

## VECTORS IN $\mathbb{R}^3$

### ▼ Cartesian product

Let  $A, B, C$  be three sets. We define the Cartesian products

$$A \times B = \{(a, b) \mid a \in A \wedge b \in B\}$$

$$A \times B \times C = \{(a, b, c) \mid a \in A \wedge b \in B \wedge c \in C\}$$

where  $(a, b)$  is an ordered pair and  $(a, b, c)$  is an ordered triplet

- The behavior of ordered pairs and ordered triplets is covered by the following axioms:

$$(a_1, a_2) = (b_1, b_2) \Leftrightarrow a_1 = b_1 \wedge a_2 = b_2$$

$$(a_1, a_2, a_3) = (b_1, b_2, b_3) \Leftrightarrow a_1 = b_1 \wedge a_2 = b_2 \wedge a_3 = b_3$$

- Geometrical three-dimensional space can be represented as

$$\mathbb{R}^3 = \mathbb{R} \times \mathbb{R} \times \mathbb{R} = \{(x, y, z) \mid x \in \mathbb{R} \wedge y \in \mathbb{R} \wedge z \in \mathbb{R}\}$$

with  $\mathbb{R}$ , the set of all real numbers.

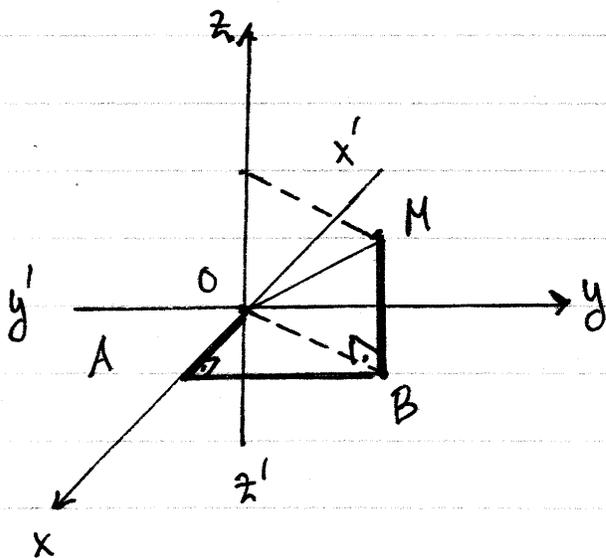
An element  $(x, y, z) \in \mathbb{R}^3$  represents a point in space with cartesian coordinates  $x, y, z$ , as defined below.

- Likewise, geometrical two-dimensional space can be represented as

$$\mathbb{R}^2 = \mathbb{R} \times \mathbb{R} = \{(x, y) \mid x \in \mathbb{R} \wedge y \in \mathbb{R}\}$$

An element  $(x, y) \in \mathbb{R}^2$  represents a point on a plane with coordinates  $(x, y)$ .

## ▼ Cartesian coordinates



The cartesian coordinate system consists of three lines  $(x'x)$ ,  $(y'y)$ ,  $(z'z)$

such that

$$\begin{cases} (x'x) \perp (y'y) \perp (z'z) \perp (x'x) \\ (x'x) \cap (y'y) \cap (z'z) = \{O\} \end{cases}$$

where  $O$  is the origin of the coordinate system.

Let  $M(x, y, z)$  be a point with coordinates  $(x, y, z)$ .

We define  $x, y, z$  as follows:

Let  $B$  be the projection of  $M$  to the  $xy$  plane.

Let  $A$  be the projection of  $B$  to the  $x'x$  axis.

Then, we define:

$$\begin{cases} x = \overline{OA} \\ y = \overline{AB} \\ z = \overline{BM} \end{cases}$$

The bar indicates using directional distance. For example,  $\overline{OA}$  is positive or negative depending on whether  $A$  is on the  $Ox$  or the  $Ox'$  ray.

Terminology:  $x$ -axis is the line  $x'Ox$

$y$ -axis is the line  $y'Oy$

$z$ -axis is the line  $z'Oz$

Likewise:

$xy$  plane: plane defined by  $(x'x)$  and  $(y'y)$   
 $yz$  plane: plane defined by  $(y'y)$  and  $(z'z)$   
 $zx$  plane: plane defined by  $(z'z)$  and  $(x'x)$


Distance Formula

$$\textcircled{1} \quad M(x, y, z) \Rightarrow OM = \sqrt{x^2 + y^2 + z^2}$$

Proof

$OA \perp AB \Rightarrow \triangle OAB$  right triangle with  $A = 90^\circ$

$$\Rightarrow OB^2 = OA^2 + AB^2 = x^2 + y^2$$

$OB \perp BM \Rightarrow \triangle OBM$  right triangle with  $B = 90^\circ$

$$\Rightarrow OM^2 = OB^2 + BM^2 = OB^2 + z^2 =$$

$$= (x^2 + y^2) + z^2$$

$$\Rightarrow OM = \sqrt{x^2 + y^2 + z^2} \quad \text{D}$$

$$\textcircled{2} \quad \left. \begin{array}{l} A(x_1, y_1, z_1) \\ B(x_2, y_2, z_2) \end{array} \right\} \Rightarrow AB = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}$$

Proof

Using  $A$  as the origin of a coordinate system where the axes are parallel and similarly oriented with the coordinate system around  $O$ , the coordinates of  $B$  are  $(x_2 - x_1, y_2 - y_1, z_2 - z_1)$ . Using the previous result we immediately calculate  $AB$ .

