## Statistical Learning– MATH 6333 Set 3 (Linear Methods for Regression)

Tamer Oraby UTRGV tamer.oraby@utrgv.edu

< □ > < 同 > < 三 > < 三 > < 三 > < ○ < ○ </p>

\* Last updated September 29, 2021

(日) (日) (日) (日) (日) (日) (日)

The linear regression model

$$f(X) = E(Y|X) = \beta_0 + \beta_1 x_1 + \dots + \beta_p x_p$$

For the training data  $T = \{(x_{i1}, x_{i2}, ..., x_{ip}, y_i) : i = 1, 2, ..., N\}$ 

$$y_i = \beta_0 + \beta_1 x_{i1} + \dots + \beta_p x_{i,p} + \epsilon_i$$

for uncorrelated  $\epsilon_i$ 's, of variance  $\sigma^2$ .

In matrix form

$$\mathbf{y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\epsilon},$$

< □ > < 同 > < 三 > < 三 > < 三 > < ○ < ○ </p>

where X is a  $N \times (p+1)$  matrix with ones in the first column.

Each input  $X_j$  (for j = 1, ..., p) could be one of several types:

- 1. quantitative variable, ex: age, sales, mileage.
- 2. transformation of a quantitative variable, ex: log(age),  $\sqrt{sales}$ , mileage<sup>2</sup>
- 3. as basis expansions, ex: in a polynomial

$$\beta_0 + \beta_1 X_1 + \beta_2 X_1^2 + \beta_3 X_1^3$$

< □ > < 同 > < 三 > < 三 > < 三 > < ○ < ○ </p>

Each input  $X_j$  (for j = 1, ..., p) could be one of several types:

1. quantitative variable, ex: age, sales, mileage.

- 2. transformation of a quantitative variable, ex: log(age),  $\sqrt{sales}$ , mileage<sup>2</sup>
- 3. as basis expansions, ex: in a polynomial

 $\beta_0 + \beta_1 X_1 + \beta_2 X_1^2 + \beta_3 X_1^3$ 

Each input  $X_j$  (for j = 1, ..., p) could be one of several types:

- 1. quantitative variable, ex: age, sales, mileage.
- 2. transformation of a quantitative variable, ex: log(age),  $\sqrt{sales}$ , mileage<sup>2</sup>
- 3. as basis expansions, ex: in a polynomial

$$\beta_0 + \beta_1 X_1 + \beta_2 X_1^2 + \beta_3 X_1^3$$

< □ > < 同 > < 三 > < 三 > < 三 > < ○ < ○ </p>

4. dummy variable (factor), ex: if *G* takes one of the levels 0, 1, or 2, then take  $X_j = I(G = j)$  for j = 1, 2 and so

$$\beta_0 + \beta_1 X_1 + \beta_2 X_2 = \begin{cases} \beta_0 & \text{if } G=0, \\ \beta_0 + \beta_1 & \text{if } G=1, \\ \beta_0 + \beta_2 & \text{if } G=2. \end{cases}$$

< □ > < 同 > < 三 > < 三 > < 三 > < ○ < ○ </p>

interaction between variables, ex: age x mileage

4. dummy variable (factor), ex: if *G* takes one of the levels 0, 1, or 2, then take  $X_j = I(G = j)$  for j = 1, 2 and so

$$\beta_0 + \beta_1 X_1 + \beta_2 X_2 = \begin{cases} \beta_0 & \text{if } G=0, \\ \beta_0 + \beta_1 & \text{if } G=1, \\ \beta_0 + \beta_2 & \text{if } G=2. \end{cases}$$

< □ > < 同 > < 三 > < 三 > < 三 > < ○ < ○ </p>

5. interaction between variables, ex: age x mileage

The method of least squares finds  $\beta$ 's that minimizes residual sums of squares

$$RSS(\beta) = \sum_{i=1}^{N} [y_i - (\beta_0 + \beta_1 x_{i1} + \dots + \beta_p x_{i,p})]^2$$
$$= \sum_{i=1}^{N} (y_i - x_i^T \beta)^2$$
$$= (y - X\beta)^T (y - X\beta)$$

minimize<sub>$$\beta$$</sub>*RSS*( $\beta$ ) =  $(y - X\beta)^T (y - X\beta)$ 

$$\frac{\partial RSS(\beta)}{\partial \beta} = -2X^{T}(y - X\beta) = 0 \implies X^{T}X\beta = X^{T}y.$$
$$\frac{\partial^{2}RSS(\beta)}{\partial \beta = 2X^{T}X}$$

► If X is full column rank (columns are linearly independent), then  $X^T X$  is positive definite and so non-singular, then

$$\hat{\beta} = (X^T X)^{-1} X^T y$$



$$\hat{y} = X\hat{\beta} = \underbrace{X(X^T X)^{-1} X^T}_{H} y$$

< □ > < 同 > < 三 > < 三 > < 三 > < ○ < ○ </p>

minimize<sub>$$\beta$$</sub> RSS( $\beta$ ) =  $(y - X\beta)^T (y - X\beta)$   
 $\frac{\partial RSS(\beta)}{\partial \beta} = -2X^T (y - X\beta) = 0 \implies X^T X\beta = X^T y.$   
 $\frac{\partial^2 RSS(\beta)}{\partial \beta \partial \beta^T} = 2X^T X$ 

► If X is full column rank (columns are linearly independent), then  $X^T X$  is positive definite and so non-singular, then

$$\hat{\beta} = (X^T X)^{-1} X^T y$$

Predictions

1

$$\hat{y} = X\hat{\beta} = \underbrace{X(X^T X)^{-1} X^T}_H y$$

< □ > < 同 > < 三 > < 三 > < 三 > < ○ < ○ </p>

minimize<sub>$$\beta$$</sub>*RSS*( $\beta$ ) =  $(y - X\beta)^T (y - X\beta)$ 

$$\frac{\partial RSS(\beta)}{\partial \beta} = -2X^{T}(y - X\beta) = 0 \implies X^{T}X\beta = X^{T}y.$$

$$\frac{\partial^{2}RSS(\beta)}{\partial \beta} = -2X^{T}(y - X\beta) = 0 \implies X^{T}X\beta = X^{T}y.$$

$$\frac{\partial^2 RSS(\beta)}{\partial \beta \partial \beta^T} = 2X^T X$$

If X is full column rank (columns are linearly independent), then X<sup>T</sup>X is positive definite and so non-singular, then

$$\hat{\beta} = (X^T X)^{-1} X^T y$$



$$\hat{y} = X\hat{\beta} = \underbrace{X(X^T X)^{-1} X^T}_{H} y$$

minimize<sub>$$\beta$$</sub>*RSS*( $\beta$ ) =  $(y - X\beta)^T (y - X\beta)$ 

$$\frac{\partial RSS(\beta)}{\partial \beta} = -2X^{T}(y - X\beta) = 0 \implies X^{T}X\beta = X^{T}y.$$

$$\frac{\partial^{2}RSS(\beta)}{\partial \beta} = -2X^{T}(y - X\beta) = 0 \implies X^{T}X\beta = X^{T}y.$$

$$\frac{\partial^2 RSS(\beta)}{\partial \beta \partial \beta^T} = 2X^T X$$

If X is full column rank (columns are linearly independent), then X<sup>T</sup>X is positive definite and so non-singular, then

$$\hat{\beta} = (X^T X)^{-1} X^T y$$

Predictions

$$\hat{\mathbf{y}} = \mathbf{X}\hat{\boldsymbol{\beta}} = \underbrace{\mathbf{X}(\mathbf{X}^T\mathbf{X})^{-1}\mathbf{X}^T}_{H}\mathbf{y}$$

• If  $y_i$ 's are uncorrelated and have variance  $\sigma^2$ , then

$$Var(\hat{eta}) = (X^T X)^{-1} \sigma^2$$

#### if $x_i$ 's are fixed.

• An unbiased estimator of  $\sigma^2$  is

$$\widehat{r^2} = \frac{RSS(\widehat{\beta})}{N - p - 1}$$

$$= \frac{(y - X\widehat{\beta})^T (y - X\widehat{\beta})}{N - p - 1}$$

$$= \frac{(y - \widehat{y})^T (y - \widehat{y})}{N - p - 1}$$

$$= \frac{1}{N - p - 1} \sum_{i=1}^N (y_i - \widehat{y}_i)^2$$

◆□ ▶ ◆□ ▶ ◆ □ ▶ ◆ □ ▶ ● ● ● ● ●

• If  $y_i$ 's are uncorrelated and have variance  $\sigma^2$ , then

$$Var(\hat{eta}) = (X^T X)^{-1} \sigma^2$$

if  $x_i$ 's are fixed.

• An unbiased estimator of  $\sigma^2$  is

$$\widehat{r^2} = \frac{RSS(\widehat{\beta})}{N - p - 1}$$

$$= \frac{(y - X\widehat{\beta})^T (y - X\widehat{\beta})}{N - p - 1}$$

$$= \frac{(y - \widehat{y})^T (y - \widehat{y})}{N - p - 1}$$

$$= \frac{1}{N - p - 1} \sum_{i=1}^N (y_i - \widehat{y}_i)^2$$

(ロ) (同) (三) (三) (三) (○) (○)

What if columns are not linearly independent?

That is, what if they are perfectly correlated

 $X_i = \text{constant} \times X_i$ 

for some *i* and *j*.

Then,  $\hat{\beta}$  is not uniquely defined.

Solutions:

- Re-code redundant qualitative inputs
- If p is much larger than N, then the number of inputs p is reduced by filtering.

(日) (日) (日) (日) (日) (日) (日)

What if columns are not linearly independent?

That is, what if they are perfectly correlated

 $X_i = \text{constant} \times X_j$ 

for some *i* and *j*.

Then,  $\hat{\beta}$  is not uniquely defined.

Solutions:

- Re-code redundant qualitative inputs
- If p is much larger than N, then the number of inputs p is reduced by filtering.

< □ > < 同 > < 三 > < 三 > < 三 > < ○ < ○ </p>

What if columns are not linearly independent?

That is, what if they are perfectly correlated

 $X_i = \text{constant} \times X_i$ 

for some *i* and *j*.

Then,  $\hat{\beta}$  is not uniquely defined.

Solutions:

- Re-code redundant qualitative inputs
- If p is much larger than N, then the number of inputs p is reduced by filtering.

◆□▶ ◆□▶ ◆□▶ ◆□▶ ● ● ● ●

If  $\epsilon_i$  are iidrv such that  $\epsilon_i \sim N(0, \sigma^2)$ , then

$$\hat{eta} \sim \mathcal{N}(eta, (X^T X)^{-1} \sigma^2),$$
 $c^T \hat{eta} = \sum_{j=0}^p c_j \hat{eta}_j \sim \mathcal{N}(c^T eta, c^T (X^T X)^{-1} c \sigma^2),$ 

for a non-zero vector c, and

$$(N-p-1)\frac{\widehat{\sigma^2}}{\sigma^2} \sim \chi^2_{N-p-1}.$$

< □ > < 同 > < 三 > < 三 > < 三 > < ○ < ○ </p>

Moreover,  $\hat{\beta}$  and  $\widehat{\sigma^2}$  are statistically independent. Thus, ...

...

$$\frac{\boldsymbol{c}^{\mathsf{T}}\hat{\boldsymbol{\beta}} - \boldsymbol{c}^{\mathsf{T}}\boldsymbol{\beta}}{\hat{\sigma}\sqrt{\boldsymbol{c}^{\mathsf{T}}(\boldsymbol{X}^{\mathsf{T}}\boldsymbol{X})^{-1}\boldsymbol{c}}} \sim T_{N-p-1}$$

Example If  $c = e_j = (0, \dots, 0, \underbrace{1}_{j^{th}}, \dots, 0)^T$ , then  $c^T \beta = \beta_j$  and  $c^T (X^T X)^{-1} c = ((X^T X)^{-1})_{ii} =: v_{ii}$ 

the  $j^{th}$  diagonal element of  $(X^T X)^{-1}$ . Therefore,

$$rac{\hat{eta}_j - eta_j}{\hat{\sigma} \sqrt{m{v}_{jj}}} \sim m{T}_{m{N}-m{
ho}-1}$$

▲□▶ ▲圖▶ ▲≣▶ ▲≣▶ → ≣ → のへで

## Example If $c = (0, \dots, 0, \underbrace{1}_{i^{th}}, 0, \dots, 0, \underbrace{-1}_{j^{th}}, \dots, 0)^T$ , then $c^T \beta = \beta_i - \beta_j$ and $c^T (X^T X)^{-1} c = v_{ii} + v_{ii} - v_{ii} - v_{ii}$

where  $v_{ij}$  the  $ij^{th}$  element of  $(X^T X)^{-1}$ . Therefore,

$$\frac{(\hat{\beta}_i - \hat{\beta}_j) - (\beta_i - \beta_j)}{\hat{\sigma} \sqrt{\mathbf{v}_{ii} + \mathbf{v}_{jj} - \mathbf{v}_{ij} - \mathbf{v}_{jj}}} \sim T_{N-p-1}$$

◆□▶ ◆□▶ ◆□▶ ◆□▶ ● ● ● ●

Now, since

$$\frac{\boldsymbol{c}^{\mathsf{T}}\hat{\boldsymbol{\beta}} - \boldsymbol{c}^{\mathsf{T}}\boldsymbol{\beta}}{\hat{\sigma}\sqrt{\boldsymbol{c}^{\mathsf{T}}(\boldsymbol{X}^{\mathsf{T}}\boldsymbol{X})^{-1}\boldsymbol{c}}} \sim T_{\boldsymbol{N}-\boldsymbol{p}-1}$$

#### then

A  $(1 - \alpha)$ 100% confidence interval for  $c^T \beta$  is given by

$$c^{T}\hat{eta}\pm t_{lpha/2,N-
ho-1}\hat{\sigma}\sqrt{c^{T}(X^{T}X)^{-1}c}$$

To test

 $H_0: c^T \beta = d_0 \text{ vs } H_A: c^T \beta \neq d_0, c^T \beta < d_0, \text{ or } c^T \beta > d_0$ 

use a test statistic

$$t = \frac{c^T \hat{\beta} - d_0}{\hat{\sigma} \sqrt{c^T (X^T X)^{-1} c}}$$

Now, since

$$\frac{\boldsymbol{c}^{\mathsf{T}}\hat{\beta} - \boldsymbol{c}^{\mathsf{T}}\beta}{\hat{\sigma}\sqrt{\boldsymbol{c}^{\mathsf{T}}(\boldsymbol{X}^{\mathsf{T}}\boldsymbol{X})^{-1}\boldsymbol{c}}} \sim T_{N-p-1}$$

then

A  $(1 - \alpha)100\%$  confidence interval for  $c^T\beta$  is given by

$$c^{\mathsf{T}}\hat{\beta} \pm t_{\alpha/2,\mathsf{N}-p-1} \hat{\sigma} \sqrt{c^{\mathsf{T}}(X^{\mathsf{T}}X)^{-1}c}$$

To test

 $H_0: c^T \beta = d_0 \text{ vs } H_A: c^T \beta \neq d_0, c^T \beta < d_0, \text{ or } c^T \beta > d_0$ 

use a test statistic

$$t = \frac{c^T \hat{\beta} - d_0}{\hat{\sigma} \sqrt{c^T (X^T X)^{-1} c}}$$

Now, since

$$\frac{\boldsymbol{c}^{\mathsf{T}}\hat{\beta} - \boldsymbol{c}^{\mathsf{T}}\beta}{\hat{\sigma}\sqrt{\boldsymbol{c}^{\mathsf{T}}(\boldsymbol{X}^{\mathsf{T}}\boldsymbol{X})^{-1}\boldsymbol{c}}} \sim T_{N-p-1}$$

then

A  $(1 - \alpha)100\%$  confidence interval for  $c^T\beta$  is given by

$$c^{\mathsf{T}}\hat{\beta} \pm t_{\alpha/2,\mathsf{N}-p-1} \hat{\sigma} \sqrt{c^{\mathsf{T}}(X^{\mathsf{T}}X)^{-1}c}$$

To test

$$H_0: \boldsymbol{c}^{\mathsf{T}}\beta = \boldsymbol{d}_0 \text{ vs } H_{\mathsf{A}}: \boldsymbol{c}^{\mathsf{T}}\beta \neq \boldsymbol{d}_0, \boldsymbol{c}^{\mathsf{T}}\beta < \boldsymbol{d}_0, \text{ or } \boldsymbol{c}^{\mathsf{T}}\beta > \boldsymbol{d}_0$$

use a test statistic

$$t = \frac{c^T \hat{\beta} - d_0}{\hat{\sigma} \sqrt{c^T (X^T X)^{-1} c}}$$

Example To test

$$H_0: \beta_j = 0 \text{ vs } H_A: \beta_j \neq 0$$

use a test statistic

$$t = \frac{\hat{\beta}_j}{\hat{\sigma}\sqrt{\mathbf{v}_{jj}}}$$

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ - 三 - のへぐ

Example To test

$$H_0: \beta_i = \beta_j \text{ vs } H_A: \beta_i \neq \beta_j$$

use a test statistic

$$t = rac{\hat{eta}_i - \hat{eta}_j}{\hat{\sigma} \sqrt{m{v}_{ii} + m{v}_{jj} - m{v}_{ij} - m{v}_{jj}}}$$

