}+\lambda\right)$, for

## Ridge Regression

Then ...

$$
\begin{aligned}
\hat{\beta}_{\lambda}^{\text {ridge }} & =\left(X^{T} X+\lambda I_{p}\right)^{-1} X^{T} y \\
& =\left(\left(U D V^{T}\right)^{T}\left(U D V^{T}\right)+\lambda I_{p}\right)^{-1}\left(U D V^{T}\right)^{T} y \\
& =\left(V D^{2} V^{T}+\lambda V V^{T}\right)^{-1} V D U^{T} y \\
& =V \Delta_{\lambda} U^{T} y
\end{aligned}
$$

where $\Delta_{\lambda}$ is a diagonal matrix with elements $d_{j} /\left(d_{j}^{2}+\lambda\right)$, for $j=1, \ldots, p$.

## Ridge Regression

Thus, the prediction is

$$
\begin{aligned}
\hat{y}_{\lambda}=X \hat{\beta}_{\lambda}^{\text {ridge }} & =H_{\lambda} y \\
& =X\left(X^{\top} X+\lambda I_{p}\right)^{-1} X^{\top} y \\
& =\left(U D V^{\top}\right) V \Delta_{\lambda} U^{\top} y \\
& =U D \Delta_{\lambda} U^{\top} y
\end{aligned}
$$

Note that, $\hat{y}_{0}=U U^{T} y=\sum_{j=1}^{p} u_{j} u_{j}^{T} y$ is the OLS prediction.

## Ridge Regression

Thus, the prediction is

$$
\begin{aligned}
\hat{y}_{\lambda}=X \hat{\beta}_{\lambda}^{\text {ridge }} & =H_{\lambda} y \\
& =X\left(X^{\top} X+\lambda I_{p}\right)^{-1} X^{\top} y \\
& =\left(U D V^{\top}\right) V \Delta_{\lambda} U^{\top} y \\
& =U D \Delta_{\lambda} U^{\top} y
\end{aligned}
$$

Note that, $\hat{y}_{0}=U U^{\top} y=\sum_{j=1}^{p} u_{j} u_{j}^{\top} y$ is the OLS prediction.

## Ridge Regression

Thus, the prediction is

$$
\begin{aligned}
\hat{y}_{\lambda}=X \hat{\beta}_{\lambda}^{\text {ridge }} & =H_{\lambda} y \\
& =X\left(X^{T} X+\lambda I_{p}\right)^{-1} X^{T} y \\
& =\left(U D V^{T}\right) V \Delta_{\lambda} U^{T} y \\
& =U D \Delta_{\lambda} U^{T} y \\
& =\sum_{j=1}^{p} u_{j} \frac{d_{j}^{2}}{d_{j}^{2}+\lambda} u_{j}^{T} y
\end{aligned}
$$

## Ridge Regression

Thus, the prediction is

$$
\begin{aligned}
\hat{y}_{\lambda}=X \hat{\beta}_{\lambda}^{\text {ridge }} & =H_{\lambda} y \\
& =X\left(X^{T} X+\lambda I_{p}\right)^{-1} X^{T} y \\
& =\left(U D V^{T}\right) V \Delta_{\lambda} U^{T} y \\
& =U D \Delta_{\lambda} U^{T} y \\
& =\sum_{j=1}^{p} u_{j} \frac{d_{j}^{2}}{d_{j}^{2}+\lambda} u_{j}^{T} y
\end{aligned}
$$

Note that, $\hat{y}_{0}=U U^{T} y=\sum_{j=1}^{p} u_{j} u_{j}^{T} y$ is the OLS prediction.

## Ridge Regression

Consider centered data $\bar{x}_{j}=0$ for all $j$

- The sample covariance matrix

$$
S=X^{\top} X / N=V D^{2} V^{\top} / N
$$

(eigen decomposition with


$$
\left.V^{T} S V=D^{2} / N\right)
$$

With $d_{1}^{2} / N \geq d_{2}^{2} / N \geq \cdots \geq d_{p}^{2} / N$
The eigen-vectors $v_{j}$ 's are called the
principal components
(Karhunen-Loeve) directions of $X$.
$X v_{1}$ is the (first) largest principal
component since $v_{1}^{\top} X^{\top} X v_{1}=d_{1}^{2} / N$
is the largest sample variance
among all normalized linear
combinations of the columns of X .

## Ridge Regression

Consider centered data $\bar{x}_{j}=0$ for all $j$

- The sample covariance matrix

$$
S=X^{\top} X / N=V D^{2} V^{T} / N
$$

(eigen decomposition with
$\left.V^{\top} S V=D^{2} / N\right)$

- With $d_{1}^{2} / N \geq d_{2}^{2} / N \geq \cdots \geq d_{p}^{2} / N$

The eigen-vectors $v_{j}$ 's are called the principal components (Karhunen-Loeve) directions of $X$.
$X v_{1}$ is the (first) largest principal
is the largest sample variance
among all normalized linear
e.g. principal components in 2D input data


## Ridge Regression

Consider centered data $\bar{x}_{j}=0$ for all $j$

- The sample covariance matrix

$$
S=X^{\top} X / N=V D^{2} V^{T} / N
$$

(eigen decomposition with

$$
\left.V^{T} S V=D^{2} / N\right)
$$

- With $d_{1}^{2} / N \geq d_{2}^{2} / N \geq \cdots \geq d_{p}^{2} / N$
- The eigen-vectors $v_{j}$ 's are called the principal components (Karhunen-Loeve) directions of $X$.
$X_{V_{1}}$ is the (first) largest principal component since $v_{1}^{\top} X^{\top} X v_{1}=d_{1}^{2} / N$ is the largest sample variance among all normalized linear
e.g. principal components in 2D input data



## Ridge Regression

Consider centered data $\bar{x}_{j}=0$ for all $j$

- The sample covariance matrix

$$
S=X^{\top} X / N=V D^{2} V^{\top} / N
$$

(eigen decomposition with

$$
\left.V^{T} S V=D^{2} / N\right)
$$

- With $d_{1}^{2} / N \geq d_{2}^{2} / N \geq \cdots \geq d_{p}^{2} / N$
- The eigen-vectors $v_{j}$ 's are called the principal components
(Karhunen-Loeve) directions of $X$.
- $X v_{1}$ is the (first) largest principal component since $v_{1}^{\top} X^{\top} X v_{1}=d_{1}^{2} / N$ is the largest sample variance among all normalized linear combinations of the columns of X .


## Ridge Regression

Thus, with

$$
\hat{\beta}_{\lambda}^{\text {ridge }}=V \Delta_{\lambda} U^{T} y=\sum_{j=1}^{p} v_{j} \frac{d_{j}}{d_{j}^{2}+\lambda} u_{j}^{T} y
$$

the prediction

$$
\hat{y}_{\lambda}=U D \Delta_{\lambda} U^{T} y=\sum_{j=1}^{p} u_{j} \frac{d_{j}^{2}}{d_{j}^{2}+\lambda} u_{j}^{T} y
$$

is made onto the those components and shrinks the coefficients of the low variance components more than those with high variance.

## Ridge Regression

Define, the effective degrees of freedom to be

$$
d f(\lambda)=\operatorname{tr}\left(H_{\lambda}\right)=\operatorname{tr}\left(D \Delta_{\lambda}\right)=\sum_{j=1}^{p} \frac{d_{j}^{2}}{d_{j}^{2}+\lambda} \leq p
$$

with $d f(\lambda)=p$ at $\lambda=0$.

## Ridge Regression

Define, the effective degrees of freedom to be

$$
d f(\lambda)=\operatorname{tr}\left(H_{\lambda}\right)=\operatorname{tr}\left(D \Delta_{\lambda}\right)=\sum_{j=1}^{p} \frac{d_{j}^{2}}{d_{j}^{2}+\lambda} \leq p
$$

with $d f(\lambda)=p$ at $\lambda=0$.

## Ridge Regression

Example (Prostate Cancer)
Estimated coefficients for different values of $d f(\lambda)$ with optimal $d f=5$ using CV.