↗ The sphere  $(A, r)$  with center  $A$  and  
radius  $r$  is defined as:

$$(A, r) = \{M \in \mathbb{R}^3 \mid AM = r\}$$

and therefore:

$$(A, r): (x - x_A)^2 + (y - y_A)^2 + (z - z_A)^2 = r^2$$

with  $A(x_A, y_A, z_A)$ .

## EXAMPLES

Find all  $\lambda \in \mathbb{R}$  such that  $AB = a$  with  $A(1, \lambda+1, \lambda-1)$  and  $B(\lambda, \lambda+1, -1)$

Solution

Since,

$$\begin{aligned} AB^2 &= (x_A - x_B)^2 + (y_A - y_B)^2 + (z_A - z_B)^2 = \\ &= (1 - \lambda)^2 + [(\lambda + 1) - (\lambda + 1)]^2 + [(\lambda - 1) - (-1)]^2 = \\ &= (1 - \lambda)^2 + 0^2 + (\lambda - 1 + 1)^2 = (1 - \lambda)^2 + \lambda^2 = \\ &= 1 - 2\lambda + \lambda^2 + \lambda^2 = 2\lambda^2 - 2\lambda + 1 \Rightarrow \end{aligned}$$

$$\Rightarrow AB = \sqrt{2\lambda^2 - 2\lambda + 1}$$

it follows that

$$\begin{aligned} AB = a &\Leftrightarrow \sqrt{2\lambda^2 - 2\lambda + 1} = a \quad [\text{Require } a \geq 0] \\ &\Leftrightarrow 2\lambda^2 - 2\lambda + 1 = a^2 \Leftrightarrow 2\lambda^2 - 2\lambda + 1 - a^2 = 0 \quad (1) \end{aligned}$$

The corresponding discriminant is:

$$\begin{aligned} \Delta &= (-2)^2 - 4 \cdot 2 \cdot (1 - a^2) = 4 - 8(1 - a^2) = 4 - 8 + 8a^2 \\ &= 8a^2 - 4 = 4(2a^2 - 1) = 4(\sqrt{2}a - 1)(\sqrt{2}a + 1) \end{aligned}$$

and note the sign of  $\Delta$ ; where we require  $a \geq 0$

$a$	$-1/\sqrt{2}$	$0$	$1/\sqrt{2}$
$\sqrt{2}a - 1$	-	-	-
$\sqrt{2}a + 1$	-	+	+
$\Delta$	<del>+</del>	-	+

We distinguish between the following cases

Case 1: Assume that  $a \in (0, 1/\sqrt{2})$ . Then  $\Delta < 0$ , and therefore Eq. (1) has no real solutions.

Case 2: Assume that  $a = 1/\sqrt{2}$ . Then  $\Delta = 0$ , and therefore Eq. (1) has one real solution:

$$\lambda = -(-2)/(2 \cdot 2) = 1/2$$

Case 3: Assume that  $a \in (1/\sqrt{2}, +\infty)$ . Then  $\Delta > 0$ , and therefore Eq. (1) has two real solutions

$$\begin{aligned} \lambda_{1,2} &= \frac{-(-2) \pm \sqrt{4(2a^2-1)}}{2 \cdot 2} = \frac{2 \pm 2\sqrt{2a^2-1}}{2 \cdot 2} \\ &= \frac{1 \pm \sqrt{2a^2-1}}{2} \end{aligned}$$

We conclude that

$$AB = a \iff \lambda \in S$$

with

$$S = \begin{cases} \{ [1 + \sqrt{2a^2-1}]/2, [1 - \sqrt{2a^2-1}]/2 \} & , \text{ if } a \in (1/\sqrt{2}, +\infty) \\ \{ 1/2 \} & , \text{ if } a = 1/\sqrt{2} \\ \emptyset & , \text{ if } a \in (0, 1/\sqrt{2}) \end{cases}$$

b) Find the center and radius of the sphere

$$(c): x^2 + y^2 + z^2 - 4x + 2y + 6z = 11.$$

Solution

Since

$$(c): x^2 + y^2 + z^2 - 4x + 2y + 6z = 11 \Leftrightarrow$$

$$\Leftrightarrow (x^2 - 4x + 4) + (y^2 + 2y + 1) + (z^2 + 6z + 9) = 11 + 4 + 1 + 9$$

$$\Leftrightarrow (x-2)^2 + (y+1)^2 + (z+3)^2 = 25$$

$$\Leftrightarrow (x-2)^2 + (y-(-1))^2 + (z-(-3))^2 = 5^2$$

it follows that (c) has center  $A(2, -1, -3)$

and radius  $r = 5$ .