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ - 三 - のへぐ

◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ ののの

To make a prediction for a new input vector  $x_* = (x_{*1}, \ldots, x_{*p})^T$ , then

- ► A point estimate is  $\hat{y} = x_*^T \hat{\beta}$ .
- A (1 − α)100% confidence interval for the mean response E(y|x<sub>\*</sub>) = x<sub>\*</sub><sup>T</sup>β is given by

$$x_*^T \hat{\beta} \pm t_{\alpha/2,N-p-1} \hat{\sigma} \sqrt{x_*^T (X^T X)^{-1} x_*}$$

A (1 − α)100% confidence interval for predicted response y at x<sub>\*</sub> is given by

$$x_*^{ op} \hat{eta} \pm t_{lpha/2,N-
ho-1} \, \hat{\sigma} \sqrt{1 + x_*^{ op} (X^{ op} X)^{-1} x_*}$$

(日) (日) (日) (日) (日) (日) (日)

To make a prediction for a new input vector  $x_* = (x_{*1}, \ldots, x_{*p})^T$ , then

- A point estimate is  $\hat{y} = x_*^T \hat{\beta}$ .
- A (1 α)100% confidence interval for the mean response
   E(y|x<sub>\*</sub>) = x<sub>\*</sub><sup>T</sup>β is given by

$$x_*^T \hat{\beta} \pm t_{\alpha/2, N-p-1} \hat{\sigma} \sqrt{x_*^T (X^T X)^{-1} x_*}$$

 A (1 – α)100% confidence interval for predicted response y at x<sub>\*</sub> is given by

$$x_*^T \hat{\beta} \pm t_{\alpha/2, N-p-1} \hat{\sigma} \sqrt{1 + x_*^T (X^T X)^{-1} x_*}$$

To make a prediction for a new input vector  $x_* = (x_{*1}, \ldots, x_{*p})^T$ , then

- A point estimate is  $\hat{y} = x_*^T \hat{\beta}$ .
- A (1 − α)100% confidence interval for the mean response E(y|x<sub>\*</sub>) = x<sub>\*</sub><sup>T</sup>β is given by

$$\boldsymbol{x}_{*}^{\mathsf{T}}\hat{\boldsymbol{\beta}} \pm \boldsymbol{t}_{\alpha/2,\boldsymbol{N}-\boldsymbol{p}-1}\,\hat{\sigma}\sqrt{\boldsymbol{x}_{*}^{\mathsf{T}}(\boldsymbol{X}^{\mathsf{T}}\boldsymbol{X})^{-1}\boldsymbol{x}_{*}}$$

 A (1 – α)100% confidence interval for predicted response y at x<sub>\*</sub> is given by

$$X_*^T \hat{eta} \pm t_{lpha/2, N-p-1} \, \hat{\sigma} \sqrt{1 + X_*^T (X^T X)^{-1} X_*}$$

To make a prediction for a new input vector  $x_* = (x_{*1}, \ldots, x_{*p})^T$ , then

- A point estimate is  $\hat{y} = x_*^T \hat{\beta}$ .
- A (1 − α)100% confidence interval for the mean response E(y|x<sub>\*</sub>) = x<sub>\*</sub><sup>T</sup>β is given by

$$\boldsymbol{x}_*^{\mathsf{T}} \hat{\boldsymbol{\beta}} \pm \boldsymbol{t}_{\alpha/2, N-p-1} \, \hat{\boldsymbol{\sigma}} \sqrt{\boldsymbol{x}_*^{\mathsf{T}} (\boldsymbol{X}^{\mathsf{T}} \boldsymbol{X})^{-1} \boldsymbol{x}_*}$$

 A (1 – α)100% confidence interval for predicted response y at x<sub>\*</sub> is given by

$$X_*^T \hat{eta} \pm t_{lpha/2, N-p-1} \, \hat{\sigma} \sqrt{1 + X_*^T (X^T X)^{-1} X_*}$$

< □ > < 同 > < 三 > < 三 > < 三 > < ○ < ○ </p>

#### To test

$$H_0: \beta_{j_1} = \beta_{j_2} = \cdots = \beta_{j_k} = 0$$
 (restricted model  $M_0$ ) vs

 $H_A$ : At least one  $\beta_{j_i} \neq 0$ ; for  $i = 1, 2, \dots, k$ 

use a test statistic

$$f = \frac{(RSS(\hat{\beta}_{\text{restricted}}) - RSS(\hat{\beta}_{\text{full}}))/k}{RSS(\hat{\beta}_{\text{full}})/(N - p - 1)}$$

and p - value = P(F > f) using the F-distribution with degrees of freedom  $df_1 = k$  and  $df_2 = N - p - 1$ .

Note:  $RSS(\hat{\beta}_{restricted})$  is the residuals sum of squares of the (nested) model restricted to  $\beta_{j_1} = \beta_{j_2} = \cdots = \beta_{j_k} = 0$ 

#### To test

$$H_0: \beta_{j_1} = \beta_{j_2} = \cdots = \beta_{j_k} = 0$$
 (restricted model  $M_0$ ) vs

 $H_A$ : At least one  $\beta_{j_i} \neq 0$ ; for  $i = 1, 2, \dots, k$ 

use a test statistic

$$f = \frac{(RSS(\hat{\beta}_{\mathsf{restricted}}) - RSS(\hat{\beta}_{\mathsf{full}}))/k}{RSS(\hat{\beta}_{\mathsf{full}})/(N - p - 1)}$$

and p - value = P(F > f) using the F-distribution with degrees of freedom  $df_1 = k$  and  $df_2 = N - p - 1$ .

Note:  $RSS(\hat{\beta}_{restricted})$  is the residuals sum of squares of the (nested) model restricted to  $\beta_{j_1} = \beta_{j_2} = \cdots = \beta_{j_k} = 0$ 

#### To test

$$H_0: \beta_{j_1} = \beta_{j_2} = \cdots = \beta_{j_k} = 0$$
 (restricted model  $M_0$ ) vs

 $H_A$ : At least one  $\beta_{j_i} \neq 0$ ; for  $i = 1, 2, \dots, k$ 

use a test statistic

$$f = \frac{(RSS(\hat{\beta}_{\mathsf{restricted}}) - RSS(\hat{\beta}_{\mathsf{full}}))/k}{RSS(\hat{\beta}_{\mathsf{full}})/(N - p - 1)}$$

and p - value = P(F > f) using the F-distribution with degrees of freedom  $df_1 = k$  and  $df_2 = N - p - 1$ .

Note:  $RSS(\hat{\beta}_{restricted})$  is the residuals sum of squares of the (nested) model restricted to  $\beta_{j_1} = \beta_{j_2} = \cdots = \beta_{j_k} = 0$
1. The coefficient of determination

$$R^2 = 1 - \frac{SSE}{SST} = \frac{SSR}{SST}$$

where the sums of squares of error is

$$SSE = RSS(\hat{eta}) = \sum_{i=1}^{N} (y_i - \hat{y}_i)^2$$

and the total sums of squares in

$$SST = \sum_{i=1}^{N} (y_i - \bar{y})^2.$$

The regression sums of squares

$$SSR = SST - SSE = \sum_{i=1}^{N} (\hat{y}_i - \bar{y})^2$$

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □

1. The coefficient of determination

$$R^2 = 1 - \frac{SSE}{SST} = \frac{SSR}{SST}$$

where the sums of squares of error is

$$SSE = RSS(\hat{eta}) = \sum_{i=1}^{N} (y_i - \hat{y}_i)^2$$

and the total sums of squares in

$$SST = \sum_{i=1}^{N} (y_i - \bar{y})^2$$

The regression sums of squares

$$SSR = SST - SSE = \sum_{i=1}^{N} (\hat{y}_i - \bar{y})^2$$

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □

1. The coefficient of determination

$$R^2 = 1 - \frac{SSE}{SST} = \frac{SSR}{SST}$$

where the sums of squares of error is

$$SSE = RSS(\hat{eta}) = \sum_{i=1}^{N} (y_i - \hat{y}_i)^2$$

and the total sums of squares in

$$SST = \sum_{i=1}^{N} (y_i - \bar{y})^2.$$

The regression sums of squares

$$SSR = SST - SSE = \sum_{i=1}^{N} (\hat{y}_i - \bar{y})^2$$

▲□▶ ▲□▶ ▲□▶ ▲□▶ = 三 のへで

1. The coefficient of determination

$$R^2 = 1 - \frac{SSE}{SST} = \frac{SSR}{SST}$$

where the sums of squares of error is

$$SSE = RSS(\hat{eta}) = \sum_{i=1}^{N} (y_i - \hat{y}_i)^2$$

and the total sums of squares in

$$SST = \sum_{i=1}^{N} (y_i - \bar{y})^2.$$

The regression sums of squares

$$SSR = SST - SSE = \sum_{i=1}^{N} (\hat{y}_i - \bar{y})^2$$

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □

2. The adjusted coefficient of determination

$$R_{adj}^2 = 1 - (1 - R^2) \frac{N - 1}{N - p - 1} = 1 - \frac{MSE}{MST}$$

where the mean sums of squares of error is

$$MSE = \frac{SSE}{N - p - 1} = \widehat{\sigma^2}$$

and the mean total sums of squares in

$$MST = \frac{SST}{N-1}.$$

The closer  $R^2$  and  $R^2_{adj}$  are to one (or 100%), the better the fit is. (Note:  $R^2_{adj} \le R^2$ .)

2. The adjusted coefficient of determination

$$R_{adj}^2 = 1 - (1 - R^2) \frac{N - 1}{N - p - 1} = 1 - \frac{MSE}{MST}$$

where the mean sums of squares of error is

$$MSE = \frac{SSE}{N-p-1} = \widehat{\sigma^2}$$

and the mean total sums of squares in

$$MST = \frac{SST}{N-1}.$$

The closer  $R^2$  and  $R^2_{adj}$  are to one (or 100%), the better the fit is. (Note:  $R^2_{adj} \le R^2$ .)

2. The adjusted coefficient of determination

$$R_{adj}^2 = 1 - (1 - R^2) \frac{N - 1}{N - p - 1} = 1 - \frac{MSE}{MST}$$

where the mean sums of squares of error is

$$MSE = \frac{SSE}{N - p - 1} = \widehat{\sigma^2}$$

and the mean total sums of squares in

$$MST = \frac{SST}{N-1}.$$

The closer  $R^2$  and  $R^2_{adj}$  are to one (or 100%), the better the fit is. (Note:  $R^2_{adj} \le R^2$ .)

2. The adjusted coefficient of determination

$$R_{adj}^2 = 1 - (1 - R^2) \frac{N - 1}{N - p - 1} = 1 - \frac{MSE}{MST}$$

where the mean sums of squares of error is

$$MSE = \frac{SSE}{N-p-1} = \widehat{\sigma^2}$$

and the mean total sums of squares in

$$MST = \frac{SST}{N-1}.$$

The closer  $R^2$  and  $R^2_{adj}$  are to one (or 100%), the better the fit is. (Note:  $R^2_{adj} \le R^2$ .)

 Residual analyses to make sure of the homogeneity (to see no pattern in scatter plots of residuals vs fitted values) and normality of the residuals using Normal Q-Q plot and Shapiro-Wilk test.

4. Tests of outliers (points standing far away from the bulk of the data) and influential points (which if removed, result in significant change to the model).

< □ > < 同 > < 三 > < 三 > < 三 > < ○ < ○ </p>

 Residual analyses to make sure of the homogeneity (to see no pattern in scatter plots of residuals vs fitted values) and normality of the residuals using Normal Q-Q plot and Shapiro-Wilk test.

4. Tests of outliers (points standing far away from the bulk of the data) and influential points (which if removed, result in significant change to the model).

(ロ) (同) (三) (三) (三) (○) (○)



#### **Example: Prostate Cancer**



Sac

#### Example: Prostate Cancer

$$N = 67$$
 and  $p = 8$ .

	lcavol	lweight	age	lbph	svi	lcp	gleason
lweight	0.300						
age	0.286	0.317					
lbph	0.063	0.437	0.287				
svi	0.593	0.181	0.129	-0.139			
lcp	0.692	0.157	0.173	-0.089	0.671		
gleason	0.426	0.024	0.366	0.033	0.307	0.476	
pgg45	0.483	0.074	0.276	-0.030	0.481	0.663	0.757

◆□▶ ◆□▶ ◆ □▶ ◆ □▶ ● □ ● ● ●

oefficient	Std. Error	Z Score
2.46	0.09	27.60
0.68	0.13	5.37
0.26	0.10	2.75
-0.14	0.10	-1.40
0.21	0.10	2.06
0.31	0.12	2.47
-0.29	0.15	-1.87
-0.02	0.15	-0.15
0.27	0.15	1.74
	$2.46 \\ 0.68 \\ 0.26 \\ -0.14 \\ 0.21 \\ 0.31 \\ -0.29 \\ -0.02 \\ 0.27$	$\begin{array}{ccccccc} 2.46 & 0.09 \\ 0.68 & 0.13 \\ 0.26 & 0.10 \\ -0.14 & 0.10 \\ 0.21 & 0.10 \\ 0.31 & 0.12 \\ -0.29 & 0.15 \\ -0.02 & 0.15 \\ 0.27 & 0.15 \end{array}$

Dropping the least significant inputs: age, lcp, gleason, and pgg45, leads to F test statistics

$$f = \frac{(32.81 - 29.43)/4}{29.43/(67 - 8 - 1)} = 1.67$$

with  $p - value = P(F_{4,58} > 1.67) = .17$  which is not significant. Thus, it is concluded to remove those inputs.

# Is LS the best method for prediction?

◆□▶ ◆□▶ ◆□▶ ◆□▶ ● ● ● ●

**Recall:**  $c^T \hat{\beta} = c^T (X^T X)^{-1} X^T y =: c_0^T y$  is unbiased (linear) estimator of  $c^T \beta$  and  $Var(c^T \hat{\beta}) = c^T (X^T X)^{-1} c \sigma^2$ .

**Theorem (The Gauss-Markov Theorem)** Let  $c_1^T y$  be another unbiased (linear) estimator of  $c^T \beta$ , then

 $Var(c^T\hat{\beta}) \leq Var(c_1^Ty)$ 

In general, the mean squared error

$$MSE(\hat{\theta}) = E(\hat{\theta} - \theta)^{2}$$
$$= Var(\hat{\theta}) + [\underline{E(\hat{\theta}) - \theta}]^{2}$$
$$\underset{\text{Bias}(\hat{\theta})}{\text{Bias}(\hat{\theta})}$$

(日) (日) (日) (日) (日) (日) (日)

**Recall:**  $c^T \hat{\beta} = c^T (X^T X)^{-1} X^T y =: c_0^T y$  is unbiased (linear) estimator of  $c^T \beta$  and  $Var(c^T \hat{\beta}) = c^T (X^T X)^{-1} c \sigma^2$ .

Theorem (The Gauss-Markov Theorem) Let  $c_1^T y$  be another unbiased (linear) estimator of  $c^T \beta$ , then

 $Var(c^T\hat{\beta}) \leq Var(c_1^T y)$ 

In general, the mean squared error

$$MSE(\hat{\theta}) = E(\hat{\theta} - \theta)^{2}$$
$$= Var(\hat{\theta}) + [\underline{E(\hat{\theta}) - \theta}]^{2}$$
$$\underset{\text{Bias}(\hat{\theta})}{\text{Bias}(\hat{\theta})}$$

・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・

**Recall:**  $c^T \hat{\beta} = c^T (X^T X)^{-1} X^T y =: c_0^T y$  is unbiased (linear) estimator of  $c^T \beta$  and  $Var(c^T \hat{\beta}) = c^T (X^T X)^{-1} c \sigma^2$ .