## Ridge Regression

## Example (Prostate Cancer)

Estimated coefficients are

| Term | LS | Best Subset | Ridge | Lasso |
| ---: | ---: | ---: | ---: | ---: |
| Intercept | 2.465 | 2.477 | 2.452 | 2.468 |
| lcavol | 0.680 | 0.740 | 0.420 | 0.533 |
| lweight | 0.263 | 0.316 | 0.238 | 0.169 |
| age | -0.141 |  | -0.046 |  |
| lbph | 0.210 |  | 0.162 | 0.002 |
| svi | 0.305 |  | 0.227 | 0.094 |
| lcp | -0.288 |  | 0.000 |  |
| gleason | -0.021 |  | 0.040 |  |
| pgg45 | 0.267 |  | 0.133 |  |
| Test Error | 0.521 | 0.492 | 0.492 | 0.479 |
| Std Error | 0.179 | 0.143 | 0.165 | 0.164 |

Least absolute shrinkage and selection operator (lasso) or basis pursuit

## Lasso

To find $\hat{\beta}^{\text {lasso }}$ that

$$
\begin{gathered}
\operatorname{minimize}_{\beta} R S S(\beta)=\sum_{i=1}^{N}\left[y_{i}-\left(\beta_{0}+\beta_{1} x_{i 1}+\cdots+\beta_{p} x_{i, p}\right)\right]^{2} \\
\text { subject to } \sum_{j=1}^{p}\left|\beta_{j}\right| \leq t \text { (size constraint) }
\end{gathered}
$$


with no closed form.

## Lasso

To find $\hat{\beta}^{\text {lasso }}$ that

$$
\begin{gathered}
\operatorname{minimize}_{\beta} R S S(\beta)=\sum_{i=1}^{N}\left[y_{i}-\left(\beta_{0}+\beta_{1} x_{i 1}+\cdots+\beta_{p} x_{i, p}\right)\right]^{2} \\
\text { subject to } \sum_{j=1}^{p}\left|\beta_{j}\right| \leq t \text { (size constraint) }
\end{gathered}
$$

OR

$$
\hat{\beta}^{\text {lasso }}=\operatorname{argmin}_{\beta}\left[\sum_{i=1}^{N}\left[y_{i}-\left(\beta_{0}+\beta_{1} x_{i 1}+\cdots+\beta_{p} x_{i, p}\right)\right]^{2}+\lambda \sum_{j=1}^{p}\left|\beta_{j}\right|\right]
$$

with no closed form.

## Lasso

To find $\hat{\beta}^{\text {lasso }}$ that

$$
\begin{gathered}
\operatorname{minimize}_{\beta} R S S(\beta)=\sum_{i=1}^{N}\left[y_{i}-\left(\beta_{0}+\beta_{1} x_{i 1}+\cdots+\beta_{p} x_{i, p}\right)\right]^{2} \\
\text { subject to } \sum_{j=1}^{p}\left|\beta_{j}\right| \leq t \text { (size constraint) }
\end{gathered}
$$

OR

$$
\hat{\beta}^{\text {lasso }}=\operatorname{argmin}_{\beta}\left[\sum_{i=1}^{N}\left[y_{i}-\left(\beta_{0}+\beta_{1} x_{i 1}+\cdots+\beta_{p} x_{i, p}\right)\right]^{2}+\lambda \sum_{j=1}^{p}\left|\beta_{j}\right|\right]
$$

with no closed form.

## Lasso

Again, the solution is found using quadratic programming algorithms for each fixed $\lambda$ or using the Least Angel Regression (LARS) (with computational costs comparable to the OLS).

- Standard errors are found computationally using bootstrap methods.
- What does happen when $t$ increases beyond $t_{0}=\sum_{j=1}^{p}\left|\hat{\beta}_{j}^{o s}\right|$ ?


## Lasso

Again, the solution is found using quadratic programming algorithms for each fixed $\lambda$ or using the Least Angel Regression (LARS) (with computational costs comparable to the OLS).

- Standard errors are found computationally using bootstrap methods.
- What does happen when $t$ increases beyond $t_{0}=\sum_{j=1}^{p}\left|\hat{\beta}_{j}^{\prime / s}\right|$ ?

Then $\hat{\beta}^{\text {lasso }}=\hat{\beta}^{\text {ols }}$.

## Lasso

Again, the solution is found using quadratic programming algorithms for each fixed $\lambda$ or using the Least Angel Regression (LARS) (with computational costs comparable to the OLS).

- Standard errors are found computationally using bootstrap methods.
- What does happen when $t$ increases beyond $t_{0}=\sum_{j=1}^{p}\left|\hat{\beta}_{j}^{\prime / s}\right|$ ?

Then $\hat{\beta}^{\text {lasso }}=\hat{\beta}^{\text {ols }}$.

## Lasso

Again, the solution is found using quadratic programming algorithms for each fixed $\lambda$ or using the Least Angel Regression (LARS) (with computational costs comparable to the OLS).

- Standard errors are found computationally using bootstrap methods.
- What does happen when $t$ increases beyond $t_{0}=\sum_{j=1}^{p}\left|\hat{\beta}_{j}^{\prime \mid s}\right|$ ?
Then $\hat{\beta}$ lasso $=\hat{\beta}^{\text {ols }}$.
- Thus, we use a normalized shrinkage factor $s=t / t_{0}$. It can be determined using CV.


## Lasso

Lasso tends to select more parameters, but it works very well when $p>N$. It outperforms subset selection and ridge regression in its predictive error.

## Lasso

- If columns of $X$ are orthonormal ( $X^{\top} X=I$ ), then

$$
\hat{\beta}_{\lambda}^{\text {lasso }}=\operatorname{sign}\left(\hat{\beta}^{o l s}\right)\left(\left|\hat{\beta}^{o l s}\right|-\lambda / 2\right)_{+}
$$

It is called soft thresholding.

## Lasso

## Example (Prostate Cancer)

Estimated coefficients for different values of shrinkage factor $s$ with optimal $s=.36$ using 10 -fold CV.


## Lasso

## Example (Prostate Cancer)

Estimated coefficients are

| Term | LS | Best Subset | Ridge | Lasso |
| ---: | ---: | ---: | ---: | ---: |
| Intercept | 2.465 | 2.477 | 2.452 | 2.468 |
| lcavol | 0.680 | 0.740 | 0.420 | 0.533 |
| lweight | 0.263 | 0.316 | 0.238 | 0.169 |
| age | -0.141 |  | -0.046 |  |
| lbph | 0.210 |  | 0.162 | 0.002 |
| svi | 0.305 |  | 0.227 | 0.094 |
| lcp | -0.288 |  | 0.000 |  |
| gleason | -0.021 |  | 0.040 |  |
| pgg45 | 0.267 |  | 0.133 |  |
| Test Error | 0.521 | 0.492 | 0.492 | 0.479 |
| Std Error | 0.179 | 0.143 | 0.165 | 0.164 |

## Lasso

Contours are for the error function around $\hat{\beta}=\hat{\beta}^{o / s}$


## Elastic-net Method

## Elastic-net Method

$$
\begin{aligned}
\hat{\beta}^{\text {elastic }}= & \operatorname{argmin}_{\beta}\left[\sum_{i=1}^{N}\left[y_{i}-\left(\beta_{0}+\beta_{1} x_{i 1}+\cdots+\beta_{p} x_{i, p}\right)\right]^{2}\right. \\
& \left.+\lambda \sum_{j=1}^{p}\left(\alpha\left|\beta_{j}\right|+(1-\alpha)\left|\beta_{j}\right|^{2}\right)\right]
\end{aligned}
$$

## Elastic-net Method

$$
\begin{aligned}
\hat{\beta}^{\text {elastic }}= & \operatorname{argmin}_{\beta}\left[\sum_{i=1}^{N}\left[y_{i}-\left(\beta_{0}+\beta_{1} x_{i 1}+\cdots+\beta_{p} x_{i, p}\right)\right]^{2}\right. \\
& \left.+\lambda \sum_{j=1}^{p}\left(\alpha\left|\beta_{j}\right|+(1-\alpha)\left|\beta_{j}\right|^{2}\right)\right]
\end{aligned}
$$