Theorem (The Gauss-Markov Theorem) Let  $c_1^T y$  be another unbiased (linear) estimator of  $c^T \beta$ , then

$$Var(c^T\hat{\beta}) \leq Var(c_1^T y)$$

In general, the mean squared error

$$\begin{split} \textit{MSE}(\hat{\theta}) &= \textit{E}(\hat{\theta} - \theta)^2 \\ &= \textit{Var}(\hat{\theta}) + [\underbrace{\textit{E}(\hat{\theta}) - \theta}_{\textit{Bias}(\hat{\theta})}]^2 \end{split}$$

・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・

How is it related to the expected prediction error (EPE) for  $Y_* = f(x_*) + \epsilon_*$ ?

$$\begin{split} EPE &= E(Y_* - \hat{f}(x_*))^2 \\ &= E(\hat{f}(x_*) - f(x_*))^2 + \sigma^2 \\ &= MSE(\hat{f}(x_*)) + \sigma^2 \\ &= MSE(x_*^T \hat{\beta}) + \sigma^2 \end{split}$$

Thus, a small  $MSE(x_*^T\hat{\beta})$  is better for prediction, even when  $Bias(x_*^T\hat{\beta}) > 0$ .

So, smaller number of predictors (shrinking) might be advised over a more detailed model. Also, a method other than OLS with smaller MSE, is more advisable for prediction.

How is it related to the expected prediction error (EPE) for  $Y_* = f(x_*) + \epsilon_*$ ?

$$\begin{split} EPE &= E(Y_* - \hat{f}(x_*))^2 \\ &= E(\hat{f}(x_*) - f(x_*))^2 + \sigma^2 \\ &= MSE(\hat{f}(x_*)) + \sigma^2 \\ &= MSE(x_*^T \hat{\beta}) + \sigma^2 \end{split}$$

Thus, a small  $MSE(x_*^T\hat{\beta})$  is better for prediction, even when  $Bias(x_*^T\hat{\beta}) > 0$ .

So, smaller number of predictors (shrinking) might be advised over a more detailed model. Also, a method other than OLS with smaller MSE, is more advisable for prediction.

How is it related to the expected prediction error (EPE) for  $Y_* = f(x_*) + \epsilon_*$ ?

$$EPE = E(Y_* - \hat{f}(x_*))^2 = E(\hat{f}(x_*) - f(x_*))^2 + \sigma^2 = MSE(\hat{f}(x_*)) + \sigma^2 = MSE(x_*^T \hat{\beta}) + \sigma^2$$

Thus, a small  $MSE(x_*^T\hat{\beta})$  is better for prediction, even when  $Bias(x_*^T\hat{\beta}) > 0$ .

So, smaller number of predictors (shrinking) might be advised over a more detailed model. Also, a method other than OLS with smaller MSE, is more advisable for prediction.

◆□▶ ◆□▶ ◆□▶ ◆□▶ ● ● ● ●

- Part of model selection.
- Objective: select one of the 2<sup>p</sup> possible subsets of variables/models (including the null regression).
- Methods:
  - 1. Best Subset method: search for the smallest RSS among all of the 2<sup>*p*</sup> models. Note:  $RSS(\hat{\beta}_{tull}) < RSS(\hat{\beta}_{subset})$ .

- Part of model selection.
- Objective: select one of the 2<sup>p</sup> possible subsets of variables/models (including the null regression).
- Methods:
  - 1. Best Subset method: search for the smallest RSS among all of the 2<sup>*p*</sup> models. Note:  $RSS(\hat{\beta}_{full}) < RSS(\hat{\beta}_{subset})$ .



- Part of model selection.
- Objective: select one of the 2<sup>p</sup> possible subsets of variables/models (including the null regression).
- Methods:
  - 1. Best Subset method: search for the smallest RSS among all of the  $2^{p}$  models. Note:  $RSS(\hat{\beta}_{full}) < RSS(\hat{\beta}_{subset})$ .



- Part of model selection.
- Objective: select one of the 2<sup>p</sup> possible subsets of variables/models (including the null regression).
- Methods:
  - 1. Best Subset method: search for the smallest RSS among all of the  $2^{p}$  models. Note:  $RSS(\hat{\beta}_{full}) < RSS(\hat{\beta}_{subset})$ .



- Part of model selection.
- Objective: select one of the 2<sup>p</sup> possible subsets of variables/models (including the null regression).
- Methods:
  - 1. Best Subset method: search for the smallest RSS among all of the  $2^{p}$  models. Note:  $RSS(\hat{\beta}_{full}) < RSS(\hat{\beta}_{subset})$ .



- Part of model selection.
- Objective: select one of the 2<sup>p</sup> possible subsets of variables/models (including the null regression).
- Methods:
  - 1. Best Subset method: search for the smallest RSS among all of the  $2^{p}$  models. Note:  $RSS(\hat{\beta}_{full}) < RSS(\hat{\beta}_{subset})$ .



2. Leaps and bounds (good for  $p \le 40$ , minimizes RSS). Also, Branch and Bounds.

#### 2. Leaps and bounds (good for $p \le 40$ , minimizes RSS). Also, Branch and Bounds.

TECHNOMETRICS©, VOL. 16, NO. 4, NOVEMBER 1974

▲□▶ ▲□▶ ▲□▶ ▲□▶ □ のQで

#### Regressions by Leaps and Bounds

George M. Furnival	and	Robert W. Wilson, Jr.
School of Forestry, Yale University		USDA Forest Service
New Haven, Connecticut		Northeastern Forest Experiment
		Station

This paper describes several algorithms for computing the residual sums of squares for all possible regressions with what appears to be a minimum of arithmetic (less than six floating-point operations per regression) and shows how two of these algorithms can be combined to form a simple leap and bound technique for finding the best subsets without examining all possible subsets. The result is a reduction of several orders of magnitude in the number of operations required to find the best subsets.

2. Leaps and bounds (good for  $p \le 40$ , minimizes RSS). Also, Branch and Bounds.



FIGURE 1-The regression tree

2. Leaps and bounds (good for  $p \le 40$ , minimizes RSS). Also, Branch and Bounds.



FIGURE 2-The bound tree

#### TECHNOMETRICS©, VOL. 16, NO. 4, NOVEMBER 1974

#### 3. Stepwise (Forward or Backward) Selection (when p > 40).

- Forward-stepwise selection (is a greedy algorithm): start with a null model (just the intercept  $\hat{\beta}_0 = \bar{y}$ ) and then sequentially adds predictors that improves the fit. Models on the steps forward are nested. Good at all cases.
- Backward-stepwise selection: start with a full model (all the predictors) and then sequentially removes predictors that do not alter the fit (smallest t- or z- score). Use only when N > p.

・ロト ・ 同 ・ ・ ヨ ・ ・ ヨ ・ うへつ

- 3. Stepwise (Forward or Backward) Selection (when p > 40).
  - Forward-stepwise selection (is a greedy algorithm): start with a null model (just the intercept  $\hat{\beta}_0 = \bar{y}$ ) and then sequentially adds predictors that improves the fit. Models on the steps forward are nested. Good at all cases.
  - Backward-stepwise selection: start with a full model (all the predictors) and then sequentially removes predictors that do not alter the fit (smallest t- or z- score). Use only when N > p.

・ロト ・ 同 ・ ・ ヨ ・ ・ ヨ ・ うへつ
- 3. Stepwise (Forward or Backward) Selection (when p > 40).
  - Forward-stepwise selection (is a greedy algorithm): start with a null model (just the intercept  $\hat{\beta}_0 = \bar{y}$ ) and then sequentially adds predictors that improves the fit. Models on the steps forward are nested. Good at all cases.
  - Backward-stepwise selection: start with a full model (all the predictors) and then sequentially removes predictors that do not alter the fit (smallest t- or z- score). Use only when N > p.

#### 4. Forward-Stagewise Regression:

Stage 0: Start with  $\hat{\beta}_{0,0} = \bar{y}$  and  $\hat{\beta}_{j,0} = 0$  for j = 1, 2, ..., p. Stage *k*: Find the most correlated variable, say  $X_j$ , with the residuals of the model in Stage k - 1 and find the slope  $(b_j)$  of the simple linear regression between the residuals and that variable  $X_j$ .

$$\hat{\beta}_{j,k} = \hat{\beta}_{j,k-1} + b_j$$

(日) (日) (日) (日) (日) (日) (日)

Until: there is no correlation between the residuals and any variable.

#### 4. Forward-Stagewise Regression:

#### Stage 0: Start with $\hat{\beta}_{0,0} = \bar{y}$ and $\hat{\beta}_{j,0} = 0$ for $j = 1, 2, \dots, p$ .

Stage *k*: Find the most correlated variable, say  $X_j$ , with the residuals of the model in Stage k - 1 and find the slope  $(b_j)$  of the simple linear regression between the residuals and that variable  $X_j$ .

$$\hat{\beta}_{j,k} = \hat{\beta}_{j,k-1} + b_j$$

(日) (日) (日) (日) (日) (日) (日)

Until: there is no correlation between the residuals and any variable.

#### 4. Forward-Stagewise Regression:

Stage 0: Start with  $\hat{\beta}_{0,0} = \bar{y}$  and  $\hat{\beta}_{j,0} = 0$  for j = 1, 2, ..., p. Stage *k*: Find the most correlated variable, say  $X_j$ , with the residuals of the model in Stage k - 1 and find the slope  $(b_j)$  of the simple linear regression between the residuals and that variable  $X_j$ .

$$\hat{\beta}_{j,k} = \hat{\beta}_{j,k-1} + \boldsymbol{b}_j$$

Until: there is no correlation between the residuals and any variable.

#### 4. Forward-Stagewise Regression:

Stage 0: Start with  $\hat{\beta}_{0,0} = \bar{y}$  and  $\hat{\beta}_{j,0} = 0$  for j = 1, 2, ..., p. Stage *k*: Find the most correlated variable, say  $X_j$ , with the residuals of the model in Stage k - 1 and find the slope  $(b_j)$  of the simple linear regression between the residuals and that variable  $X_j$ .

$$\hat{\beta}_{j,k} = \hat{\beta}_{j,k-1} + b_j$$

Until: there is no correlation between the residuals and any variable.

#### 4. Forward-Stagewise Regression:

Stage 0: Start with  $\hat{\beta}_{0,0} = \bar{y}$  and  $\hat{\beta}_{j,0} = 0$  for j = 1, 2, ..., p. Stage *k*: Find the most correlated variable, say  $X_j$ , with the residuals of the model in Stage k - 1 and find the slope  $(b_j)$  of the simple linear regression between the residuals and that

variable  $X_j$ .

$$\hat{\beta}_{j,k} = \hat{\beta}_{j,k-1} + b_j$$

Until: there is no correlation between the residuals and any variable.

#### 4. Forward-Stagewise Regression:

Stage 0: Start with  $\hat{\beta}_{0,0} = \bar{y}$  and  $\hat{\beta}_{j,0} = 0$  for j = 1, 2, ..., p. Stage *k*: Find the most correlated variable, say  $X_j$ , with the residuals of the model in Stage k - 1 and find the slope  $(b_j)$  of the simple linear regression between the residuals and that

variable  $X_j$ .

$$\hat{\beta}_{j,k} = \hat{\beta}_{j,k-1} + b_j$$

Until: there is no correlation between the residuals and any variable.

#### 4. Forward-Stagewise Regression:

Stage 0: Start with  $\hat{\beta}_{0,0} = \bar{y}$  and  $\hat{\beta}_{j,0} = 0$  for j = 1, 2, ..., p.

Stage *k*: Find the most correlated variable, say  $X_j$ , with the residuals of the model in Stage k - 1 and find the slope  $(b_j)$  of the simple linear regression between the residuals and that variable  $X_j$ .

$$\hat{\beta}_{j,k} = \hat{\beta}_{j,k-1} + b_j$$

- Until: there is no correlation between the residuals and any variable.
  - $\Downarrow$  Slow and might need more than *p* stages till converge.
  - $\Uparrow$  Good for high dimensional problems.

In a simulation study, with N = 300 and p = 31.



◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 三臣 - 釣��

#### Measures of selection

- 1. Largest  $R^2$  or  $R^2_{adj}$ .
- 2. Smallest RSS.
- 3. Smallest *CV* or *GCV*.
- 4. Smallest Mallow's  $C_p$ :

$$C_p = \frac{RSS_{subset of k}}{RSS(\hat{\beta}_{full})/(N-p-1)} - (N-2k)$$

▲□▶ ▲□▶ ▲三▶ ▲三▶ - 三 - のへで

Measures of selection

- 1. Largest  $R^2$  or  $R^2_{adi}$ .
- 2. Smallest RSS.
- 3. Smallest *CV* or *GCV*.

4. Smallest Mallow's  $C_p$ :

$$C_{p} = \frac{RSS_{subset of k}}{RSS(\hat{\beta}_{full})/(N-p-1)} - (N-2k)$$

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ - 三 - のへぐ

Measures of selection

- 1. Largest  $R^2$  or  $R^2_{adi}$ .
- 2. Smallest RSS.
- 3. Smallest CV or GCV.

4. Smallest Mallow's Cp:

$$C_{p} = \frac{RSS_{subset of k}}{RSS(\hat{\beta}_{full})/(N-p-1)} - (N-2k)$$

◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ ののの

Measures of selection

- 1. Largest  $R^2$  or  $R^2_{adi}$ .
- 2. Smallest RSS.
- 3. Smallest CV or GCV.
- 4. Smallest Mallow's C<sub>p</sub>:

$$C_{p} = \frac{RSS_{subset of k}}{RSS(\hat{\beta}_{full})/(N-p-1)} - (N-2k)$$

◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ ののの

More measures of selection: (For general classes of models.) Let *L* be the likelihood function.  $\hat{\beta}_{MLE,k}$  is the maximum likelihood estimator of size *k*.

1. Smallest

deviance = 
$$-2 \log L(\hat{\beta}_{MLE,k})$$

2. Smallest Akaike's Information Criterion

$$AIC_k = -2 \log L(\hat{\beta}_{MLE,k}) + 2k$$

3. Smallest Bayes' Information Criterion

$$BIC_k = -2 \log L(\hat{\beta}_{MLE,k}) + 2k \log(N)$$

More measures of selection: (For general classes of models.) Let *L* be the likelihood function.  $\hat{\beta}_{MLE,k}$  is the maximum likelihood estimator of size *k*.

1. Smallest

$$deviance = -2 \log L(\hat{\beta}_{MLE,k})$$

2. Smallest Akaike's Information Criterion

$$AIC_k = -2 \log L(\hat{\beta}_{MLE,k}) + 2k$$

3. Smallest Bayes' Information Criterion

$$BIC_k = -2 \log L(\hat{\beta}_{MLE,k}) + 2k \log(N)$$

(日) (日) (日) (日) (日) (日) (日)

More measures of selection: (For general classes of models.) Let *L* be the likelihood function.  $\hat{\beta}_{MLE,k}$  is the maximum likelihood estimator of size *k*.

1. Smallest

$$deviance = -2 \log L(\hat{\beta}_{MLE,k})$$

2. Smallest Akaike's Information Criterion

$$AIC_k = -2 \log L(\hat{\beta}_{MLE,k}) + 2k$$

3. Smallest Bayes' Information Criterion

$$BIC_k = -2 \log L(\hat{\beta}_{MLE,k}) + 2k \log(N)$$

< □ > < 同 > < 三 > < 三 > < 三 > < ○ < ○ </p>

Subset (Variable) Selection Example (Prostate Cancer)

All Subsets



# Shrinkage (regularization,constraints)

◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ ののの

- It includes subset selection. But, it is continuous selection rather than discrete.
- Objective: To include all of the *p* inputs but shrinking their coefficients towards zero. If some of them become zero, then it results in a subset. (Note: Intercept is not included in that objective.)

◆□▶ ◆□▶ ▲□▶ ▲□▶ □ のQ@

It reduces variance of the estimates.

- It includes subset selection. But, it is continuous selection rather than discrete.
- Objective: To include all of the p inputs but shrinking their coefficients towards zero. If some of them become zero, then it results in a subset. (Note: Intercept is not included in that objective.)

(日) (日) (日) (日) (日) (日) (日)

It reduces variance of the estimates.

- It includes subset selection. But, it is continuous selection rather than discrete.
- Objective: To include all of the p inputs but shrinking their coefficients towards zero. If some of them become zero, then it results in a subset. (Note: Intercept is not included in that objective.)

(日) (日) (日) (日) (日) (日) (日)

It reduces variance of the estimates.

To find  $\hat{\beta}^{\text{shrunk}}$  that

$$\begin{split} \text{minimize}_{\beta} \ RSS(\beta) &= \sum_{i=1}^{N} [y_i - (\beta_0 + \beta_1 x_{i1} + \dots + \beta_p x_{i,p})]^2 \\ \text{subject to} \ \sum_{j=1}^{p} G(\beta_j) \leq t \text{ (size constraint)} \end{split}$$

**OR**  $\hat{\beta}^{\text{shrunk}} =$ 

$$\operatorname{argmin}_{\beta}\left[\sum_{i=1}^{N}[y_{i}-(\beta_{0}+\beta_{1}x_{i1}+\cdots+\beta_{p}x_{i,p})]^{2}+\lambda\sum_{j=1}^{p}G(\beta_{j})\right]$$

for some positive function G. The term  $\lambda \sum_{j=1}^{p} G(\beta_j)$  is called shrinkage penalty.

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● のへぐ

To find  $\hat{\beta}^{\text{shrunk}}$  that

minimize<sub>$$\beta$$</sub>  $RSS(\beta) = \sum_{i=1}^{N} [y_i - (\beta_0 + \beta_1 x_{i1} + \dots + \beta_p x_{i,p})]^2$ 

subject to 
$$\sum_{j=1}^{\mu} G(\beta_j) \leq t$$
 (size constraint)

 ${\sf OR}\; \hat{\beta}^{\sf shrunk} =$ 

$$\operatorname{argmin}_{\beta}\left[\sum_{i=1}^{N}[y_{i}-(\beta_{0}+\beta_{1}x_{i1}+\cdots+\beta_{p}x_{i,p})]^{2}+\lambda\sum_{j=1}^{p}G(\beta_{j})\right]$$

for some positive function *G*. The term  $\lambda \sum_{j=1}^{p} G(\beta_j)$  is called shrinkage penalty.

#### Some methods:

1. Ridge regression,  $G(x) = x^2$ . (An  $L_2$  shrinkage method.)

2. Least absolute shrinkage and selection operator (lasso), G(x) = |x|. (An  $L_1$  shrinkage method.)

#### 3. Bridge shrinkage,

$$G(x) = \begin{cases} |x|^q & \text{if } q > 0, \\ I(x \neq 0) & \text{if } q = 0. \end{cases}$$

(An L<sub>q</sub> shrinkage method.) It includes both ridge and lasso

< □ > < 同 > < 三 > < 三 > < 三 > < ○ < ○ </p>

#### Some methods:

1. Ridge regression,  $G(x) = x^2$ . (An  $L_2$  shrinkage method.)

2. Least absolute shrinkage and selection operator (lasso), G(x) = |x|. (An  $L_1$  shrinkage method.)

#### 3. Bridge shrinkage,

$$G(x) = \begin{cases} |x|^q & \text{if } q > 0, \\ l(x \neq 0) & \text{if } q = 0. \end{cases}$$

(An L<sub>q</sub> shrinkage method.) It includes both ridge and lasso

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ - 三 - のへぐ

#### Some methods:

1. Ridge regression,  $G(x) = x^2$ . (An  $L_2$  shrinkage method.)

2. Least absolute shrinkage and selection operator (lasso), G(x) = |x|. (An  $L_1$  shrinkage method.)

#### 3. Bridge shrinkage,

$$G(x) = \begin{cases} |x|^q & \text{if } q > 0, \\ l(x \neq 0) & \text{if } q = 0. \end{cases}$$

(An  $L_q$  shrinkage method.) It includes both ridge and lasso.

#### Example (Prostate Cancer)



#### Example (Prostate Cancer)

#### Estimated coefficients are

Term	LS	Best Subset	Ridge	Lasso
Intercept	2.465	2.477	2.452	2.468
lcavol	0.680	0.740	0.420	0.533
lweight	0.263	0.316	0.238	0.169
age	-0.141		-0.046	
lbph	0.210		0.162	0.002
svi	0.305		0.227	0.094
lcp	-0.288		0.000	
gleason	-0.021		0.040	
pgg45	0.267		0.133	
Test Error	0.521	0.492	0.492	0.479
Std Error	0.179	0.143	0.165	0.164

▲□▶ ▲圖▶ ▲臣▶ ▲臣▶ ―臣 … のへで

To find  $\hat{\beta}^{\rm ridge}$  that

minimize<sub>$$\beta$$</sub>  $RSS(\beta) = \sum_{i=1}^{N} [y_i - (\beta_0 + \beta_1 x_{i1} + \dots + \beta_p x_{i,p})]^2$   
subject to  $\sum_{j=1}^{p} \beta_j^2 \le t$  (size constraint)

OR in the Lagrangian form

$$\hat{\beta}^{\text{ridge}} = \operatorname{argmin}_{\beta} \left[ \sum_{i=1}^{N} [y_i - (\beta_0 + \beta_1 x_{i1} + \dots + \beta_p x_{i,p})]^2 + \lambda \sum_{j=1}^{p} \beta_j^2 \right]$$

▲□▶▲圖▶▲≣▶▲≣▶ ≣ のQ@

To find  $\hat{\beta}^{\text{ridge}}$  that

minimize<sub>$$\beta$$</sub> *RSS*( $\beta$ ) =  $\sum_{i=1}^{N} [y_i - (\beta_0 + \beta_1 x_{i1} + \dots + \beta_p x_{i,p})]^2$ 

subject to 
$$\sum_{j=1}^{p} \beta_j^2 \leq t$$
 (size constraint)

OR in the Lagrangian form

$$\hat{\beta}^{\mathsf{ridge}} = \operatorname{argmin}_{\beta} \left[ \sum_{i=1}^{N} [y_i - (\beta_0 + \beta_1 x_{i1} + \dots + \beta_p x_{i,p})]^2 + \lambda \sum_{j=1}^{p} \beta_j^2 \right]$$

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 のへで

► The decay/tuning parameter \u03c0 ≥ 0 is determined first through CV then the parameters are estimated.

(ロ) (同) (三) (三) (三) (○) (○)

• What does happen when  $\lambda$  increase?

Better, start with standardized data:

$$\sum_{i=1}^{N} x_{ij} = 0, \sum_{i=1}^{N} x_{ij}^2 = 1$$

which results in removing  $\hat{\beta}_0$  from the optimization problem as its value would be  $\bar{y}$ . We are now left with a  $p \times p$  matrix *X*.

The problem is now equivalent to find  $\hat{\beta}^{\text{ridge}}$  that

minimize<sub>$$\beta$$</sub>  $RSS(\beta) = (y - X\beta)^T (y - X\beta)$   
subject to  $\beta^T \beta \le t$ 

$$\hat{\beta}^{\mathsf{ridge}} = argmin_{\beta} \left[ (y - X\beta)^{\mathsf{T}} (y - X\beta) + \lambda \beta^{\mathsf{T}} \beta \right]$$

Call:

$$RSS_{\lambda}(\beta) := (y - X\beta)^{T}(y - X\beta) + \lambda\beta^{T}\beta$$

▲□▶▲圖▶▲≣▶▲≣▶ ▲■ のへ⊙

The problem is now equivalent to find  $\hat{\beta}^{\text{ridge}}$  that

minimize<sub>$$\beta$$</sub>  $RSS(\beta) = (y - X\beta)^T (y - X\beta)$   
subject to  $\beta^T \beta \le t$ 

$$\hat{eta}^{\mathsf{ridge}} = \textit{argmin}_{eta} \left[ (\mathbf{y} - \mathbf{X}eta)^{\mathsf{T}} (\mathbf{y} - \mathbf{X}eta) + \lambda eta^{\mathsf{T}}eta 
ight]^{\mathsf{T}}$$

Call

$$RSS_{\lambda}(\beta) := (y - X\beta)^{T}(y - X\beta) + \lambda\beta^{T}\beta$$

▲□▶▲圖▶▲≣▶▲≣▶ ▲■ のへ⊙

The problem is now equivalent to find  $\hat{\beta}^{\text{ridge}}$  that

minimize<sub>$$\beta$$</sub>  $RSS(\beta) = (y - X\beta)^T (y - X\beta)$   
subject to  $\beta^T \beta \le t$ 

$$\hat{eta}^{\mathsf{ridge}} = \textit{argmin}_{eta} \left[ (m{y} - m{X}eta)^{\mathsf{T}} (m{y} - m{X}eta) + \lambdaeta^{\mathsf{T}}eta 
ight]$$

Call:

$$RSS_{\lambda}(\beta) := (y - X\beta)^{T}(y - X\beta) + \lambda\beta^{T}\beta$$

▲□▶▲圖▶▲≣▶▲≣▶ ▲■ のへ⊙
$$(X^T X + \lambda I_p)\beta = X^T y$$

 $\blacktriangleright \frac{\partial^2 RSS_{\lambda}(\beta)}{\partial \beta \partial \beta^T} = 2X^T X + 2\lambda I_{\rho}$ 

Even when X is not a full column rank, X<sup>T</sup>X + λI<sub>p</sub> is positive definite for λ > 0 and so non-singular, then

$$\hat{\beta}_{\lambda}^{\mathsf{ridge}} = (X^T X + \lambda I_p)^{-1} X^T y$$

Predictions

$$\hat{y}_{\lambda} = X \hat{\beta}_{\lambda}^{\text{ridge}} = \underbrace{X (X^T X + \lambda I_p)^{-1} X^T}_{} y$$

< □ > < 同 > < 三 > < 三 > < 三 > < ○ < ○ </p>

the  $\lambda$ -hat matrix  $H_{\lambda}$ 

$$(X^T X + \lambda I_p)\beta = X^T y$$

$$\blacktriangleright \frac{\partial^2 RSS_{\lambda}(\beta)}{\partial \beta \partial \beta^T} = 2X^T X + 2\lambda I_{\rho}$$

Even when X is not a full column rank, X<sup>T</sup>X + λI<sub>p</sub> is positive definite for λ > 0 and so non-singular, then

$$\hat{\beta}_{\lambda}^{\mathsf{ridge}} = (X^T X + \lambda I_p)^{-1} X^T y$$

Predictions

$$\hat{y}_{\lambda} = X \hat{\beta}_{\lambda}^{\text{ridge}} = \underbrace{X (X^T X + \lambda I_p)^{-1} X^T}_{} y$$

< □ > < 同 > < 三 > < 三 > < 三 > < ○ < ○ </p>

the  $\lambda$ -hat matrix  $H_{\lambda}$ 

$$(X^T X + \lambda I_p)\beta = X^T y$$

$$\blacktriangleright \frac{\partial^2 RSS_{\lambda}(\beta)}{\partial \beta \partial \beta^T} = 2X^T X + 2\lambda I_p$$

Even when X is not a full column rank, X<sup>T</sup>X + λI<sub>p</sub> is positive definite for λ > 0 and so non-singular, then

$$\hat{\beta}_{\lambda}^{\mathsf{ridge}} = (X^T X + \lambda I_p)^{-1} X^T y$$

Predictions

$$\hat{y}_{\lambda} = X \hat{\beta}_{\lambda}^{\text{ridge}} = \underbrace{X (X^T X + \lambda I_p)^{-1} X^T}_{} y$$

the  $\lambda$ -hat matrix  $H_{\lambda}$ 

< □ > < 同 > < 三 > < 三 > < 三 > < ○ < ○ </p>

$$(X^T X + \lambda I_p)\beta = X^T y$$

$$\blacktriangleright \frac{\partial^2 RSS_{\lambda}(\beta)}{\partial \beta \partial \beta^T} = 2X^T X + 2\lambda I_p$$

Even when X is not a full column rank, X<sup>T</sup>X + λI<sub>p</sub> is positive definite for λ > 0 and so non-singular, then

$$\hat{\beta}_{\lambda}^{\mathsf{ridge}} = (X^T X + \lambda I_p)^{-1} X^T y$$

Predictions

$$\hat{y}_{\lambda} = X \hat{\beta}_{\lambda}^{\text{ridge}} = \underbrace{X (X^T X + \lambda I_p)^{-1} X^T}_{} y$$

the  $\lambda$ -hat matrix  $H_{\lambda}$ 

$$\hat{\beta}_{\lambda}^{\mathsf{ridge}} = (X^T X + \lambda I_p)^{-1} X^T y$$

- What does happen when λ decreases to zero?
- lf columns of X are orthonormal ( $X^T X = I$ ), then

$$\hat{eta}_{\lambda}^{\mathsf{ridge}} = rac{1}{1+\lambda}\hat{eta}^{\mathit{ols}}$$

- ▶ In general,  $\hat{\beta}_{\lambda}^{\text{ridge}}$  is a biased estimator of  $\beta$ . (Good problem to prove it, hint: E(Az) = AE(z).)
- ▶ Yet, it has smaller variance than that of the OLS's. (Another good problem, hint:  $Var(Az) = A Var(z) A^{T}$ .)

$$\hat{\beta}_{\lambda}^{\mathsf{ridge}} = (X^T X + \lambda I_p)^{-1} X^T y$$

- What does happen when  $\lambda$  decreases to zero?
- If columns of X are orthonormal  $(X^T X = I)$ , then

$$\hat{eta}_{\lambda}^{\mathsf{ridge}} = rac{1}{1+\lambda}\hat{eta}^{\mathit{ols}}$$

- ▶ In general,  $\hat{\beta}_{\lambda}^{\text{ridge}}$  is a biased estimator of  $\beta$ . (Good problem to prove it, hint: E(Az) = AE(z).)
- ▶ Yet, it has smaller variance than that of the OLS's. (Another good problem, hint:  $Var(Az) = A Var(z) A^{T}$ .)

$$\hat{\beta}_{\lambda}^{\mathsf{ridge}} = (X^T X + \lambda I_p)^{-1} X^T y$$

- What does happen when λ decreases to zero?
- If columns of X are orthonormal  $(X^T X = I)$ , then

$$\hat{eta}_{\lambda}^{\mathsf{ridge}} = rac{1}{1+\lambda} \hat{eta}^{\mathit{ols}}$$

- ▶ In general,  $\hat{\beta}_{\lambda}^{\text{ridge}}$  is a biased estimator of  $\beta$ . (Good problem to prove it, hint: E(Az) = AE(z).)
- Yet, it has smaller variance than that of the OLS's. (Another good problem, hint: Var(Az) = A Var(z) A<sup>T</sup>.)

$$\hat{\beta}_{\lambda}^{\text{ridge}} = (X^T X + \lambda I_p)^{-1} X^T y$$

- What does happen when λ decreases to zero?
- If columns of X are orthonormal  $(X^T X = I)$ , then

$$\hat{eta}_{\lambda}^{\mathsf{ridge}} = rac{1}{1+\lambda}\hat{eta}^{\mathit{ols}}$$

- ▶ In general,  $\hat{\beta}_{\lambda}^{\text{ridge}}$  is a biased estimator of  $\beta$ . (Good problem to prove it, hint: E(Az) = AE(z).)
- > Yet, it has smaller variance than that of the OLS's. (Another good problem, hint:  $Var(Az) = A Var(z) A^{T}$ .)

It handles very well the case of collinearity, as

Originally, When a coefficient of a variable becomes large, coefficient of any correlated variables balance up with a very small and negative value. But placing a bound resolves that issue.

< □ > < 同 > < 三 > < 三 > < 三 > < ○ < ○ </p>

▶ It fixes the problem that *X* is not column full-rank.

It handles very well the case of collinearity, as

Originally, When a coefficient of a variable becomes large, coefficient of any correlated variables balance up with a very small and negative value. But placing a bound resolves that issue.

< □ > < 同 > < 三 > < 三 > < 三 > < ○ < ○ </p>

It fixes the problem that X is not column full-rank.

Using singular values decomposition (SVD):

$$X = UDV^T$$

Where *U* and *V* are two orthogonal matrices,  $U^T U = I_p$  and  $V^T V = I_p$ . The columns  $u_j$  and  $v_j$  of the  $N \times p$  matrix *U* and the  $p \times p$  matrix *V* are spanning the columns and rows of *X*, respectively. *D* is a  $p \times p$  diagonal matrix of singular values  $d_1 \ge \ldots \ge d_p \ge 0$  (some might be possible 0). Then ...

(日) (日) (日) (日) (日) (日) (日)

Using singular values decomposition (SVD):

$$X = UDV^T$$

Where *U* and *V* are two orthogonal matrices,  $U^T U = I_p$  and  $V^T V = I_p$ . The columns  $u_j$  and  $v_j$  of the  $N \times p$  matrix *U* and the  $p \times p$  matrix *V* are spanning the columns and rows of *X*, respectively. *D* is a  $p \times p$  diagonal matrix of singular values  $d_1 \ge \ldots \ge d_p \ge 0$  (some might be possible 0). Then ...

(日) (日) (日) (日) (日) (日) (日)

#### Then ...

$$\hat{\beta}_{\lambda}^{\mathsf{ridge}} = (X^T X + \lambda I_p)^{-1} X^T y$$
  
=  $((UDV^T)^T (UDV^T) + \lambda I_p)^{-1} (UDV^T)^T y$   
=  $(VD^2 V^T + \lambda VV^T)^{-1} VDU^T y$   
=  $V \Delta_{\lambda} U^T y$ 

where  $\Delta_{\lambda}$  is a diagonal matrix with elements  $d_j/(d_j^2 + \lambda)$ , for j = 1, ..., p.