Elastic-net selects like a lasso, shrinks like a ridge.
Example
For $\alpha=.8$, the elastic-net penalty $\sum_{j=1}^{2}\left(.8\left|\beta_{j}\right|+.2\left|\beta_{j}\right|^{2}\right) \leq t$

## Elastic-net Method

$$
\begin{aligned}
\hat{\beta}^{\text {elastic }}= & \operatorname{argmin}_{\beta}\left[\sum_{i=1}^{N}\left[y_{i}-\left(\beta_{0}+\beta_{1} x_{i 1}+\cdots+\beta_{p} x_{i, p}\right)\right]^{2}\right. \\
& \left.+\lambda \sum_{j=1}^{p}\left(\alpha\left|\beta_{j}\right|+(1-\alpha)\left|\beta_{j}\right|^{2}\right)\right]
\end{aligned}
$$

Elastic-net selects like a lasso, shrinks like a ridge.
Example
For $\alpha=.8$, the elastic-net penalty $\sum_{j=1}^{2}\left(.8\left|\beta_{j}\right|+.2\left|\beta_{j}\right|^{2}\right) \leq t$


Bridge Method

## Bridge Method

To find $\hat{\beta}^{\text {bridge }}$ that

$$
\begin{gathered}
\operatorname{minimize}_{\beta} R S S(\beta)=\sum_{i=1}^{N}\left[y_{i}-\left(\beta_{0}+\beta_{1} x_{i 1}+\cdots+\beta_{p} x_{i, p}\right)\right]^{2} \\
\text { subject to } \sum_{j=1}^{p}\left|\beta_{j}\right|^{q} \leq t \text { (size constraint) }
\end{gathered}
$$


with no closed form for $0<q \leq 1$.

## Bridge Method

To find $\hat{\beta}^{\text {bridge }}$ that

$$
\begin{gathered}
\operatorname{minimize}_{\beta} R S S(\beta)=\sum_{i=1}^{N}\left[y_{i}-\left(\beta_{0}+\beta_{1} x_{i 1}+\cdots+\beta_{p} x_{i, p}\right)\right]^{2} \\
\text { subject to } \sum_{j=1}^{p}\left|\beta_{j}\right|^{q} \leq t \text { (size constraint) }
\end{gathered}
$$

OR
$\hat{\beta}^{\text {bridge }}=\operatorname{argmin}_{\beta}\left[\sum_{i=1}^{N}\left[y_{i}-\left(\beta_{0}+\beta_{1} x_{i 1}+\cdots+\beta_{p} x_{i, p}\right)\right]^{2}+\lambda \sum_{j=1}^{p}\left|\beta_{j}\right|^{q}\right]$
with no closed form for $0<q \leq 1$.

## Bridge Method

To find $\hat{\beta}^{\text {bridge }}$ that

$$
\begin{gathered}
\operatorname{minimize}_{\beta} R S S(\beta)=\sum_{i=1}^{N}\left[y_{i}-\left(\beta_{0}+\beta_{1} x_{i 1}+\cdots+\beta_{p} x_{i, p}\right)\right]^{2} \\
\text { subject to } \sum_{j=1}^{p}\left|\beta_{j}\right|^{a} \leq t \text { (size constraint) }
\end{gathered}
$$

OR
$\hat{\beta}^{\text {bridge }}=\operatorname{argmin}_{\beta}\left[\sum_{i=1}^{N}\left[y_{i}-\left(\beta_{0}+\beta_{1} x_{i 1}+\cdots+\beta_{p} x_{i, p}\right)\right]^{2}+\lambda \sum_{j=1}^{p}\left|\beta_{j}\right|^{q}\right]$
with no closed form for $0<q \leq 1$.

## Bridge Method

$\left|\beta_{1}\right|^{q}+\left|\beta_{2}\right|^{q} \leq t$ for some $q$ values.






## Bridge Method

- When $q=0$, the penalty term becomes $\lambda \sum_{j=1}^{p} I\left(\beta_{j} \neq 0\right)$ If columns of $X$ are orthonormal $\left(X^{\top} X=I\right)$, then $\hat{\beta}^{\text {bridge }}=\hat{\beta}^{o l s} I\left(\left|\hat{\beta}^{o l s}\right| \geq\left|\hat{\beta}_{(M)}^{o l s}\right|\right)$
where $\hat{\beta}_{(M)}^{o l s}$ is the $M^{\text {th }}$ Iargest coefficient. It is called hard thresholding. It is a subset selection method.


## Bridge Method

- When $q=0$, the penalty term becomes $\lambda \sum_{j=1}^{p} I\left(\beta_{j} \neq 0\right)$
- If columns of $X$ are orthonormal ( $X^{\top} X=I$ ), then

$$
\hat{\beta}^{\text {bridge }}=\hat{\beta}^{o l s} I\left(\left|\hat{\beta}^{o l s}\right| \geq\left|\hat{\beta}_{(M)}^{o l s}\right|\right)
$$

where $\hat{\beta}_{(M)}^{o l s}$ is the $M^{\text {th }}$ largest coefficient. It is called hard thresholding. It is a subset selection method.

# Bayesian Interpretation (bridge, lasso, and ridge) 

## Bayesian Interpretation (bridge, lasso, and ridge)

Define: The generalized Gaussian distribution $G G_{q}\left(\mu, \tau^{2}\right)$ with pdf

$$
f_{q}(x)=\frac{1}{2 \Gamma\left(1+\frac{1}{q}\right) \sqrt{\frac{\Gamma(1 / q)}{\Gamma(3 / q)}} \tau} e^{-\left(\frac{\Gamma(3 / q)}{\Gamma(1 / q)}\right)^{q / 2}\left|\frac{x-\mu}{\tau}\right|^{q}}, \text { for } x \in \mathbb{R}
$$

with mean $\mu$ and variance $\tau^{2}$.

- When $q=1$, then $G G_{1}(\mu, \tau)$ is the Laplace distribution.

$$
f_{1}(x)=\frac{1}{\sqrt{2} \tau} e^{-\sqrt{2}\left|\frac{x-\mu}{\tau}\right|}, \text { for } x \in \mathbb{R}
$$

## Bayesian Interpretation (bridge, lasso, and ridge)

Define: The generalized Gaussian distribution $G G_{q}\left(\mu, \tau^{2}\right)$ with pdf

$$
f_{q}(x)=\frac{1}{2 \Gamma\left(1+\frac{1}{q}\right) \sqrt{\frac{\Gamma(1 / q)}{\Gamma(3 / q)}} \tau} e^{-\left(\frac{\Gamma(3 / q)}{\Gamma(1 / q)}\right)^{q / 2}\left|\frac{x-\mu}{\tau}\right|^{q}}, \text { for } x \in \mathbb{R}
$$

with mean $\mu$ and variance $\tau^{2}$.

- When $q=1$, then $G G_{1}(\mu, \tau)$ is the Laplace distribution.

$$
f_{1}(x)=\frac{1}{\sqrt{2} \tau} e^{-\sqrt{2}\left|\frac{x-\mu}{\tau}\right|}, \text { for } x \in \mathbb{R}
$$

- When $q=2$, then $G G_{2}(\mu, \tau)$ is the normal distribution $N\left(\mu, \tau^{2}\right)$.

$$
f_{2}(x)=\frac{1}{\sqrt{2 \pi} \tau} e^{-\frac{1}{2}\left(\frac{x-\mu}{\tau}\right)^{2}}, \text { for } x \in \mathbb{R}
$$

## Bayesian Interpretation (bridge, lasso, and ridge)

The generalized Gaussian distribution $G G_{q}\left(\mu, \tau^{2}\right)$ with pdf

$$
f_{q}(x)=\frac{1}{2 \Gamma\left(1+\frac{1}{q}\right) \sqrt{\frac{\Gamma(1 / q)}{\Gamma(3 / q)}} \tau} e^{-\left(\frac{\Gamma(3 / q)}{\Gamma(1 / q)}\right)^{q / 2}\left|\frac{x-\mu}{\tau}\right| q}, \text { for } x \in \mathbb{R}
$$

with mean $\mu$ and variance $\tau^{2}$.

- When $q \rightarrow \infty$, then $G G_{q}(\mu, \tau)$ converges point-wise to the uniform distribution Uniform $(\mu-\sqrt{3} \tau, \mu+\sqrt{3} \tau)$.
$>$ When $q \rightarrow 0^{+}$, then $G G_{q}(\mu, \tau)$ converges to a degenerate distribution at $x=\mu$.


## Bayesian Interpretation (bridge, lasso, and ridge)

The generalized Gaussian distribution $G G_{q}\left(\mu, \tau^{2}\right)$ with pdf

$$
f_{q}(x)=\frac{1}{2 \Gamma\left(1+\frac{1}{q}\right) \sqrt{\frac{\Gamma(1 / q)}{\Gamma(3 / q)}} \tau} e^{-\left(\frac{\Gamma(3 / q)}{\Gamma(1 / q)}\right)^{q / 2}\left|\frac{x-\mu}{\tau}\right|^{q}}, \text { for } x \in \mathbb{R}
$$

with mean $\mu$ and variance $\tau^{2}$.

- When $q \rightarrow \infty$, then $G G_{q}(\mu, \tau)$ converges point-wise to the uniform distribution Uniform $(\mu-\sqrt{3} \tau, \mu+\sqrt{3} \tau)$.
- When $q \rightarrow 0^{+}$, then $G G_{q}(\mu, \tau)$ converges to a degenerate distribution at $x=\mu$.


## Bayesian Analysis of Linear Regression

The linear regression model is

$$
Y=X \beta+\epsilon,
$$

where $X$ is a $N \times(p+1)$, and $\epsilon \sim N\left(0, \sigma^{2} I_{N}\right)$.
Then,

$$
Y \sim N\left(X \beta, \sigma^{2} I_{N}\right)
$$

## So the likelihood function is



## Bayesian Analysis of Linear Regression

The linear regression model is

$$
Y=X \beta+\epsilon,
$$

where $X$ is a $N \times(p+1)$, and $\epsilon \sim N\left(0, \sigma^{2} I_{N}\right)$. Then,

$$
Y \sim N\left(X \beta, \sigma^{2} I_{N}\right)
$$

## So the likelihood function is



## Bayesian Analysis of Linear Regression

The linear regression model is

$$
Y=X \beta+\epsilon
$$

where $X$ is a $N \times(p+1)$, and $\epsilon \sim N\left(0, \sigma^{2} I_{N}\right)$.
Then,

$$
Y \sim N\left(X \beta, \sigma^{2} I_{N}\right)
$$

So the likelihood function is

$$
L(\beta, \sigma \mid y)=\prod_{i=1}^{N} \frac{1}{\sqrt{2 \pi} \sigma} e^{-\frac{1}{2}\left(\frac{y_{i}-\left(\beta_{0}+\sum_{j=1}^{p} x_{i, j} \beta_{j}\right)}{\sigma}\right)^{2}}
$$

## Bayesian Analysis of Linear Regression

By Bayes' rule

posterior $\propto$ Likelihood • prior

Choose $G G_{q}(0, \tau)$ to be a prior for each of the coefficients $\beta_{1}, \ldots, \beta_{p}$ (with the assumption that they are independent).
Thus,

## posterior


where $\lambda=2 \sigma^{2}\left(\frac{\Gamma(3 / q)}{\tau^{2} \Gamma(1 / q)}\right)^{q / 2}$

## Bayesian Analysis of Linear Regression

By Bayes' rule
posterior $\propto$ Likelihood • prior
Choose $G G_{q}(0, \tau)$ to be a prior for each of the coefficients $\beta_{1}, \ldots, \beta_{p}$ (with the assumption that they are independent).
$\qquad$

where $\lambda=2 \sigma^{2}\left(\frac{\Gamma(3 / q)}{\tau^{2} \Gamma(1 / q)}\right)^{q / 2}$

## Bayesian Analysis of Linear Regression

By Bayes' rule
posterior $\propto$ Likelihood • prior
Choose $G G_{q}(0, \tau)$ to be a prior for each of the coefficients $\beta_{1}, \ldots, \beta_{p}$ (with the assumption that they are independent). Thus,
posterior $\propto \prod_{i=1}^{N} e^{-\frac{1}{2}\left(\frac{y_{i}-\left(\beta_{0}+\sum_{j=1}^{p} x_{i, j} \beta_{j}\right)}{\sigma}\right)^{2}} \cdot \prod_{j=1}^{p} e^{-\left(\frac{\Gamma(3 / q)}{\Gamma(1 / q)}\right)^{q / 2}\left|\frac{\beta_{j}}{\tau}\right|^{q}}$
where $\lambda=2 \sigma^{2}\left(\frac{\Gamma(3 / q)}{\tau^{2} \Gamma(1 / q)}\right)^{q / 2}$.

## Bayesian Analysis of Linear Regression

By Bayes' rule
posterior $\propto$ Likelihood • prior
Choose $G G_{q}(0, \tau)$ to be a prior for each of the coefficients $\beta_{1}, \ldots, \beta_{p}$ (with the assumption that they are independent). Thus,

$$
\begin{aligned}
\text { posterior } & \propto \prod_{i=1}^{N} e^{-\frac{1}{2}\left(\frac{y_{i}-\left(\beta_{0}+\sum_{j=1}^{p} x_{i, j} \beta_{j}\right)}{\sigma}\right)^{2}} \cdot \prod_{j=1}^{p} e^{-\left(\frac{\Gamma(3 / q)}{\Gamma(1 / q)}\right)^{q / 2}\left|\frac{\beta_{j}}{\tau}\right|^{q}} \\
& =e^{-\frac{1}{2 \sigma^{2}} \sum_{i=1}^{N}\left(y_{i}-\left(\beta_{0}+\sum_{j=1}^{p} x_{i, j} \beta_{j}\right)\right)^{2}} \cdot e^{-\left(\frac{\Gamma(3 / q)}{\tau^{2} \Gamma(1 / q)}\right)^{q / 2} \sum_{j=1}^{p}\left|\beta_{j}\right|^{q}}
\end{aligned}
$$

## Bayesian Analysis of Linear Regression

By Bayes' rule
posterior $\propto$ Likelihood • prior
Choose $G G_{q}(0, \tau)$ to be a prior for each of the coefficients $\beta_{1}, \ldots, \beta_{p}$ (with the assumption that they are independent). Thus,

$$
\begin{aligned}
\text { posterior } & \propto \prod_{i=1}^{N} e^{-\frac{1}{2}\left(\frac{y_{i}-\left(\beta_{0}+\sum_{j=1}^{p} x_{i, j} \beta_{j}\right)}{\sigma}\right)^{2}} \cdot \prod_{j=1}^{p} e^{-\left(\frac{\Gamma(3 / q)}{\Gamma(1 / q)}\right)^{q / 2}\left|\frac{\beta_{j}}{\tau}\right|^{q}} \\
& =e^{-\frac{1}{2 \sigma^{2}} \sum_{i=1}^{N}\left(y_{i}-\left(\beta_{0}+\sum_{j=1}^{p} x_{i, j} \beta_{j}\right)\right)^{2}} \cdot e^{-\left(\frac{\Gamma(3 / q)}{\tau^{2} \Gamma(1 / q)}\right)^{q / 2} \sum_{j=1}^{p}\left|\beta_{j}\right|^{q}} \\
& =e^{-\frac{1}{2 \sigma^{2}}\left[\sum_{i=1}^{N}\left(y_{i}-\left(\beta_{0}+\sum_{j=1}^{p} x_{i, j} \beta_{j}\right)\right)^{2}+\lambda \sum_{j=1}^{p}\left|\beta_{j}\right|^{q}\right]}
\end{aligned}
$$

where $\lambda=2 \sigma^{2}\left(\frac{\Gamma(3 / q)}{\tau^{2} \Gamma(1 / q)}\right)^{q / 2}$.