#### Then ...

$$\hat{\beta}_{\lambda}^{\mathsf{ridge}} = (X^T X + \lambda I_p)^{-1} X^T y$$
  
=  $((UDV^T)^T (UDV^T) + \lambda I_p)^{-1} (UDV^T)^T y$   
=  $(VD^2 V^T + \lambda VV^T)^{-1} VDU^T y$   
=  $V \Delta_{\lambda} U^T y$ 

where  $\Delta_{\lambda}$  is a diagonal matrix with elements  $d_j/(d_j^2 + \lambda)$ , for j = 1, ..., p.

#### Then ...

$$\hat{\beta}_{\lambda}^{\mathsf{ridge}} = (X^T X + \lambda I_p)^{-1} X^T y$$
  
=  $((UDV^T)^T (UDV^T) + \lambda I_p)^{-1} (UDV^T)^T y$   
=  $(VD^2 V^T + \lambda VV^T)^{-1} VDU^T y$   
=  $V \Delta_{\lambda} U^T y$ 

where  $\Delta_{\lambda}$  is a diagonal matrix with elements  $d_j/(d_j^2 + \lambda)$ , for j = 1, ..., p.

#### Then ...

$$\begin{split} \hat{\beta}_{\lambda}^{\mathsf{ridge}} &= (X^T X + \lambda I_{\rho})^{-1} X^T y \\ &= ((U D V^T)^T (U D V^T) + \lambda I_{\rho})^{-1} (U D V^T)^T y \\ &= (V D^2 V^T + \lambda V V^T)^{-1} V D U^T y \\ &= V \Delta_{\lambda} U^T y \end{split}$$

where  $\Delta_{\lambda}$  is a diagonal matrix with elements  $d_j/(d_j^2 + \lambda)$ , for j = 1, ..., p.

#### Then ...

$$\begin{split} \hat{\beta}_{\lambda}^{\mathsf{ridge}} &= (X^T X + \lambda I_p)^{-1} X^T y \\ &= ((UDV^T)^T (UDV^T) + \lambda I_p)^{-1} (UDV^T)^T y \\ &= (VD^2 V^T + \lambda VV^T)^{-1} VDU^T y \\ &= V \Delta_{\lambda} U^T y \end{split}$$

where  $\Delta_{\lambda}$  is a diagonal matrix with elements  $d_j/(d_j^2 + \lambda)$ , for j = 1, ..., p.

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ - 三 - のへぐ

Thus, the prediction is

$$\begin{aligned} \hat{y}_{\lambda} &= X \hat{\beta}_{\lambda}^{\mathsf{ridge}} = \mathcal{H}_{\lambda} y \\ &= X (X^T X + \lambda I_p)^{-1} X^T y \\ &= (U D V^T) V \Delta_{\lambda} U^T y \\ &= U D \Delta_{\lambda} U^T y \\ &= \sum_{j=1}^{p} u_j \frac{d_j^2}{d_j^2 + \lambda} u_j^T y \end{aligned}$$

Note that,  $\hat{y}_0 = UU^T y = \sum_{j=1}^p u_j u_j^T y$  is the OLS prediction.

Thus, the prediction is

$$\begin{aligned} \hat{y}_{\lambda} &= X \hat{\beta}_{\lambda}^{\mathsf{ridge}} = H_{\lambda} y \\ &= X (X^T X + \lambda I_p)^{-1} X^T y \\ &= (U D V^T) V \Delta_{\lambda} U^T y \\ &= U D \Delta_{\lambda} U^T y \\ &= \sum_{j=1}^p u_j \frac{d_j^2}{d_j^2 + \lambda} u_j^T y \end{aligned}$$

Note that,  $\hat{y}_0 = UU^T y = \sum_{j=1}^p u_j u_j^T y$  is the OLS prediction.

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ - 三 - のへぐ

Thus, the prediction is

$$\begin{split} \hat{y}_{\lambda} &= X \hat{\beta}_{\lambda}^{\mathsf{ridge}} = \mathcal{H}_{\lambda} \mathbf{y} \\ &= X (X^T X + \lambda I_p)^{-1} X^T \mathbf{y} \\ &= (U D V^T) V \Delta_{\lambda} U^T \mathbf{y} \\ &= U D \Delta_{\lambda} U^T \mathbf{y} \\ &= \sum_{j=1}^p u_j \frac{d_j^2}{d_j^2 + \lambda} u_j^T \mathbf{y} \end{split}$$

Note that,  $\hat{y}_0 = UU^T y = \sum_{j=1}^p u_j u_j^T y$  is the OLS prediction.

Thus, the prediction is

$$\begin{split} \hat{y}_{\lambda} &= X \hat{\beta}_{\lambda}^{\mathsf{ridge}} = \mathcal{H}_{\lambda} \mathbf{y} \\ &= X (X^T X + \lambda I_p)^{-1} X^T \mathbf{y} \\ &= (U D V^T) V \Delta_{\lambda} U^T \mathbf{y} \\ &= U D \Delta_{\lambda} U^T \mathbf{y} \\ &= \sum_{j=1}^p u_j \frac{d_j^2}{d_j^2 + \lambda} u_j^T \mathbf{y} \end{split}$$

Note that,  $\hat{y}_0 = UU^T y = \sum_{j=1}^p u_j u_j^T y$  is the OLS prediction.

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ - 三 - のへぐ

Consider centered data  $\bar{x}_j = 0$  for all j

The sample covariance matrix

$$S = X^T X / N = V D^2 V^T / N$$

(eigen decomposition with  $V^T S V = D^2/N$ )

- With  $d_1^2/N \ge d_2^2/N \ge \cdots \ge d_p^2/N$
- The eigen-vectors v<sub>j</sub>'s are called the principal components (Karhunen-Loeve) directions of X.
- Xv<sub>1</sub> is the (first) largest principal component since v<sub>1</sub><sup>T</sup>X<sup>T</sup>Xv<sub>1</sub> = d<sub>1</sub><sup>2</sup>/N is the largest sample variance among all normalized linear combinations of the columns of X.

e.g. principal components in 2D input data

(日) (日) (日) (日) (日) (日) (日)

Consider centered data  $\bar{x}_j = 0$  for all j

The sample covariance matrix

$$S = X^T X / N = V D^2 V^T / N$$

(eigen decomposition with  $V^T S V = D^2/N$ )

- With  $d_1^2/N \ge d_2^2/N \ge \cdots \ge d_p^2/N$
- The eigen-vectors v<sub>i</sub>'s are called the principal components (Karhunen-Loeve) directions of X.
- Xv<sub>1</sub> is the (first) largest principal component since v<sub>1</sub><sup>T</sup>X<sup>T</sup>Xv<sub>1</sub> = d<sub>1</sub><sup>2</sup>/N is the largest sample variance among all normalized linear combinations of the columns of X.





Consider centered data  $\bar{x}_j = 0$  for all j

The sample covariance matrix

$$S = X^T X / N = V D^2 V^T / N$$

(eigen decomposition with  $V^T S V = D^2/N$ )

• With 
$$d_1^2/N \ge d_2^2/N \ge \cdots \ge d_p^2/N$$

- The eigen-vectors v<sub>i</sub>'s are called the principal components (Karhunen-Loeve) directions of X.
- Xv<sub>1</sub> is the (first) largest principal component since v<sub>1</sub><sup>T</sup>X<sup>T</sup>Xv<sub>1</sub> = d<sub>1</sub><sup>2</sup>/N is the largest sample variance among all normalized linear combinations of the columns of X.





・ コット (雪) ( 小田) ( コット 日)

Consider centered data  $\bar{x}_j = 0$  for all j

The sample covariance matrix

$$S = X^T X / N = V D^2 V^T / N$$

(eigen decomposition with  $V^T S V = D^2/N$ )

• With 
$$d_1^2/N \ge d_2^2/N \ge \cdots \ge d_p^2/N$$

- The eigen-vectors v<sub>i</sub>'s are called the principal components (Karhunen-Loeve) directions of X.
- Xv<sub>1</sub> is the (first) largest principal component since v<sub>1</sub><sup>T</sup> X<sup>T</sup> Xv<sub>1</sub> = d<sub>1</sub><sup>2</sup>/N is the largest sample variance among all normalized linear combinations of the columns of X.





イロト 不良 とくほ とくほう 二日

Thus, with

$$\hat{eta}_{\lambda}^{\mathsf{ridge}} = oldsymbol{V} \Delta_{\lambda} oldsymbol{U}^{\mathsf{T}} oldsymbol{y} = \sum_{j=1}^{p} oldsymbol{v}_{j} rac{oldsymbol{d}_{j}}{oldsymbol{d}_{j}^{2} + \lambda} oldsymbol{u}_{j}^{\mathsf{T}} oldsymbol{y}$$

the prediction

$$\hat{y}_{\lambda} = UD\Delta_{\lambda}U^{T}y = \sum_{j=1}^{p} u_{j} \frac{d_{j}^{2}}{d_{j}^{2} + \lambda}u_{j}^{T}y$$

is made onto the those components and shrinks the coefficients of the low variance components more than those with high variance.

#### Define, the effective degrees of freedom to be

$$df(\lambda) = tr(H_{\lambda}) = tr(D\Delta_{\lambda}) = \sum_{j=1}^{p} rac{d_{j}^{2}}{d_{j}^{2} + \lambda} \leq p$$

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● のへぐ

with  $df(\lambda) = p$  at  $\lambda = 0$ .

Define, the effective degrees of freedom to be

$$df(\lambda) = tr(H_{\lambda}) = tr(D\Delta_{\lambda}) = \sum_{j=1}^{p} \frac{d_{j}^{2}}{d_{j}^{2} + \lambda} \leq p$$

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● のへぐ

with  $df(\lambda) = p$  at  $\lambda = 0$ .

Example (Prostate Cancer)

Estimated coefficients for different values of  $df(\lambda)$  with optimal df = 5 using CV.



#### Example (Prostate Cancer)

#### Estimated coefficients are

Term	LS	Best Subset	Ridge	Lasso
Intercept	2.465	2.477	2.452	2.468
lcavol	0.680	0.740	0.420	0.533
lweight	0.263	0.316	0.238	0.169
age	-0.141		-0.046	
lbph	0.210		0.162	0.002
svi	0.305		0.227	0.094
lcp	-0.288		0.000	
gleason	-0.021		0.040	
pgg45	0.267		0.133	
Test Error	0.521	0.492	0.492	0.479
Std Error	0.179	0.143	0.165	0.164

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ ─臣 ─のへで

# Least absolute shrinkage and selection operator (lasso) or basis pursuit

To find  $\hat{\beta}^{\rm lasso}$  that

minimize<sub>$$\beta$$</sub> *RSS*( $\beta$ ) =  $\sum_{i=1}^{N} [y_i - (\beta_0 + \beta_1 x_{i1} + \dots + \beta_p x_{i,p})]^2$   
subject to  $\sum_{j=1}^{p} |\beta_j| \le t$  (size constraint)

OR

$$\hat{\beta}^{\text{lasso}} = \operatorname{argmin}_{\beta} \left[ \sum_{i=1}^{N} [y_i - (\beta_0 + \beta_1 x_{i1} + \dots + \beta_p x_{i,p})]^2 + \lambda \sum_{j=1}^{p} |\beta_j| \right]$$

◆□ > ◆□ > ◆ 三 > ◆ 三 > ● ○ ○ ○ ○

with no closed form.

To find  $\hat{\beta}^{\rm lasso}$  that

minimize<sub>$$\beta$$</sub>  $RSS(\beta) = \sum_{i=1}^{N} [y_i - (\beta_0 + \beta_1 x_{i1} + \dots + \beta_p x_{i,p})]^2$   
subject to  $\sum_{j=1}^{p} |\beta_j| \le t$  (size constraint)

OR

$$\hat{\beta}^{\text{lasso}} = \operatorname{argmin}_{\beta} \left[ \sum_{i=1}^{N} [y_i - (\beta_0 + \beta_1 x_{i1} + \dots + \beta_p x_{i,p})]^2 + \lambda \sum_{j=1}^{p} |\beta_j| \right]$$

with no closed form.

To find  $\hat{\beta}^{\rm lasso}$  that

minimize<sub>$$\beta$$</sub>  $RSS(\beta) = \sum_{i=1}^{N} [y_i - (\beta_0 + \beta_1 x_{i1} + \dots + \beta_p x_{i,p})]^2$   
subject to  $\sum_{j=1}^{p} |\beta_j| \le t$  (size constraint)

OR

$$\hat{\beta}^{\text{lasso}} = \operatorname{argmin}_{\beta} \left[ \sum_{i=1}^{N} [y_i - (\beta_0 + \beta_1 x_{i1} + \dots + \beta_p x_{i,p})]^2 + \lambda \sum_{j=1}^{p} |\beta_j| \right]$$

with no closed form.

Again, the solution is found using quadratic programming algorithms for each fixed  $\lambda$  or using the Least Angel Regression (LARS) (with computational costs comparable to the OLS).

- Standard errors are found computationally using bootstrap methods.
- What does happen when *t* increases beyond  $t_0 = \sum_{j=1}^{p} |\hat{\beta}_j^{ols}|$ ?

Then  $\hat{\beta}^{\text{lasso}} = \hat{\beta}^{ols}$ .

▶ Thus, we use a normalized shrinkage factor  $s = t/t_0$ . It can be determined using CV.

(日) (日) (日) (日) (日) (日) (日)

Again, the solution is found using quadratic programming algorithms for each fixed  $\lambda$  or using the Least Angel Regression (LARS) (with computational costs comparable to the OLS).

- Standard errors are found computationally using bootstrap methods.
- What does happen when *t* increases beyond  $t_0 = \sum_{j=1}^{p} |\hat{\beta}_j^{ols}|$ ?

Then  $\hat{eta}^{\mathsf{lasso}} = \hat{eta}^{\mathsf{ols}}$ .

Thus, we use a normalized shrinkage factor s = t/t<sub>0</sub>. It can be determined using CV.
Again, the solution is found using quadratic programming algorithms for each fixed  $\lambda$  or using the Least Angel Regression (LARS) (with computational costs comparable to the OLS).

- Standard errors are found computationally using bootstrap methods.
- What does happen when *t* increases beyond  $t_0 = \sum_{j=1}^{p} |\hat{\beta}_j^{ols}|$ ?

Then  $\hat{eta}^{\mathsf{lasso}} = \hat{eta}^{\mathsf{ols}}$ .

Thus, we use a normalized shrinkage factor s = t/t<sub>0</sub>. It can be determined using CV.

Again, the solution is found using quadratic programming algorithms for each fixed  $\lambda$  or using the Least Angel Regression (LARS) (with computational costs comparable to the OLS).

- Standard errors are found computationally using bootstrap methods.
- What does happen when *t* increases beyond  $t_0 = \sum_{j=1}^{p} |\hat{\beta}_j^{ols}|$ ?

Then  $\hat{\beta}^{\text{lasso}} = \hat{\beta}^{ols}$ .

► Thus, we use a normalized shrinkage factor  $s = t/t_0$ . It can be determined using CV.

Lasso tends to select more parameters, but it works very well when p > N. It outperforms subset selection and ridge regression in its predictive error.

< □ > < 同 > < 三 > < 三 > < 三 > < ○ < ○ </p>

## ► If columns of X are orthonormal $(X^T X = I)$ , then $\hat{\beta}_{\lambda}^{\text{lasso}} = \text{sign}(\hat{\beta}^{ols})(|\hat{\beta}^{ols}| - \lambda/2)_+$

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ - 三 - のへぐ

It is called soft thresholding.

### Example (Prostate Cancer)

Estimated coefficients for different values of shrinkage factor s with optimal s = .36 using 10-fold CV.



< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □

#### Example (Prostate Cancer)

#### Estimated coefficients are

Term	LS	Best Subset	Ridge	Lasso
Intercept	2.465	2.477	2.452	2.468
lcavol	0.680	0.740	0.420	0.533
lweight	0.263	0.316	0.238	0.169
age	-0.141		-0.046	
lbph	0.210		0.162	0.002
svi	0.305		0.227	0.094
lcp	-0.288		0.000	
gleason	-0.021		0.040	
pgg45	0.267		0.133	
Test Error	0.521	0.492	0.492	0.479
Std Error	0.179	0.143	0.165	0.164

Contours are for the error function around  $\hat{\beta}=\hat{\beta}^{\textit{ols}}$ 



$$\hat{\beta}^{\text{elastic}} = \operatorname{argmin}_{\beta} \left[ \sum_{i=1}^{N} [y_i - (\beta_0 + \beta_1 x_{i1} + \dots + \beta_p x_{i,p})]^2 + \lambda \sum_{j=1}^{p} \left( \alpha |\beta_j| + (1 - \alpha) |\beta_j|^2 \right) \right]$$

Elastic-net selects like a lasso, shrinks like a ridge.