## Bayesian Analysis of Linear Regression

Thus, - log posterior is a linear function in

$$
\left[\sum_{i=1}^{N}\left(y_{i}-\left(\beta_{0}+\sum_{j=1}^{p} x_{i, j} \beta_{j}\right)\right)^{2}+\lambda \sum_{j=1}^{p}\left|\beta_{j}\right|^{q}\right]
$$

and so the posterior mode (the maximum point of the posterior distribution) is the minimum of the - log posterior and so it is the bridge estimate. If $q=2$, then it is also the mean.

# Principal Component Regression (PCR) - an unsupervised technique for dimension reduction 

## Principal Component Regression (PCR)

Starting with standardized data ...
PCR Idea: rotate the coordinates to reflect the most variability
in the inputs in $X$, using $z_{i}:=X v_{i}$. Then perform regression on the new coordinate system. In that manner,

## Principal Component Regression (PCR)

Starting with standardized data ... PCR Idea: rotate the coordinates to reflect the most variability in the inputs in $X$, using $z_{i}:=X v_{i}$. Then perform regression on the new coordinate system. In that manner,

## Principal Component Regression (PCR)

Starting with standardized data ... PCR Idea: rotate the coordinates to reflect the most variability in the inputs in $X$, using $z_{i}:=X v_{i}$. Then perform regression on the new coordinate system. In that manner,

- We introduce the $N \times M$ matrix $W_{M}=X V$ with an $p \times M$ orthonormal matrix $V$ (with $V V^{T}=I_{p}$ ) for some $M \in\{1,2, \ldots, p\}$
gives a reduced regression
where $\theta=V^{T} \beta$ and so $\beta=V \theta$.


## Principal Component Regression (PCR)

Starting with standardized data ... PCR Idea: rotate the coordinates to reflect the most variability in the inputs in $X$, using $z_{i}:=X v_{i}$. Then perform regression on the new coordinate system. In that manner,

- We introduce the $N \times M$ matrix $W_{M}=X V$ with an $p \times M$ orthonormal matrix $V$ (with $V V^{T}=I_{p}$ ) for some $M \in\{1,2, \ldots, p\}$
- That is, the $i^{\text {th }}$ column of $W_{M}$ is $z_{i}=X v_{i}$.
gives a reduced regression
where $\theta=V^{\top} \beta$ and so $\beta=V \theta$.


## Principal Component Regression (PCR)

Starting with standardized data ...
PCR Idea: rotate the coordinates to reflect the most variability in the inputs in $X$, using $z_{i}:=X v_{i}$. Then perform regression on the new coordinate system. In that manner,

- We introduce the $N \times M$ matrix $W_{M}=X V$ with an $p \times M$ orthonormal matrix $V$ (with $V V^{T}=I_{p}$ ) for some $M \in\{1,2, \ldots, p\}$
- That is, the $i^{\text {th }}$ column of $W_{M}$ is $z_{i}=X v_{i}$.
- Then,

$$
Y=X \beta+\epsilon
$$

gives a reduced regression

$$
Y=W_{M} \theta+\epsilon
$$

where $\theta=V^{\top} \beta$ and so $\beta=V \theta$.

## Principal Component Regression (PCR)

Thus,

- The PCR estimate is

$$
\hat{\beta}^{\mathrm{pcr}}=V \hat{\theta} .
$$

- If $M=p$, then



## Principal Component Regression (PCR)

Thus,

- The PCR estimate is

$$
\hat{\beta}^{\mathrm{pcr}}=V \hat{\theta} .
$$

- If $M=p$, then

$$
\hat{\beta}^{\mathrm{pcr}}=\hat{\beta}^{\mathrm{ols}} .
$$

## Principal Component Regression (PCR)

- PCR starts with principal component analysis (PCA), an unsupervised learning, from $X$.
- PCR shares the idea of principal components with ridge regression
- Ridge Regression shrinks in the principal component directions of the small variance, whereas Principal Component Regression omit those directions (a number of $p-M$ smallest eigenvalues).
- Yet, PCR, like ridge regresion, is not a subset selection method, since the $M$ components $z_{i}$ 's are linear combinations of the $p$ inputs as in $z_{i}=X v_{i}$.


## Principal Component Regression (PCR)

- PCR starts with principal component analysis (PCA), an unsupervised learning, from $X$.
- PCR shares the idea of principal components with ridge regression ...
- Ridge Regression shrinks in the principal component directions of the small variance, whereas Principal Component Regression omit those directions (a number of $p-M$ smallest eigenvalues).
- Yet, PCR, like ridge regresion, is not a subset selection method, since the $M$ components $z_{i}$ 's are linear combinations of the $p$ inputs as in $z_{i}=X v_{i}$.


## Principal Component Regression (PCR)

- PCR starts with principal component analysis (PCA), an unsupervised learning, from $X$.
- PCR shares the idea of principal components with ridge regression ...
- Ridge Regression shrinks in the principal component directions of the small variance, whereas Principal Component Regression omit those directions (a number of $p-M$ smallest eigenvalues).
$\square$
method, since the $M$ components $z_{i}$ 's are linear combinations of the $p$ inputs as in $z_{i}=X v_{i}$.


## Principal Component Regression (PCR)

- PCR starts with principal component analysis (PCA), an unsupervised learning, from $X$.
- PCR shares the idea of principal components with ridge regression ...
- Ridge Regression shrinks in the principal component directions of the small variance, whereas Principal Component Regression omit those directions (a number of $p-M$ smallest eigenvalues).
- Yet, PCR, like ridge regresion, is not a subset selection method, since the $M$ components $z_{i}$ 's are linear combinations of the $p$ inputs as in $z_{i}=X v_{i}$.


## Principal Component Regression (PCR)

## Example (Prostate Cancer)

Shrinkage factor $d^{2} /\left(d^{2}+\lambda\right)$ versus the index of the component


## PCR

## Example (Prostate Cancer)

CV error shows optimal less complex at $M=7$ using 10-fold CV.

Principal Components Regression


## Principal Component Analysis (PCA)

1. For population data $X$ :

Step 1: Find $v_{1}=\operatorname{argmax} \operatorname{Var}(X \omega)=\operatorname{argmax} \omega^{\top} \operatorname{Var}(X) \omega$

Step 2: Find $v_{2}=\operatorname{argmax} \operatorname{Var}(X \omega)$
$\operatorname{Cov}\left(X \omega \cdot X v_{1}\right)=0$

Step $M:$ Find $v_{M}=\begin{gathered}\underset{\substack{\omega: \omega^{\top} \omega=1,}}{\operatorname{argmax}} \operatorname{Cov}\left(X \omega, X v_{i}\right)=0 ; i=1, \ldots, M-1\end{gathered}$
How to determine $M$ ? By CV.

## Principal Component Analysis (PCA)

1. For population data $X$ :

Step 1: Find $v_{1}=\operatorname{argmax} \operatorname{Var}(X \omega)=\operatorname{argmax} \omega^{\top} \operatorname{Var}(X) \omega$

$$
\omega: \omega^{T} \omega=1 \quad \omega: \omega^{T} \omega=1
$$

Step 2: Find $v_{2}=\operatorname{argmax} \operatorname{Var}(X \omega)$


Step $M$ : Find $v_{M}=\quad \operatorname{argmax} \quad \operatorname{Var}(X \omega)$ $\operatorname{Cov}\left(X_{\omega}, X_{i}\right)=0: i=1 \ldots, M-1$

## Principal Component Analysis (PCA)

1. For population data $X$ :

Step 1: Find $v_{1}=\operatorname{argmax} \operatorname{Var}(X \omega)=\operatorname{argmax} \omega^{\top} \operatorname{Var}(X) \omega$

$$
\omega: \omega^{T} \omega=1 \quad \omega: \omega^{T} \omega=1
$$

Step 2: Find $v_{2}=\operatorname{argmax} \operatorname{Var}(X \omega)$

$$
\begin{gathered}
\omega: \omega^{\top} \omega=1, \\
\operatorname{Cov}\left(X \omega, X v_{1}\right)=0
\end{gathered}
$$

Step $M$ : Find $v_{M}=\quad \operatorname{argmax} \quad \operatorname{Var}(X \omega)$ $\operatorname{Cov}\left(X \omega X, Y_{i}\right)=0 ; i=1 \quad M-1$

How to determine M? By CV.

## Principal Component Analysis (PCA)

1. For population data $X$ :

Step 1: Find $v_{1}=\operatorname{argmax} \operatorname{Var}(X \omega)=\operatorname{argmax} \omega^{\top} \operatorname{Var}(X) \omega$

$$
\omega: \omega^{T} \omega=1 \quad \omega: \omega^{T} \omega=1
$$

Step 2: Find $v_{2}=\operatorname{argmax} \operatorname{Var}(X \omega)$

$$
\operatorname{Cov}\left(X \omega, X v_{1}\right)=0
$$

Step $M$ : Find $v_{M}=\quad \operatorname{argmax} \quad \operatorname{Var}(X \omega)$ $\operatorname{Cov}\left(X \omega, X V_{i}\right)=0 ; i=1, \ldots, M-1$

How to determine M? By CV.

## Principal Component Analysis (PCA)

1. For population data $X$ :

Step 1: Find $v_{1}=\operatorname{argmax} \operatorname{Var}(X \omega)=\operatorname{argmax} \omega^{\top} \operatorname{Var}(X) \omega$

$$
\omega: \omega^{\top} \omega=1 \quad \omega: \omega^{\top} \omega=1
$$

Step 2: Find $v_{2}=\operatorname{argmax} \operatorname{Var}(X \omega)$

$$
\begin{gathered}
\omega: \omega^{\top} \omega=1, \\
\operatorname{Cov}\left(X \omega, X v_{1}\right)=0
\end{gathered}
$$

Step $M$ : Find $v_{M}=$

$$
\begin{gathered}
\underset{\substack{\omega: \omega^{\top} \omega=1, \operatorname{argmax}}}{\operatorname{Cov}\left(X \omega, X V_{i}\right)=0 ; i=1, \ldots, M-1}
\end{gathered} \operatorname{Var}(X \omega)
$$

How to determine $M$ ? By CV.

## Principal Component Analysis (PCA)

1. For population data $X$ :

Step 1: Find $v_{1}=\operatorname{argmax} \operatorname{Var}(X \omega)=\operatorname{argmax} \omega^{\top} \operatorname{Var}(X) \omega$

$$
\omega: \omega^{\top} \omega=1 \quad \omega: \omega^{\top} \omega=1
$$

Step 2: Find $v_{2}=\operatorname{argmax} \operatorname{Var}(X \omega)$

$$
\begin{gathered}
\omega: \omega^{\top} \omega=1, \\
\operatorname{Cov}\left(X \omega, X v_{1}\right)=0
\end{gathered}
$$

Step $M$ : Find $v_{M}=$

$$
\begin{gathered}
\underset{\substack{\omega: \omega^{\top} \omega=1, \operatorname{argmax}}}{\operatorname{Cov}\left(X \omega, X V_{i}\right)=0 ; i=1, \ldots, M-1}
\end{gathered} \operatorname{Var}(X \omega)
$$

How to determine $M$ ? By CV.

## Principal Component Analysis (PCA)

1. For population data $X$ :

Step 1: Find $v_{1}=\operatorname{argmax} \operatorname{Var}(X \omega)=\operatorname{argmax} \omega^{\top} \operatorname{Var}(X) \omega$

$$
\omega: \omega^{\top} \omega=1 \quad \omega: \omega^{\top} \omega=1
$$

Step 2: Find $v_{2}=\operatorname{argmax} \operatorname{Var}(X \omega)$

$$
\begin{gathered}
\omega: \omega^{\top} \omega=1, \\
\operatorname{Cov}\left(X \omega, X v_{1}\right)=0
\end{gathered}
$$

Step M: Find $v_{M}=\underset{\substack{\omega: \omega^{\top} \omega=1, \operatorname{Cov}\left(X \omega, X v_{i}\right)=0 ; i=1, \ldots, M-1}}{\operatorname{argmax}} \operatorname{Var}(X \omega)$

How to determine $M$ ?

## Principal Component Analysis (PCA)

1. For population data $X$ :

Step 1: Find $v_{1}=\operatorname{argmax} \operatorname{Var}(X \omega)=\operatorname{argmax} \omega^{\top} \operatorname{Var}(X) \omega$

$$
\omega: \omega^{\top} \omega=1 \quad \omega: \omega^{\top} \omega=1
$$

Step 2: Find $v_{2}=\operatorname{argmax} \operatorname{Var}(X \omega)$

$$
\begin{gathered}
\omega: \omega^{\top} \omega=1, \\
\operatorname{Cov}\left(X \omega, X v_{1}\right)=0
\end{gathered}
$$

Step M: Find $v_{M}=\underset{\substack{\omega: \omega^{\top} \omega=1, \operatorname{Cov}\left(X \omega, X v_{i}\right)=0 ; i=1, \ldots, M-1}}{\operatorname{argmax}} \operatorname{Var}(X \omega)$

How to determine $M$ ? By CV.

## Principal Component Analysis (PCA)

2. For sample data $X$ :


Step $M$ : Find $v_{M}=$ argmax $\omega^{\top} X^{\top} X \omega$ $\omega^{\top} X^{\top} X v=0 i=1 \ldots . M_{1}-1$
But, no guarantee that the directions with the largest
variance/explanation of the predictor, will also be the best for prediction. So ...

## Principal Component Analysis (PCA)

2. For sample data $X$ :

Step 1: Find $v_{1}=\operatorname{argmax} \omega^{\top} X^{\top} X \omega$

$$
\omega: \omega^{\top} \omega=1
$$

Step 2: Find $v_{2}=\operatorname{argmax} \omega^{\top} X^{\top} X \omega$ $\omega_{\omega^{\top} \Psi^{\top} \boldsymbol{\omega}^{\top} \omega X_{1,1}=0}$

But, no guarantee that the directions with the largest
variance/explanation of the predictor, will also be the best for prediction. So ...

## Principal Component Analysis (PCA)

2. For sample data $X$ :

Step 1: Find $v_{1}=\operatorname{argmax} \omega^{\top} X^{\top} X \omega$

$$
\omega: \omega^{T} \omega=1
$$

Step 2: Find $v_{2}=\operatorname{argmax} \omega^{\top} X^{\top} X \omega$

$$
\begin{gathered}
\omega: \omega^{T} \omega=1 \\
\omega^{T} X^{T} X v_{1}=0
\end{gathered}
$$

Step $M$ : Find $v_{M}=$

But, no guarantee that the directions with the largest
variance/explanation of the predictor, will also be the best for prediction. So ...

## Principal Component Analysis (PCA)

2. For sample data $X$ :

Step 1: Find $v_{1}=\operatorname{argmax} \omega^{\top} X^{\top} X \omega$

$$
\omega: \omega^{T} \omega=1
$$

Step 2: Find $v_{2}=\operatorname{argmax} \omega^{\top} X^{\top} X \omega$

$$
\begin{gathered}
\omega: \omega^{T} \omega=1 \\
\omega^{T} X^{T} X v_{1}=0
\end{gathered}
$$

Step $M$ : Find $V_{M}=\quad$ argmax

But, no guarantee that the directions with the largest
variance/explanation of the predictor, will also be the best for prediction. So ...

## Principal Component Analysis (PCA)

2. For sample data $X$ :

Step 1: Find $v_{1}=\operatorname{argmax} \omega^{\top} X^{\top} X \omega$

$$
\omega: \omega^{T} \omega=1
$$

Step 2: Find $v_{2}=\operatorname{argmax} \omega^{\top} X^{\top} X \omega$

$$
\begin{gathered}
\omega: \omega^{\top} \omega=1, \\
\omega^{\top} X^{\top} X v_{1}=0
\end{gathered}
$$

Step $M$ : Find $v_{M}=\quad \operatorname{argmax} \quad \omega^{\top} X^{\top} X \omega$

$$
\omega^{\top} X^{\top} X v_{i}=0 ; i=1, \ldots, M-1
$$

But, no guarantee that the directions with the largest
variance/explanation of the predictor, will also be the best for prediction. So ...