#### Example

For  $\alpha = .8$ , the elastic-net penalty  $\sum_{j=1}^{2} (.8|\beta_j| + .2|\beta_j|^2) \le t$ 

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ - 三 - のへぐ

$$\hat{\beta}^{\text{elastic}} = \operatorname{argmin}_{\beta} \left[ \sum_{i=1}^{N} [y_i - (\beta_0 + \beta_1 x_{i1} + \dots + \beta_p x_{i,p})]^2 + \lambda \sum_{j=1}^{p} \left( \alpha |\beta_j| + (1 - \alpha) |\beta_j|^2 \right) \right]$$

Elastic-net selects like a lasso, shrinks like a ridge.

#### Example

For  $\alpha = .8$ , the elastic-net penalty  $\sum_{i=1}^{2} (.8|\beta_i| + .2|\beta_i|^2) \le t$ 

$$\hat{\beta}^{\text{elastic}} = \operatorname{argmin}_{\beta} \left[ \sum_{i=1}^{N} [y_i - (\beta_0 + \beta_1 x_{i1} + \dots + \beta_p x_{i,p})]^2 + \lambda \sum_{j=1}^{p} \left( \alpha |\beta_j| + (1 - \alpha) |\beta_j|^2 \right) \right]$$

Elastic-net selects like a lasso, shrinks like a ridge.

#### Example

For  $\alpha = .8$ , the elastic-net penalty  $\sum_{j=1}^{2} (.8|\beta_j| + .2|\beta_j|^2) \le t$ 



To find  $\hat{\beta}^{\rm bridge}$  that

minimize<sub>$$\beta$$</sub> *RSS*( $\beta$ ) =  $\sum_{i=1}^{N} [y_i - (\beta_0 + \beta_1 x_{i1} + \dots + \beta_p x_{i,p})]^2$   
subject to  $\sum_{j=1}^{p} |\beta_j|^q \le t$  (size constraint)

OR

$$\hat{\beta}^{\text{bridge}} = \operatorname{argmin}_{\beta} \left[ \sum_{i=1}^{N} [y_i - (\beta_0 + \beta_1 x_{i1} + \dots + \beta_p x_{i,p})]^2 + \lambda \sum_{j=1}^{p} |\beta_j|^q \right]$$

(ロ)、

with no closed form for  $0 < q \leq 1$ .

To find  $\hat{\beta}^{\rm bridge}$  that

minimize<sub>$$\beta$$</sub> *RSS*( $\beta$ ) =  $\sum_{i=1}^{N} [y_i - (\beta_0 + \beta_1 x_{i1} + \dots + \beta_p x_{i,p})]^2$   
subject to  $\sum_{j=1}^{p} |\beta_j|^q \le t$  (size constraint)

OR

$$\hat{\beta}^{\text{bridge}} = \operatorname{argmin}_{\beta} \left[ \sum_{i=1}^{N} [y_i - (\beta_0 + \beta_1 x_{i1} + \dots + \beta_p x_{i,p})]^2 + \lambda \sum_{j=1}^{p} |\beta_j|^q \right]$$

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 のへぐ

with no closed form for  $0 < q \leq 1$ .

To find  $\hat{\beta}^{\text{bridge}}$  that

minimize<sub>$$\beta$$</sub> *RSS*( $\beta$ ) =  $\sum_{i=1}^{N} [y_i - (\beta_0 + \beta_1 x_{i1} + \dots + \beta_p x_{i,p})]^2$   
subject to  $\sum_{j=1}^{p} |\beta_j|^q \le t$  (size constraint)

OR

$$\hat{\beta}^{\text{bridge}} = \operatorname{argmin}_{\beta} \left[ \sum_{i=1}^{N} [y_i - (\beta_0 + \beta_1 x_{i1} + \dots + \beta_p x_{i,p})]^2 + \lambda \sum_{j=1}^{p} |\beta_j|^q \right]$$

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● のへぐ

with no closed form for  $0 < q \leq 1$ .

 $|\beta_1|^q + |\beta_2|^q \le t$  for some *q* values.



When q = 0, the penalty term becomes λ Σ<sup>p</sup><sub>j=1</sub> I(β<sub>j</sub> ≠ 0)
 If columns of X are orthonormal (X<sup>T</sup>X = I), then
 β<sup>bridge</sup> = β<sup>ols</sup> I(|β<sup>ols</sup>| ≥ |β<sup>ols</sup><sub>(M)</sub>|)
 where β<sup>ols</sup> is the M<sup>th</sup> largest coefficient. It is called hard

where  $\beta_{(M)}^{ols}$  is the  $M^{th}$  largest coefficient. It is called hard thresholding. It is a subset selection method.

・ロト・日本・日本・日本・日本

- When q = 0, the penalty term becomes  $\lambda \sum_{i=1}^{p} I(\beta_i \neq 0)$
- ▶ If columns of X are orthonormal  $(X^T X = I)$ , then

$$\hat{\beta}^{\mathsf{bridge}} = \hat{\beta}^{\mathsf{ols}} I(|\hat{\beta}^{\mathsf{ols}}| \ge |\hat{\beta}^{\mathsf{ols}}_{(M)}|)$$

where  $\hat{\beta}_{(M)}^{ols}$  is the  $M^{th}$  largest coefficient. It is called hard thresholding. It is a subset selection method.

◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ ののの

Define: The generalized Gaussian distribution  $GG_q(\mu, \tau^2)$  with pdf

$$f_q(x) = \frac{1}{2\Gamma(1+\frac{1}{q})\sqrt{\frac{\Gamma(1/q)}{\Gamma(3/q)}}\tau} e^{-(\frac{\Gamma(3/q)}{\Gamma(1/q)})^{q/2}|\frac{x-\mu}{\tau}|^q}, \text{ for } x \in \mathbb{R}$$

with mean  $\mu$  and variance  $\tau^2$ .

• When q = 1, then  $GG_1(\mu, \tau)$  is the Laplace distribution.

$$f_1(x)=rac{1}{\sqrt{2} au}e^{-\sqrt{2}|rac{x-\mu}{ au}|}, ext{ for } x\in\mathbb{R}$$

When q = 2, then GG<sub>2</sub>(μ, τ) is the normal distribution N(μ, τ<sup>2</sup>).

$$f_2(x) = rac{1}{\sqrt{2\pi}\tau} e^{-rac{1}{2}(rac{x-\mu}{\tau})^2}, ext{ for } x \in \mathbb{R}$$

Define: The generalized Gaussian distribution  $GG_q(\mu, \tau^2)$  with pdf

$$f_q(x) = \frac{1}{2\Gamma(1+\frac{1}{q})\sqrt{\frac{\Gamma(1/q)}{\Gamma(3/q)}}\tau} e^{-(\frac{\Gamma(3/q)}{\Gamma(1/q)})^{q/2}|\frac{x-\mu}{\tau}|^q}, \text{ for } x \in \mathbb{R}$$

with mean  $\mu$  and variance  $\tau^2$ .

• When q = 1, then  $GG_1(\mu, \tau)$  is the Laplace distribution.

$$f_1(x)=rac{1}{\sqrt{2} au}e^{-\sqrt{2}|rac{x-\mu}{ au}|}, ext{ for } x\in \mathbb{R}$$

When q = 2, then GG<sub>2</sub>(μ, τ) is the normal distribution N(μ, τ<sup>2</sup>).

$$f_2(x) = rac{1}{\sqrt{2\pi} au} e^{-rac{1}{2}(rac{x-\mu}{ au})^2}, ext{ for } x \in \mathbb{R}$$

The generalized Gaussian distribution  $GG_q(\mu, \tau^2)$  with pdf

$$f_q(x) = \frac{1}{2\Gamma(1+\frac{1}{q})\sqrt{\frac{\Gamma(1/q)}{\Gamma(3/q)}}\tau} e^{-(\frac{\Gamma(3/q)}{\Gamma(1/q)})^{q/2}|\frac{x-\mu}{\tau}|^q}, \text{ for } x \in \mathbb{R}$$

with mean  $\mu$  and variance  $\tau^2$ .

- ▶ When  $q \to \infty$ , then  $GG_q(\mu, \tau)$  converges point-wise to the uniform distribution  $Uniform(\mu \sqrt{3}\tau, \mu + \sqrt{3}\tau)$ .
- When q → 0<sup>+</sup>, then GG<sub>q</sub>(µ, τ) converges to a degenerate distribution at x = µ.

・ロト ・ 同 ・ ・ ヨ ・ ・ ヨ ・ うへつ

The generalized Gaussian distribution  $GG_q(\mu, \tau^2)$  with pdf

$$f_q(x) = \frac{1}{2\Gamma(1+\frac{1}{q})\sqrt{\frac{\Gamma(1/q)}{\Gamma(3/q)}}\tau} e^{-(\frac{\Gamma(3/q)}{\Gamma(1/q)})^{q/2}|\frac{x-\mu}{\tau}|^q}, \text{ for } x \in \mathbb{R}$$

with mean  $\mu$  and variance  $\tau^2$ .

- ▶ When  $q \to \infty$ , then  $GG_q(\mu, \tau)$  converges point-wise to the uniform distribution  $Uniform(\mu \sqrt{3}\tau, \mu + \sqrt{3}\tau)$ .
- When q → 0<sup>+</sup>, then GG<sub>q</sub>(μ, τ) converges to a degenerate distribution at x = μ.

・ロト ・ 同 ・ ・ ヨ ・ ・ ヨ ・ うへつ

The linear regression model is

$$Y = X\beta + \epsilon,$$

where X is a  $N \times (p + 1)$ , and  $\epsilon \sim N(0, \sigma^2 I_N)$ . Then,

 $Y \sim N(X\beta, \sigma^2 I_N).$ 

So the likelihood function is

$$L(\beta,\sigma|y) = \prod_{i=1}^{N} \frac{1}{\sqrt{2\pi\sigma}} e^{-\frac{1}{2}\left(\frac{y_i - (\beta_0 + \sum_{j=1}^{p} x_{i,j}\beta_j)}{\sigma}\right)^2}$$

< □ > < 同 > < 三 > < 三 > < 三 > < ○ < ○ </p>

The linear regression model is

$$Y = X\beta + \epsilon,$$

where X is a  $N \times (p + 1)$ , and  $\epsilon \sim N(0, \sigma^2 I_N)$ . Then,

 $Y \sim N(X\beta, \sigma^2 I_N).$ 

So the likelihood function is

$$L(\beta,\sigma|\mathbf{y}) = \prod_{i=1}^{N} \frac{1}{\sqrt{2\pi\sigma}} e^{-\frac{1}{2}\left(\frac{\mathbf{y}_{i-(\beta_{0}+\sum_{j=1}^{p}\mathbf{x}_{i,j}\beta_{j})}{\sigma}\right)^{2}}$$

◆□ ▶ ◆□ ▶ ◆ □ ▶ ◆ □ ▶ ◆ □ ● ◆ ○ へ ○

The linear regression model is

$$Y = X\beta + \epsilon,$$

where X is a  $N \times (p + 1)$ , and  $\epsilon \sim N(0, \sigma^2 I_N)$ . Then,

$$Y \sim N(X\beta, \sigma^2 I_N).$$

So the likelihood function is

$$L(\beta,\sigma|\mathbf{y}) = \prod_{i=1}^{N} \frac{1}{\sqrt{2\pi\sigma}} e^{-\frac{1}{2}(\frac{\mathbf{y}_{i-(\beta_{0}+\sum_{j=1}^{p} \mathbf{x}_{i,j}\beta_{j})}{\sigma})^{2}}$$

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ - 三 - のへぐ

#### By Bayes' rule

#### posterior $\propto$ Likelihood $\cdot$ prior

Choose  $GG_q(0, \tau)$  to be a prior for each of the coefficients  $\beta_1, \ldots, \beta_p$  (with the assumption that they are independent). Thus,

$$posterior \propto \prod_{i=1}^{N} e^{-\frac{1}{2} \left(\frac{y_{i} - (\beta_{0} + \sum_{j=1}^{p} x_{i,j}\beta_{j})}{\sigma}\right)^{2}} \cdot \prod_{j=1}^{p} e^{-\left(\frac{\Gamma(3/q)}{\Gamma(1/q)}\right)^{q/2} \left|\frac{\beta_{j}}{\tau}\right|^{q}}$$
$$= e^{-\frac{1}{2\sigma^{2}} \sum_{i=1}^{N} (y_{i} - (\beta_{0} + \sum_{j=1}^{p} x_{i,j}\beta_{j}))^{2}} \cdot e^{-\left(\frac{\Gamma(3/q)}{\tau^{2}\Gamma(1/q)}\right)^{q/2} \sum_{j=1}^{p} |\beta_{j}|^{q}}$$
$$= e^{-\frac{1}{2\sigma^{2}} \left[\sum_{i=1}^{N} (y_{i} - (\beta_{0} + \sum_{j=1}^{p} x_{i,j}\beta_{j}))^{2} + \lambda \sum_{j=1}^{p} |\beta_{j}|^{q}}\right]}$$

・ロト ・ 同 ・ ・ ヨ ・ ・ ヨ ・ うへつ

where  $\lambda = 2\sigma^2 \left(\frac{\Gamma(3/q)}{\tau^2\Gamma(1/q)}\right)^{q/2}$ .

By Bayes' rule

#### posterior $\propto$ Likelihood $\cdot$ prior

Choose  $GG_q(0, \tau)$  to be a prior for each of the coefficients  $\beta_1, \ldots, \beta_p$  (with the assumption that they are independent). Thus,

$$posterior \propto \prod_{i=1}^{N} e^{-\frac{1}{2} (\frac{y_{i} - (\beta_{0} + \sum_{j=1}^{p} x_{i,j}\beta_{j})}{\sigma})^{2}} \cdot \prod_{j=1}^{p} e^{-(\frac{\Gamma(3/q)}{\Gamma(1/q)})^{q/2} |\frac{\beta_{j}}{\tau}|^{q}}$$
$$= e^{-\frac{1}{2\sigma^{2}} \sum_{i=1}^{N} (y_{i} - (\beta_{0} + \sum_{j=1}^{p} x_{i,j}\beta_{j}))^{2}} \cdot e^{-(\frac{\Gamma(3/q)}{\tau^{2}\Gamma(1/q)})^{q/2} \sum_{j=1}^{p} |\beta_{j}|^{q}}$$
$$= e^{-\frac{1}{2\sigma^{2}} \left[ \sum_{i=1}^{N} (y_{i} - (\beta_{0} + \sum_{j=1}^{p} x_{i,j}\beta_{j}))^{2} + \lambda \sum_{j=1}^{p} |\beta_{j}|^{q} \right]}$$

・ロト ・ 同 ・ ・ ヨ ・ ・ ヨ ・ うへつ

where  $\lambda = 2\sigma^2 \left(\frac{\Gamma(3/q)}{\tau^2\Gamma(1/q)}\right)^{q/2}$ .

By Bayes' rule

#### posterior $\propto$ Likelihood $\cdot$ prior

Choose  $GG_q(0, \tau)$  to be a prior for each of the coefficients  $\beta_1, \ldots, \beta_p$  (with the assumption that they are independent). Thus,

$$posterior \propto \prod_{i=1}^{N} e^{-\frac{1}{2} \left( \frac{y_{i} - (\beta_{0} + \sum_{j=1}^{p} x_{i,j}\beta_{j})}{\sigma} \right)^{2}} \cdot \prod_{j=1}^{p} e^{-\left( \frac{\Gamma(3/q)}{\Gamma(1/q)} \right)^{q/2} \left| \frac{\beta_{j}}{\tau} \right|^{q}}$$
$$= e^{-\frac{1}{2\sigma^{2}} \sum_{i=1}^{N} (y_{i} - (\beta_{0} + \sum_{j=1}^{p} x_{i,j}\beta_{j}))^{2}} \cdot e^{-\left( \frac{\Gamma(3/q)}{\tau^{2} \Gamma(1/q)} \right)^{q/2} \sum_{j=1}^{p} |\beta_{j}|^{q}}$$
$$= e^{-\frac{1}{2\sigma^{2}} \left[ \sum_{i=1}^{N} (y_{i} - (\beta_{0} + \sum_{j=1}^{p} x_{i,j}\beta_{j}))^{2} + \lambda \sum_{j=1}^{p} |\beta_{j}|^{q}} \right]$$

・ロト ・ 同 ・ ・ ヨ ・ ・ ヨ ・ うへつ

where  $\lambda = 2\sigma^2 \left(\frac{\Gamma(3/q)}{\tau^2\Gamma(1/q)}\right)^{q/2}$ .