## Principal Component Analysis (PCA)

2. For sample data $X$ :

Step 1: Find $v_{1}=\operatorname{argmax} \omega^{\top} X^{\top} X \omega$

$$
\omega: \omega^{T} \omega=1
$$

Step 2: Find $v_{2}=\operatorname{argmax} \omega^{\top} X^{\top} X \omega$

$$
\begin{gathered}
\omega: \omega^{\top} \omega=1, \\
\omega^{\top} X^{\top} X v_{1}=0
\end{gathered}
$$

Step $M$ : Find $v_{M}=\quad \operatorname{argmax} \quad \omega^{\top} X^{\top} X \omega$

$$
\omega^{\top} X^{\top} X v_{i}=0 ; i=1, \ldots, M-1
$$

But, no guarantee that the directions with the largest
variance/explanation of the predictor, will also be the best for prediction. So ...

## Principal Component Analysis (PCA)

2. For sample data $X$ :

Step 1: Find $v_{1}=\operatorname{argmax} \omega^{\top} X^{\top} X \omega$

$$
\omega: \omega^{\top} \omega=1
$$

Step 2: Find $v_{2}=\operatorname{argmax} \omega^{\top} X^{\top} X \omega$

$$
\begin{gathered}
\omega: \omega^{T} \omega=1 \\
\omega^{T} X^{T} X v_{1}=0
\end{gathered}
$$

Step $M$ : Find $v_{M}=\quad \operatorname{argmax} \quad \omega^{\top} X^{\top} X \omega$

$$
\omega: \omega^{T} \omega=1
$$

$$
\omega^{T} X^{T} X v_{i}=0 ; i=1, \ldots, M-1
$$

But, no guarantee that the directions with the largest variance/explanation of the predictor, will also be the best for prediction. So ...

# Partial Least Squares (PLS) - a supervised technique for dimension reduction 

## Partial Least Squares (PLS)

Starting with standardized data but this time including $Y \ldots$
PLS Idea: rotate the coordinates to reflect the most correlation between the output $Y$ and the inputs in $X$, using PLS directions $z_{i}:=X v_{i}$. Then perform regression on the new coordinate system. In that manner,

## Partial Least Squares (PLS)

Starting with standardized data but this time including $Y \ldots$ PLS Idea: rotate the coordinates to reflect the most correlation between the output $Y$ and the inputs in $X$, using PLS directions $z_{i}:=X v_{i}$. Then perform regression on the new coordinate system. In that manner,

## Partial Least Squares (PLS)

Starting with standardized data but this time including $Y \ldots$ PLS Idea: rotate the coordinates to reflect the most correlation between the output $Y$ and the inputs in $X$, using PLS directions $z_{i}:=X v_{i}$. Then perform regression on the new coordinate system. In that manner,

- We introduce the $N \times M$ matrix $W_{M}=X V$ with an $p \times M$ orthonormal matrix $V$ (with $V V^{T}=I_{p}$ ) for some $M \in\{1,2, \ldots, p\}$
That is, the $i^{\text {th }}$ column of $W_{M}$ is $z_{i}=X v_{i}$.
- Then,
gives a reduced regression
where $\theta=V^{\top} \beta$ and so $\beta=V \theta$.


## Partial Least Squares (PLS)

Starting with standardized data but this time including $Y \ldots$ PLS Idea: rotate the coordinates to reflect the most correlation between the output $Y$ and the inputs in $X$, using PLS directions $z_{i}:=X v_{i}$. Then perform regression on the new coordinate system. In that manner,

- We introduce the $N \times M$ matrix $W_{M}=X V$ with an $p \times M$ orthonormal matrix $V$ (with $V V^{T}=I_{p}$ ) for some $M \in\{1,2, \ldots, p\}$
- That is, the $i^{\text {th }}$ column of $W_{M}$ is $z_{i}=X v_{i}$.
gives a reduced regression
where $\theta=V^{\top} \beta$ and so $\beta=V \theta$.


## Partial Least Squares (PLS)

Starting with standardized data but this time including $Y \ldots$
PLS Idea: rotate the coordinates to reflect the most correlation between the output $Y$ and the inputs in $X$, using PLS directions $z_{i}:=X v_{i}$. Then perform regression on the new coordinate system. In that manner,

- We introduce the $N \times M$ matrix $W_{M}=X V$ with an $p \times M$ orthonormal matrix $V$ (with $V V^{T}=I_{p}$ ) for some $M \in\{1,2, \ldots, p\}$
- That is, the $i^{\text {th }}$ column of $W_{M}$ is $z_{i}=X v_{i}$.
- Then,

$$
Y=X \beta+\epsilon
$$

gives a reduced regression

$$
Y=W_{M} \theta+\epsilon
$$

where $\theta=V^{\top} \beta$ and so $\beta=V \theta$.

## Partial Least Squares (PLS)

Thus,

- The PLS estimate is

$$
\hat{\beta}^{\mathrm{pls}}=V \hat{\theta}
$$

- If $M=p$, then
$\hat{\beta}^{\mathrm{pls}}=\hat{\beta}^{\mathrm{ols}}$.


## Partial Least Squares (PLS)

Thus,

- The PLS estimate is

$$
\hat{\beta}^{\mathrm{pls}}=V \hat{\theta}
$$

- If $M=p$, then

$$
\hat{\beta}^{\mathrm{pls}}=\hat{\beta}^{\mathrm{ols}} .
$$

## PLS Directions $z_{i}=X v_{i}$

For population data $X$ :

```
Step 1: Find
\(v_{1}=\operatorname{argmax} \operatorname{Cov}^{2}(Y, X \omega)=\underset{\operatorname{argmax}}{\operatorname{Corr}}{ }^{2}(Y, X \omega) \operatorname{Var}(X \omega)\)
\(\omega: \omega^{\top} \omega=1 \quad \omega: \omega^{\top} \omega=1\)
```

Step 2: Find $v_{2}=\operatorname{argmax} \operatorname{Cov}^{2}(Y, X \omega)$
$\operatorname{Cov}\left(X_{\omega}, X_{V_{1}}\right)=0$

Step $M$ : Find $v_{M}=$ argmax

$\operatorname{Cov}\left(X\left(\omega, X_{1},\right)-0 \cdot i=1 \quad 1 / \quad 1-1\right.$

How to determine $M$ ? By CV.

## PLS Directions $z_{i}=X v_{i}$

For population data $X$ :
Step 1: Find

$$
v_{1}=\underset{\omega: \omega^{\top} \omega=1}{\operatorname{argmax}} \operatorname{Cov}^{2}(Y, X \omega)=\underset{\omega: \omega^{\top} \omega=1}{\operatorname{argmax}} \operatorname{Corr}^{2}(Y, X \omega) \operatorname{Var}(X \omega)
$$

Step 2: Find $v_{2}=\operatorname{argmax} \operatorname{Cov}^{2}(Y, X \omega)$

Step $M$ : Find $v_{M}=$ argmax $\operatorname{Cov}^{2}(Y, X \omega)$
$\operatorname{Cov}\left(X_{\omega}, x_{1},\right)-0 \cdot i=1, \quad 11-1$

How to determine $M$ ? By CV.