By Bayes' rule

#### posterior $\propto$ Likelihood $\cdot$ prior

Choose  $GG_q(0, \tau)$  to be a prior for each of the coefficients  $\beta_1, \ldots, \beta_p$  (with the assumption that they are independent). Thus,

$$posterior \propto \prod_{i=1}^{N} e^{-\frac{1}{2} (\frac{y_{i} - (\beta_{0} + \sum_{j=1}^{p} x_{i,j}\beta_{j})}{\sigma})^{2}} \cdot \prod_{j=1}^{p} e^{-(\frac{\Gamma(3/q)}{\Gamma(1/q)})^{q/2} |\frac{\beta_{j}}{\tau}|^{q}}$$
$$= e^{-\frac{1}{2\sigma^{2}} \sum_{i=1}^{N} (y_{i} - (\beta_{0} + \sum_{j=1}^{p} x_{i,j}\beta_{j}))^{2}} \cdot e^{-(\frac{\Gamma(3/q)}{\tau^{2}\Gamma(1/q)})^{q/2} \sum_{j=1}^{p} |\beta_{j}|^{q}}$$
$$= e^{-\frac{1}{2\sigma^{2}} \left[ \sum_{i=1}^{N} (y_{i} - (\beta_{0} + \sum_{j=1}^{p} x_{i,j}\beta_{j}))^{2} + \lambda \sum_{j=1}^{p} |\beta_{j}|^{q}} \right]}$$

・ロト ・ 同 ・ ・ ヨ ・ ・ ヨ ・ うへつ

where  $\lambda = 2\sigma^2 \left(\frac{\Gamma(3/q)}{\tau^2 \Gamma(1/q)}\right)^{q/2}$ .

By Bayes' rule

#### posterior $\propto$ Likelihood $\cdot$ prior

Choose  $GG_q(0, \tau)$  to be a prior for each of the coefficients  $\beta_1, \ldots, \beta_p$  (with the assumption that they are independent). Thus,

$$posterior \propto \prod_{i=1}^{N} e^{-\frac{1}{2} (\frac{y_{i} - (\beta_{0} + \sum_{j=1}^{p} x_{i,j}\beta_{j})}{\sigma})^{2}} \cdot \prod_{j=1}^{p} e^{-(\frac{\Gamma(3/q)}{\Gamma(1/q)})^{q/2} |\frac{\beta_{j}}{\tau}|^{q}}$$
$$= e^{-\frac{1}{2\sigma^{2}} \sum_{i=1}^{N} (y_{i} - (\beta_{0} + \sum_{j=1}^{p} x_{i,j}\beta_{j}))^{2}} \cdot e^{-(\frac{\Gamma(3/q)}{\tau^{2}\Gamma(1/q)})^{q/2} \sum_{j=1}^{p} |\beta_{j}|^{q}}$$
$$= e^{-\frac{1}{2\sigma^{2}} \left[ \sum_{i=1}^{N} (y_{i} - (\beta_{0} + \sum_{j=1}^{p} x_{i,j}\beta_{j}))^{2} + \lambda \sum_{j=1}^{p} |\beta_{j}|^{q}} \right]}$$

・ロト ・ 同 ・ ・ ヨ ・ ・ ヨ ・ うへつ

where  $\lambda = 2\sigma^2 \left(\frac{\Gamma(3/q)}{\tau^2 \Gamma(1/q)}\right)^{q/2}$ .

Thus, -log posterior is a linear function in

$$\left[\sum_{i=1}^{N}(y_i-(\beta_0+\sum_{j=1}^{p}x_{i,j}\beta_j))^2+\lambda\sum_{j=1}^{p}|\beta_j|^q\right]$$

and so the posterior mode (the maximum point of the posterior distribution) is the minimum of the -log posterior and so it is the bridge estimate. If q = 2, then it is also the mean.

(ロ) (同) (三) (三) (三) (○) (○)

## Principal Component Regression (PCR) - an unsupervised technique for dimension reduction

・ロット (雪) (日) (日) (日)

## Principal Component Regression (PCR)

#### Starting with standardized data ...

**PCR Idea**: rotate the coordinates to reflect the most variability in the inputs in *X*, using  $z_i := Xv_i$ . Then perform regression on the new coordinate system. In that manner,

- We introduce the  $N \times M$  matrix  $W_M = XV$  with an  $p \times M$  orthonormal matrix V (with  $VV^T = l_p$ ) for some  $M \in \{1, 2, ..., p\}$
- That is, the *i*<sup>th</sup> column of  $W_M$  is  $z_i = Xv_i$ .

▶ Then,

 $Y = X\beta + \epsilon$ 

gives a reduced regression

 $Y = W_M \theta + \epsilon$ 

・ロト ・ 同 ・ ・ ヨ ・ ・ ヨ ・ うへつ

where  $\theta = V^T \beta$  and so  $\beta = V \theta$ .

## Principal Component Regression (PCR)

Starting with standardized data ...

**PCR Idea:** rotate the coordinates to reflect the most variability in the inputs in *X*, using  $z_i := Xv_i$ . Then perform regression on the new coordinate system. In that manner,

- ▶ We introduce the  $N \times M$  matrix  $W_M = XV$  with an  $p \times M$  orthonormal matrix V (with  $VV^T = l_p$ ) for some  $M \in \{1, 2, ..., p\}$
- That is, the *i*<sup>th</sup> column of  $W_M$  is  $z_i = Xv_i$ .

▶ Then,

 $Y = X\beta + \epsilon$ 

gives a reduced regression

 $Y = W_M \theta + \epsilon$ 

where  $\theta = V^T \beta$  and so  $\beta = V \theta$ .

## Principal Component Regression (PCR)

Starting with standardized data ...

**PCR Idea:** rotate the coordinates to reflect the most variability in the inputs in *X*, using  $z_i := Xv_i$ . Then perform regression on the new coordinate system. In that manner,

- We introduce the N × M matrix W<sub>M</sub> = XV with an p × M orthonormal matrix V (with VV<sup>T</sup> = I<sub>p</sub>) for some M ∈ {1, 2, ..., p}
- That is, the *i<sup>th</sup>* column of *W<sub>M</sub>* is *z<sub>i</sub>* = *Xv<sub>i</sub>*.
  Then.

$$Y = X\beta + \epsilon$$

gives a reduced regression

$$Y = W_M \theta + \epsilon$$

where  $\theta = V^T \beta$  and so  $\beta = V \theta$ .
Starting with standardized data ...

**PCR Idea:** rotate the coordinates to reflect the most variability in the inputs in *X*, using  $z_i := Xv_i$ . Then perform regression on the new coordinate system. In that manner,

- We introduce the N × M matrix W<sub>M</sub> = XV with an p × M orthonormal matrix V (with VV<sup>T</sup> = I<sub>p</sub>) for some M ∈ {1, 2, ..., p}
- That is, the *i<sup>th</sup>* column of *W<sub>M</sub>* is *z<sub>i</sub>* = *Xv<sub>i</sub>*.
   Then.

 $Y = X\beta + \epsilon$ 

gives a reduced regression

$$Y = W_M \theta + \epsilon$$

Starting with standardized data ...

**PCR Idea:** rotate the coordinates to reflect the most variability in the inputs in *X*, using  $z_i := Xv_i$ . Then perform regression on the new coordinate system. In that manner,

- We introduce the N × M matrix W<sub>M</sub> = XV with an p × M orthonormal matrix V (with VV<sup>T</sup> = I<sub>p</sub>) for some M ∈ {1, 2, ..., p}
- That is, the *i*<sup>th</sup> column of  $W_M$  is  $z_i = Xv_i$ .

Then,

$$Y = X\beta + \epsilon$$

gives a reduced regression

$$Y = W_M \theta + \epsilon$$

Thus,



$$\hat{\beta}^{\mathsf{pcr}} = V\hat{\theta}.$$

lf 
$$M = p$$
, then

$$\hat{\beta}^{\mathsf{pcr}} = \hat{\beta}^{\mathsf{ols}}.$$

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ - 三 - のへぐ

Thus,

The PCR estimate is

 $\hat{\beta}^{\mathsf{pcr}} = V\hat{\theta}.$ 

• If M = p, then

 $\hat{\beta}^{\mathsf{pcr}} = \hat{\beta}^{\mathsf{ols}}.$ 

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ - 三 - のへぐ

PCR starts with principal component analysis (PCA), an unsupervised learning, from X.

- PCR shares the idea of principal components with ridge regression ...
- Ridge Regression shrinks in the principal component directions of the small variance, whereas Principal Component Regression omit those directions (a number of *p* – *M* smallest eigenvalues).
- Yet, PCR, like ridge regression, is not a subset selection method, since the *M* components *z<sub>i</sub>*'s are linear combinations of the *p* inputs as in *z<sub>i</sub>* = *Xv<sub>i</sub>*.

- PCR starts with principal component analysis (PCA), an unsupervised learning, from X.
- PCR shares the idea of principal components with ridge regression ...
- Ridge Regression shrinks in the principal component directions of the small variance, whereas Principal Component Regression omit those directions (a number of *p* – *M* smallest eigenvalues).
- Yet, PCR, like ridge regression, is not a subset selection method, since the *M* components *z<sub>i</sub>*'s are linear combinations of the *p* inputs as in *z<sub>i</sub>* = *Xv<sub>i</sub>*.

- PCR starts with principal component analysis (PCA), an unsupervised learning, from X.
- PCR shares the idea of principal components with ridge regression ...
- Ridge Regression shrinks in the principal component directions of the small variance, whereas Principal Component Regression omit those directions (a number of *p* – *M* smallest eigenvalues).
- Yet, PCR, like ridge regression, is not a subset selection method, since the *M* components *z<sub>i</sub>*'s are linear combinations of the *p* inputs as in *z<sub>i</sub>* = *Xv<sub>i</sub>*.

- PCR starts with principal component analysis (PCA), an unsupervised learning, from X.
- PCR shares the idea of principal components with ridge regression ...
- Ridge Regression shrinks in the principal component directions of the small variance, whereas Principal Component Regression omit those directions (a number of *p* – *M* smallest eigenvalues).
- Yet, PCR, like ridge regression, is not a subset selection method, since the *M* components *z<sub>i</sub>*'s are linear combinations of the *p* inputs as in *z<sub>i</sub>* = *Xv<sub>i</sub>*.

#### Example (Prostate Cancer)

Shrinkage factor  $d^2/(d^2 + \lambda)$  versus the index of the component



ヘロト ヘポト ヘヨト ヘヨト

## PCR

#### Example (Prostate Cancer)

CV error shows optimal less complex at M = 7 using 10-fold CV.



```
1. For population data X:

Step 1: Find v_1 = \underset{\omega:\omega^T \omega=1}{\operatorname{argmax}} \operatorname{Var}(X\omega) = \underset{\omega:\omega^T \omega=1}{\operatorname{argmax}} \omega^T \operatorname{Var}(X\omega)

Step 2: Find v_2 = \underset{\substack{\omega:\omega^T \omega=1, \\ Cov(X\omega, Xv_1)=0}}{\operatorname{argmax}} \operatorname{Var}(X\omega)

:

Step M: Find v_M = \underset{\substack{\omega:\omega^T \omega=1, \\ Cov(X\omega, Xv_1)=0; i=1, \dots, M-1}}{\operatorname{argmax}} \operatorname{Var}(X\omega)
```

◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ ののの

1. For population data X: Step 1: Find  $v_1 = \underset{\omega:\omega^T \omega=1}{\operatorname{argmax}} \operatorname{Var}(X\omega) = \underset{\omega:\omega^T \omega=1}{\operatorname{argmax}} \omega^T \operatorname{Var}(X)\omega$ Step 2: Find  $v_2 = \underset{\substack{\omega:\omega^T \omega=1, \\ Cov(X\omega, Xv_1)=0}}{\operatorname{argmax}} \operatorname{Var}(X\omega)$ : Step M: Find  $v_M = \underset{\substack{\omega:\omega^T \omega=1, \\ Cov(X\omega, Xv_1)=0; i=1, \dots, M-1}}{\operatorname{argmax}} \operatorname{Var}(X\omega)$ 

◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ ののの

1. For population data X: Step 1: Find  $v_1 = \underset{\omega:\omega^T\omega=1}{\operatorname{argmax}} \operatorname{Var}(X\omega) = \underset{\omega:\omega^T\omega=1}{\operatorname{argmax}} \omega^T \operatorname{Var}(X)\omega$ Step 2: Find  $v_2 = \underset{\substack{\omega:\omega^T\omega=1, \\ Cov(X\omega,Xv_1)=0}}{\operatorname{argmax}} \operatorname{Var}(X\omega)$ : Step M: Find  $v_M = \underset{\substack{\omega:\omega^T\omega=1, \\ Cov(X\omega,Xv_l)=0; i=1,...,M-1}}{\operatorname{Var}(X\omega)}$ 

◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ ののの

1. For population data X: Step 1: Find  $v_1 = \underset{\omega:\omega^T\omega=1}{\operatorname{argmax}} \operatorname{Var}(X\omega) = \underset{\omega:\omega^T\omega=1}{\operatorname{argmax}} \omega^T \operatorname{Var}(X)\omega$ Step 2: Find  $v_2 = \underset{\substack{\omega:\omega^T\omega=1, \\ Cov(X\omega, Xv_1)=0}}{\operatorname{argmax}} \operatorname{Var}(X\omega)$ : Step M: Find  $v_M = \underset{\substack{\omega:\omega^T\omega=1, \\ Cov(X\omega, Xv_1)=0; i=1, \dots, M-1}}{\operatorname{argmax}} \operatorname{Var}(X\omega)$ 

◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ ののの

1. For population data X: Step 1: Find  $v_1 = \underset{\omega:\omega^T \omega=1}{\operatorname{argmax}} \operatorname{Var}(X\omega) = \underset{\omega:\omega^T \omega=1}{\operatorname{argmax}} \omega^T \operatorname{Var}(X)\omega$ Step 2: Find  $v_2 = \underset{\substack{\omega:\omega^T \omega=1, \\ Cov(X\omega, Xv_1)=0}}{\operatorname{argmax}} \operatorname{Var}(X\omega)$ : Step M: Find  $v_M = \underset{\substack{\omega:\omega^T \omega=1, \\ Cov(X\omega, Xv_l)=0; i=1, \dots, M-1}}{\operatorname{argmax}} \operatorname{Var}(X\omega)$ 

◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ ののの

1. For population data X: Step 1: Find  $v_1 = \underset{\omega:\omega^T \omega=1}{\operatorname{argmax}} \operatorname{Var}(X\omega) = \underset{\omega:\omega^T \omega=1}{\operatorname{argmax}} \omega^T \operatorname{Var}(X)\omega$ Step 2: Find  $v_2 = \underset{\substack{\omega:\omega^T \omega=1, \\ Cov(X\omega, Xv_1)=0}}{\operatorname{argmax}} \operatorname{Var}(X\omega)$ : Step M: Find  $v_M = \underset{\substack{\omega:\omega^T \omega=1, \\ Cov(X\omega, Xv_l)=0; i=1, \dots, M-1}}{\operatorname{argmax}} \operatorname{Var}(X\omega)$ 

◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ ののの

1. For population data X: Step 1: Find  $v_1 = \underset{\omega:\omega^{T}\omega=1}{\operatorname{argmax}} \operatorname{Var}(X\omega) = \underset{\omega:\omega^{T}\omega=1}{\operatorname{argmax}} \omega^{T} \operatorname{Var}(X)\omega$ Step 2: Find  $v_2 = \underset{\substack{\omega:\omega^{T}\omega=1, \\ Cov(X\omega, Xv_1)=0}}{\operatorname{argmax}} \operatorname{Var}(X\omega)$ : Step M: Find  $v_M = \underset{\substack{\omega:\omega^{T}\omega=1, \\ Cov(X\omega, Xv_l)=0; i=1, \dots, M-1}}{\operatorname{argmax}} \operatorname{Var}(X\omega)$ 

◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ ののの

1. For population data X: Step 1: Find  $v_1 = \underset{\omega:\omega^{T}\omega=1}{\operatorname{argmax}} \operatorname{Var}(X\omega) = \underset{\omega:\omega^{T}\omega=1}{\operatorname{argmax}} \omega^{T} \operatorname{Var}(X)\omega$ Step 2: Find  $v_2 = \underset{\substack{\omega:\omega^{T}\omega=1, \\ Cov(X\omega, Xv_1)=0}}{\operatorname{argmax}} \operatorname{Var}(X\omega)$ : Step M: Find  $v_M = \underset{\substack{\omega:\omega^{T}\omega=1, \\ Cov(X\omega, Xv_i)=0; i=1, \dots, M-1}}{\operatorname{argmax}} \operatorname{Var}(X\omega)$ 

◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ ののの

```
2. For sample data X:
Step M: Find v_M = argmax \omega^T X^T X \omega
```

▲□▶ ▲□▶ ▲目▶ ▲目▶ 三目 - のへの

```
2. For sample data X:
 Step 1: Find v_1 = argmax \omega^T X^T X \omega
                       \omega:\omega^T\omega=1
Step M: Find v_M = argmax \omega^T X^T X \omega
```

```
2. For sample data X:
 Step 1: Find v_1 = argmax \omega^T X^T X \omega
                          \omega:\omega^T\omega=1
 Step 2: Find v_2 = argmax \omega^T X^T X \omega
                           \omega:\omega^T\omega=1.
                          \omega^T X^T X v_1 = 0
Step M: Find v_M = argmax \omega^T X^T X \omega
```

```
2. For sample data X:
 Step 1: Find v_1 = argmax \omega^T X^T X \omega
                          \omega:\omega^T\omega=1
 Step 2: Find v_2 = argmax \omega^T X^T X \omega
                           \omega:\omega^T\omega=1.
                          \omega^T X^T X v_1 = 0
Step M: Find v_M = argmax \omega^T X^T X \omega
```

・ロト・日本・日本・日本・日本・日本

```
2. For sample data X:
 Step 1: Find v_1 = \operatorname{argmax} \omega^T X^T X \omega
                               \omega:\omega^T\omega=1
 Step 2: Find v_2 = argmax \omega^T X^T X \omega
                               \omega:\omega^T\omega=1.
                              \omega^T X^T X v_1 = 0
Step M: Find v_M = argmax \omega^T X^T X \omega
                                        \omega:\omega^T\omega=1,
                               \omega^T X^T X v_i = 0; i = 1, ..., M - 1
```

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● ● ●

```
2. For sample data X:
 Step 1: Find v_1 = \operatorname{argmax} \omega^T X^T X \omega
                               \omega:\omega^T\omega=1
 Step 2: Find v_2 = argmax \omega^T X^T X \omega
                               \omega:\omega^T\omega=1.
                              \omega^T X^T X v_1 = 0
Step M: Find v_M = argmax \omega^T X^T X \omega
                                        \omega:\omega^T\omega=1,
                               \omega^T X^T X v_i = 0; i = 1, ..., M - 1
```

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● ● ●

```
2. For sample data X:
  Step 1: Find v_1 = \operatorname{argmax} \omega^T X^T X \omega
                             \omega:\omega^T\omega=1
  Step 2: Find v_2 = argmax \ \omega^T X^T X \omega
                             \omega:\omega^T\omega=1.
                             \omega^T X^T X v_1 = 0
Step M: Find v_M = argmax \omega^T X^T X \omega
                                     \omega:\omega^T\omega=1,
                             \omega^T X^T X v_i = 0; i = 1, \dots, M-1
But, no guarantee that the directions with the largest
```

variance/explanation of the predictor, will also be the best for prediction. So ...

◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ ののの

Partial Least Squares (PLS) - a supervised technique for dimension reduction

#### Starting with standardized data but this time including Y ...

**PLS Idea**: rotate the coordinates to reflect the most correlation between the output *Y* and the inputs in *X*, using PLS directions  $z_i := Xv_i$ . Then perform regression on the new coordinate system. In that manner,

- We introduce the N × M matrix W<sub>M</sub> = XV with an p × M orthonormal matrix V (with VV<sup>T</sup> = l<sub>p</sub>) for some M ∈ {1, 2, ..., p}
- That is, the *i*<sup>th</sup> column of  $W_M$  is  $z_i = Xv_i$ .

▶ Then,

 $Y = X\beta + \epsilon$ 

gives a reduced regression

$$Y = W_M \theta + \epsilon$$

(日) (日) (日) (日) (日) (日) (日)

Starting with standardized data but this time including  $Y \dots$ PLS Idea: rotate the coordinates to reflect the most correlation between the output Y and the inputs in X, using PLS directions  $z_i := Xv_i$ . Then perform regression on the new coordinate system. In that manner,

- ▶ We introduce the  $N \times M$  matrix  $W_M = XV$  with an  $p \times M$ orthonormal matrix V (with  $VV^T = I_p$ ) for some  $M \in \{1, 2, ..., p\}$
- That is, the *i*<sup>th</sup> column of  $W_M$  is  $z_i = Xv_i$ .

Then,

 $Y = X\beta + \epsilon$ 

gives a reduced regression

 $Y = W_M \theta + \epsilon$ 

Starting with standardized data but this time including  $Y \dots$ PLS Idea: rotate the coordinates to reflect the most correlation between the output Y and the inputs in X, using PLS directions  $z_i := Xv_i$ . Then perform regression on the new coordinate system. In that manner,

We introduce the N × M matrix W<sub>M</sub> = XV with an p × M orthonormal matrix V (with VV<sup>T</sup> = I<sub>p</sub>) for some M ∈ {1, 2, ..., p}

That is, the *i*<sup>th</sup> column of  $W_M$  is  $z_i = Xv_i$ .

► Then,

 $Y = X\beta + \epsilon$ 

gives a reduced regression

$$Y = W_M \theta + \epsilon$$

Starting with standardized data but this time including  $Y \dots$ PLS Idea: rotate the coordinates to reflect the most correlation between the output Y and the inputs in X, using PLS directions  $z_i := Xv_i$ . Then perform regression on the new coordinate system. In that manner,

- We introduce the N × M matrix W<sub>M</sub> = XV with an p × M orthonormal matrix V (with VV<sup>T</sup> = I<sub>p</sub>) for some M ∈ {1, 2, ..., p}
- That is, the *i*<sup>th</sup> column of  $W_M$  is  $z_i = Xv_i$ .

Then,

 $Y = X\beta + \epsilon$ 

gives a reduced regression

$$Y = W_M \theta + \epsilon$$

Starting with standardized data but this time including  $Y \dots$ PLS Idea: rotate the coordinates to reflect the most correlation between the output Y and the inputs in X, using PLS directions  $z_i := Xv_i$ . Then perform regression on the new coordinate system. In that manner,

- We introduce the N × M matrix W<sub>M</sub> = XV with an p × M orthonormal matrix V (with VV<sup>T</sup> = I<sub>p</sub>) for some M ∈ {1, 2, ..., p}
- That is, the *i*<sup>th</sup> column of  $W_M$  is  $z_i = Xv_i$ .

Then,

$$\mathbf{Y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\epsilon}$$

gives a reduced regression

$$Y = W_M \theta + \epsilon$$

Thus,



 $\hat{\beta}^{\mathsf{pls}} = V\hat{\theta}.$ 

▶ If 
$$M = p$$
, then

 $\hat{\beta}^{\mathsf{pls}} = \hat{\beta}^{\mathsf{ols}}$ 

◆□▶ ◆□▶ ◆ □▶ ◆ □▶ ● □ ● ● ●

Thus,

The PLS estimate is

 $\hat{\beta}^{\mathsf{pls}} = V\hat{\theta}.$ 

• If M = p, then

 $\hat{\beta}^{\mathsf{pls}} = \hat{\beta}^{\mathsf{ols}}.$ 

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ - 三 - のへぐ

#### PLS Directions $z_i = Xv_i$

#### For population data X:

Step 1: Find

 $v_{1} = \underset{\omega:\omega^{\tau}\omega=1}{\operatorname{argmax}} \operatorname{Cov}^{2}(Y, X\omega) = \underset{\omega:\omega^{\tau}\omega=1}{\operatorname{argmax}} \operatorname{Corr}^{2}(Y, X\omega) \operatorname{Var}(X\omega)$ 

Step 2: Find  $v_2 = \underset{\substack{\omega:\omega^T \omega = 1, \\ Cov(X\omega, Xv_1) = 0}}{\operatorname{argmax}} Cov^2(Y, X\omega)$  $\vdots$ Step M: Find  $v_M = \underset{\substack{\omega:\omega^T \omega = 1, \\ Cov(X\omega, Xv_l) = 0; i = 1, \dots, M - 1}}{\operatorname{argmax}} Cov^2(Y, X\omega)$ 

PLS Directions  $z_i = Xv_i$ 

For population data X: Step 1: Find

 $v_{1} = \underset{\omega:\omega^{T}\omega=1}{\operatorname{argmax}} \operatorname{Corr}^{2}(Y, X\omega) = \underset{\omega:\omega^{T}\omega=1}{\operatorname{argmax}} \operatorname{Corr}^{2}(Y, X\omega) \operatorname{Var}(X\omega)$ 

◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ ののの

Step 2: Find  $v_2 = \underset{\substack{\omega:\omega^T \omega = 1, \\ Cov(X\omega, Xv_1) = 0}}{\operatorname{argmax}} Cov^2(Y, X\omega)$ : Step M: Find  $v_M = \underset{\substack{\omega:\omega^T \omega = 1, \\ Cov(X\omega, Xv_l) = 0; l = 1, \dots, M-1}}{\operatorname{argmax}} Cov^2(Y, X\omega)$ 

PLS Directions  $z_i = Xv_i$ 

For population data X: Step 1: Find

$$v_{1} = \underset{\omega:\omega^{T}\omega=1}{\operatorname{argmax}} \operatorname{Corr}^{2}(Y, X\omega) = \underset{\omega:\omega^{T}\omega=1}{\operatorname{argmax}} \operatorname{Corr}^{2}(Y, X\omega) \operatorname{Var}(X\omega)$$

Step 2: Find 
$$v_2 = \underset{\substack{\omega:\omega^T\omega=1,\\Cov(X\omega,Xv_1)=0}}{\operatorname{argmax}} Cov^2(Y,X\omega)$$

Step M: Find  $v_M = \underset{\substack{\omega:\omega^T\omega=1,\\Cov(X\omega,Xv_l)=0; i=1,...,M-1}}{argmax} Cov^2(Y,X)$
For population data X: Step 1: Find

$$v_{1} = \underset{\omega:\omega^{T}\omega=1}{\operatorname{argmax}} \operatorname{Corr}^{2}(Y, X\omega) = \underset{\omega:\omega^{T}\omega=1}{\operatorname{argmax}} \operatorname{Corr}^{2}(Y, X\omega) \operatorname{Var}(X\omega)$$

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● のへぐ

Step 2: Find 
$$v_2 = \underset{\substack{\omega:\omega^T \omega = 1, \\ Cov(X\omega, Xv_1) = 0}}{\operatorname{argmax}} Cov^2(Y, X\omega)$$
  
:  
Step M: Find  $v_M = \underset{\substack{\omega:\omega^T \omega = 1, \\ Cov(X\omega, Xv_i) = 0; i = 1, \dots, M-1}}{\operatorname{argmax}} Cov^2(Y, X\omega)$ 

For population data X: Step 1: Find

$$v_{1} = \underset{\omega:\omega^{T}\omega=1}{\operatorname{argmax}} \operatorname{Corr}^{2}(Y, X\omega) = \underset{\omega:\omega^{T}\omega=1}{\operatorname{argmax}} \operatorname{Corr}^{2}(Y, X\omega) \operatorname{Var}(X\omega)$$

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● のへぐ

Step 2: Find 
$$v_2 = \underset{\substack{\omega:\omega^T \omega = 1, \\ Cov(X\omega, Xv_1) = 0}}{\operatorname{argmax}} Cov^2(Y, X\omega)$$
  
:  
Step M: Find  $v_M = \underset{\substack{\omega:\omega^T \omega = 1, \\ Cov(X\omega, Xv_i) = 0; i = 1, \dots, M-1}}{\operatorname{argmax}} Cov^2(Y, X\omega)$ 

For population data X: Step 1: Find

$$v_{1} = \underset{\omega:\omega^{T}\omega=1}{\operatorname{argmax}} \operatorname{Corr}^{2}(Y, X\omega) = \underset{\omega:\omega^{T}\omega=1}{\operatorname{argmax}} \operatorname{Corr}^{2}(Y, X\omega) \operatorname{Var}(X\omega)$$

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● のへぐ

Step 2: Find 
$$v_2 = \underset{\substack{\omega:\omega^T \omega = 1, \\ Cov(X\omega, Xv_1) = 0}}{\operatorname{argmax}} Cov^2(Y, X\omega)$$
  
:  
Step M: Find  $v_M = \underset{\substack{\omega:\omega^T \omega = 1, \\ Cov(X\omega, Xv_i) = 0; i = 1, \dots, M-1}}{\operatorname{argmax}} Cov^2(Y, X\omega)$ 

For population data X: Step 1: Find

$$v_{1} = \underset{\omega:\omega^{T}\omega=1}{\operatorname{argmax}} \operatorname{Corr}^{2}(Y, X\omega) = \underset{\omega:\omega^{T}\omega=1}{\operatorname{argmax}} \operatorname{Corr}^{2}(Y, X\omega) \operatorname{Var}(X\omega)$$

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● のへぐ

Step 2: Find 
$$v_2 = \underset{\substack{\omega:\omega^{T}\omega=1,\\Cov(X\omega,Xv_1)=0}}{\operatorname{argmax}} Cov^2(Y, X\omega)$$
  
:  
Step M: Find  $v_M = \underset{\substack{\omega:\omega^{T}\omega=1,\\Cov(X\omega,Xv_i)=0; i=1,...,M-1}}{\operatorname{argmax}} Cov^2(Y, X\omega)$ 

For population data X: Step 1: Find

$$v_{1} = \underset{\omega:\omega^{T}\omega=1}{\operatorname{argmax}} \operatorname{Corr}^{2}(Y, X\omega) = \underset{\omega:\omega^{T}\omega=1}{\operatorname{argmax}} \operatorname{Corr}^{2}(Y, X\omega) \operatorname{Var}(X\omega)$$

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● のへぐ

Step 2: Find 
$$v_2 = \underset{\substack{\omega:\omega^{T}\omega=1,\\Cov(X\omega,Xv_1)=0}}{\operatorname{argmax}} Cov^2(Y, X\omega)$$
  
:  
Step M: Find  $v_M = \underset{\substack{\omega:\omega^{T}\omega=1,\\Cov(X\omega,Xv_i)=0; i=1,...,M-1}}{\operatorname{argmax}} Cov^2(Y, X\omega)$ 

### PLS

#### Example (Prostate Cancer)

CV error shows optimal less complex at M = 2 using 10-fold CV.



Partial Least Squares

▲□▶ ▲□▶ ▲三▶ ▲三▶ 三三 のへで

#### Example (Prostate Cancer)

Term	LS	Best Subset	Ridge	Lasso	PCR	PLS
Intercept	2.465	2.477	2.452	2.468	2.497	2.452
lcavol	0.680	0.740	0.420	0.533	0.543	0.419
lweight	0.263	0.316	0.238	0.169	0.289	0.344
age	-0.141		-0.046		-0.152	-0.026
lbph	0.210		0.162	0.002	0.214	0.220
svi	0.305		0.227	0.094	0.315	0.243
lcp	-0.288		0.000		-0.051	0.079
gleason	-0.021		0.040		0.232	0.011
pgg45	0.267		0.133		-0.056	0.084
Test Error	0.521	0.492	0.492	0.479	0.449	0.528
Std Error	0.179	0.143	0.165	0.164	0.105	0.152

▲□▶▲□▶▲□▶▲□▶ □ のQ@

#### It is a non-parametric method.

K-means Idea: the simplest is the K-nearest neighbor regression (K-NN). Thus, K-means regression is a local method. In that manner,

The predicted response at x<sub>\*</sub> is

$$\hat{f}(x_*) = Average(y_i | x_i \in N_k(x_*)) = \frac{1}{k} \sum_{x_i \in N_k(x_*)} y_i$$

▲□▶ ▲□▶ ▲三▶ ▲三▶ - 三 - のへで

where  $N_k(x_*)$  is a neighborhood of  $x_*$  of size k.

It is a non-parametric method.

K-means Idea: the simplest is the K-nearest neighbor regression (K-NN). Thus, K-means regression is a local method. In that manner,

The predicted response at x<sub>\*</sub> is



◆□ ▶ ◆□ ▶ ◆三 ▶ ◆□ ▶ ◆□ ● ◆○ ○ ○

where  $N_k(x_*)$  is a neighborhood of  $x_*$  of size k.

It is a non-parametric method.

K-means Idea: the simplest is the K-nearest neighbor regression (K-NN). Thus, K-means regression is a local method. In that manner,

The predicted response at x<sub>\*</sub> is

$$\hat{f}(x_*) = Average(y_i | x_i \in N_k(x_*)) = \frac{1}{k} \sum_{x_i \in N_k(x_*)} y_i$$

< □ > < 同 > < 三 > < 三 > < 三 > < ○ < ○ </p>

where  $N_k(x_*)$  is a neighborhood of  $x_*$  of size k.

K = 1 versus K = 9



Parametric functions that really represent the data outperform non-parametric methods. Curse of dimensionality vs overfitting.



◆□▶★□▶★□▶★□▶ □ のへで

# End of Set 3