## PLS Directions $z_{i}=X v_{i}$

For population data $X$ :
Step 1: Find

$$
v_{1}=\underset{\omega: \omega^{\top} \omega=1}{\operatorname{argmax}} \operatorname{Cov}^{2}(Y, X \omega)=\underset{\omega: \omega^{\top} \omega=1}{\operatorname{argmax}} \operatorname{Corr}^{2}(Y, X \omega) \operatorname{Var}(X \omega)
$$

Step 2: Find $v_{2}=\operatorname{argmax} \operatorname{Cov}^{2}(Y, X \omega)$

$$
\begin{gathered}
\omega: \omega^{\top} \omega=1, \\
\operatorname{Cov}\left(X \omega, X v_{1}\right)=0
\end{gathered}
$$

Step $M$ : Find $v_{M}=$

## PLS Directions $z_{i}=X v_{i}$

For population data $X$ :
Step 1: Find

$$
v_{1}=\underset{\omega: \omega^{\top} \omega=1}{\operatorname{argmax}} \operatorname{Cov}^{2}(Y, X \omega)=\underset{\omega: \omega^{\top} \omega=1}{\operatorname{argmax}} \operatorname{Corr}^{2}(Y, X \omega) \operatorname{Var}(X \omega)
$$

Step 2: Find $v_{2}=\underset{\operatorname{argmax}}{\operatorname{Cov}}{ }^{2}(Y, X \omega)$

$$
\begin{gathered}
\omega: \omega^{\top} \omega=1, \\
\operatorname{Cov}\left(X \omega, X v_{1}\right)=0
\end{gathered}
$$

Step $M$ : Find $v_{M}=$

## PLS Directions $z_{i}=X v_{i}$

For population data $X$ :
Step 1: Find

$$
v_{1}=\underset{\omega: \omega^{\top} \omega=1}{\operatorname{argmax}} \operatorname{Cov}^{2}(Y, X \omega)=\underset{\omega: \omega^{\top} \omega=1}{\operatorname{argmax}} \operatorname{Corr}^{2}(Y, X \omega) \operatorname{Var}(X \omega)
$$

Step 2: Find $v_{2}=\underset{\operatorname{argmax}}{\operatorname{Cov}}{ }^{2}(Y, X \omega)$

$$
\begin{gathered}
\omega: \omega^{\top} \omega=1, \\
\operatorname{Cov}\left(X \omega, X v_{1}\right)=0
\end{gathered}
$$

Step $M:$ Find $v_{M}=\underset{\substack{\omega: \omega^{\top} \omega=1, \operatorname{Cov}\left(X \omega, X v_{i}\right)=0 ; i=1, \ldots, M-1}}{\operatorname{argmax}} \operatorname{Cov}^{2}(Y, X \omega)$

## PLS Directions $z_{i}=X v_{i}$

For population data $X$ :
Step 1: Find

$$
v_{1}=\underset{\omega: \omega^{\top} \omega=1}{\operatorname{argmax}} \operatorname{Cov}^{2}(Y, X \omega)=\underset{\omega: \omega^{\top} \omega=1}{\operatorname{argmax}} \operatorname{Corr}^{2}(Y, X \omega) \operatorname{Var}(X \omega)
$$

Step 2: Find $v_{2}=\underset{\operatorname{argmax}}{\operatorname{Cov}}{ }^{2}(Y, X \omega)$

$$
\begin{gathered}
\omega: \omega^{\top} \omega=1, \\
\operatorname{Cov}\left(X \omega, X v_{1}\right)=0
\end{gathered}
$$

Step $M:$ Find $v_{M}=\underset{\substack{\omega: \omega^{\top} \omega=1, \operatorname{Cov}\left(X \omega, X v_{i}\right)=0 ; i=1, \ldots, M-1}}{\operatorname{argmax}} \operatorname{Cov}^{2}(Y, X \omega)$

## PLS Directions $z_{i}=X v_{i}$

For population data $X$ :
Step 1: Find

$$
v_{1}=\underset{\omega: \omega^{\top} \omega=1}{\operatorname{argmax}} \operatorname{Cov}^{2}(Y, X \omega)=\underset{\omega: \omega^{\top} \omega=1}{\operatorname{argmax}} \operatorname{Corr}^{2}(Y, X \omega) \operatorname{Var}(X \omega)
$$

Step 2: Find $v_{2}=\operatorname{argmax} \operatorname{Cov}^{2}(Y, X \omega)$

$$
\begin{gathered}
\omega: \omega^{\top} \omega=1, \\
\operatorname{Cov}\left(X \omega, X v_{1}\right)=0
\end{gathered}
$$

Step $M:$ Find $v_{M}=\underset{\substack{\omega: \omega^{\top} \omega=1, \operatorname{Cov}\left(X \omega, X v_{i}\right)=0 ; i=1, \ldots, M-1}}{\operatorname{argmax}} \operatorname{Cov}^{2}(Y, X \omega)$

How to determine $M$ ?

## PLS Directions $z_{i}=X v_{i}$

For population data $X$ :
Step 1: Find

$$
v_{1}=\underset{\omega: \omega^{\top} \omega=1}{\operatorname{argmax}} \operatorname{Cov}^{2}(Y, X \omega)=\underset{\omega: \omega^{\top} \omega=1}{\operatorname{argmax}} \operatorname{Corr}^{2}(Y, X \omega) \operatorname{Var}(X \omega)
$$

Step 2: Find $v_{2}=\underset{\tau}{\operatorname{argmax}} \operatorname{Cov}^{2}(Y, X \omega)$

$$
\begin{gathered}
\omega: \omega^{\top} \omega=1, \\
\operatorname{Cov}\left(X \omega, X v_{1}\right)=0
\end{gathered}
$$

Step $M:$ Find $v_{M}=\underset{\substack{\omega: \omega^{\top} \omega=1, \operatorname{Cov}\left(X \omega, X v_{i}\right)=0 ; i=1, \ldots, M-1}}{\operatorname{argmax}} \operatorname{Cov}^{2}(Y, X \omega)$

How to determine $M$ ? By CV.

## PLS

## Example (Prostate Cancer)

CV error shows optimal less complex at $M=2$ using 10-fold CV.

## Partial Least Squares



## PLS

Example (Prostate Cancer)

| Term | LS | Best Subset | Ridge | Lasso | PCR | PLS |
| ---: | ---: | ---: | ---: | ---: | ---: | ---: |
| Intercept | 2.465 | 2.477 | 2.452 | 2.468 | 2.497 | 2.452 |
| lcavol | 0.680 | 0.740 | 0.420 | 0.533 | 0.543 | 0.419 |
| lweight | 0.263 | 0.316 | 0.238 | 0.169 | 0.289 | 0.344 |
| age | -0.141 |  | -0.046 |  | -0.152 | -0.026 |
| lbph | 0.210 |  | 0.162 | 0.002 | 0.214 | 0.220 |
| svi | 0.305 |  | 0.227 | 0.094 | 0.315 | 0.243 |
| lcp | -0.288 |  | 0.000 |  | -0.051 | 0.079 |
| gleason | -0.021 |  | 0.040 |  | 0.232 | 0.011 |
| pgg45 | 0.267 |  | 0.133 |  | -0.056 | 0.084 |
| Test Error | 0.521 | 0.492 | 0.492 | 0.479 | 0.449 | 0.528 |
| Std Error | 0.179 | 0.143 | 0.165 | 0.164 | 0.105 | 0.152 |

## K-means Regression

## K-means Regression

It is a non-parametric method.
K-means Idea: the simplest is the K-nearest neighbor regression (K-NN). Thus, K-means regression is a local method. In that manner,

## K-means Regression

It is a non-parametric method.
K-means Idea: the simplest is the K-nearest neighbor regression ( $\mathrm{K}-\mathrm{NN}$ ). Thus, K -means regression is a local method. In that manner,

## K-means Regression

It is a non-parametric method.
K-means Idea: the simplest is the K-nearest neighbor regression (K-NN). Thus, K -means regression is a local method. In that manner,

- The predicted response at $x_{*}$ is

$$
\hat{f}\left(x_{*}\right)=\operatorname{Average}\left(y_{i} \mid x_{i} \in N_{k}\left(x_{*}\right)\right)=\frac{1}{k} \sum_{x_{i} \in N_{k}\left(x_{*}\right)} y_{i}
$$

where $N_{k}\left(x_{*}\right)$ is a neighborhood of $x_{*}$ of size $k$.

## K-means Regression

$K=1$ versus $K=9$


## K-means Regression

Parametric functions that really represent the data outperform non-parametric methods. Curse of dimensionality vs overfitting.



## End of Set 3