## EXERCISES

- ① Find the distance  $AB$  between the points  $A$  and  $B$  with coordinates:
- a)  $A(\sqrt{2}+\sqrt{3}, 2, \sqrt{2})$  and  $B(\sqrt{2}-\sqrt{3}, 3, 1)$
  - b)  $A(0, \sqrt{3}, \sqrt{5})$  and  $B(2, 1+\sqrt{3}, \sqrt{2})$
  - c)  $A(a, b, a)$  and  $B(-b, a, b)$
  - d)  $A(ab, b^2, bc)$  and  $B(ac, bc, c^2)$
  - e)  $A(at, bt, ct)$  and  $B(bt, ct, at)$
- ② Find all  $\lambda \in \mathbb{R}$  such that for  $A(\lambda, \lambda+1, \lambda+2)$  and  $B(\lambda-1, 2\lambda, \lambda)$  satisfy  $AB=1$ .
- ③ Let  $\triangle ABC$  be a triangle with  $A(a, b, c)$ ,  $B(b, c, a)$ , and  $C(c, a, b)$ . Show that  $\triangle ABC$  is an equilateral triangle.
- ④ Write the equation of a sphere with center  $C$  and radius  $r$  given by:
- a)  $C(1, 2, 3)$  and  $r=5$
  - b)  $C(-2, -3, -6)$  and  $r=\sqrt{5}$
  - c)  $C(\pi, e, \sqrt{2})$  and  $r=\sqrt{\pi}$
- ⑤ Find the radius and center for the following spheres:

a) (c):  $x^2 + y^2 + z^2 - 12x + 14y - 8z + 1 = 0$

b) (c):  $x^2 + y^2 + z^2 + 2x - 6y - 10z + 34 = 0$

c) (c):  $4x^2 + 4y^2 + 4z^2 - 4x + 8y + 16z - 13 = 0$

d) (c):  $x^2 + y^2 + z^2 + 8x - 4y - 22z + 77 = 0$

⑥ Find the equation of the sphere with center C and passing through the point A with

a) C(1, 2, 1) and A(3, 2, -1)

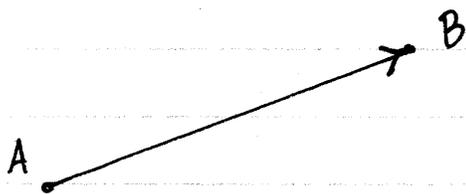
b) C(2, 0, 3) and A(-1, -1, -2)

c) C(0, 1, -1) and A(2, 2, 3)

## ▼ Geometric vectors

- Let  $A, B$  be two points. The vector  $\vec{AB}$  is a segment  $AB$  in which we define a direction from  $A$  to  $B$ .

We say that:  $A$  is the initial point of  $\vec{AB}$   
 $B$  is the terminal point of  $\vec{AB}$



## ► Geometric vector equivalence

Given the vectors  $\vec{AB}$  and  $\vec{CD}$ , we say that  $\vec{AB} = \vec{CD}$  if and only if the vectors  $\vec{AB}$  and  $\vec{CD}$  have the same length, are parallel to each other and have the same direction.

More rigorously, we give the following definition:

Def: Let  $\vec{AB}$  and  $\vec{CD}$  be two vectors and let

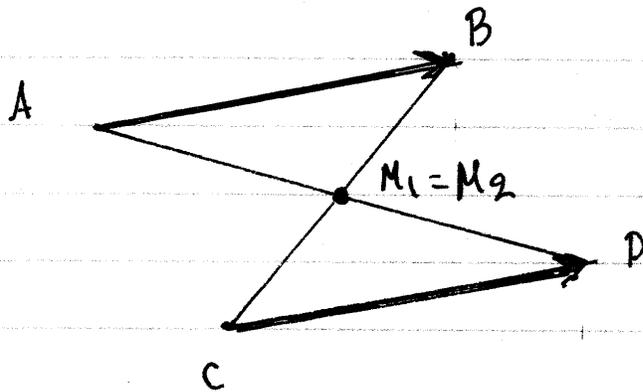
$M_1 = \text{midpoint of } AD$

$M_2 = \text{midpoint of } BC$

Then:

$$\vec{AB} = \vec{CD} \Leftrightarrow M_1 = M_2$$

which is illustrated in the following figure:



Recall the definition of the midpoint:

$$M = \text{midpoint of } AB \Leftrightarrow \begin{cases} x_M = (1/2)(x_A + x_B) \\ y_M = (1/2)(y_A + y_B) \\ z_M = (1/2)(z_A + z_B) \end{cases}$$

→ Coordinate representation of geometric vectors.

Choose a coordinate system and assume that  $A(x_A, y_A, z_A)$  and  $B(x_B, y_B, z_B)$  with respect to the chosen coordinate system. We define the coordinate representation of the vector  $\vec{AB}$  as

$$\vec{AB} = (x_B - x_A, y_B - y_A, z_B - z_A)$$

Note that this representation is dependent on our choice of coordinate system.

It follows that

$$\vec{AA} = (0, 0, 0) = \mathbf{0}$$

with  $\mathbf{0}$  the zero vector.

We will now show that equivalent geometric vectors have the same coordinate representation.

Prop: Let  $\vec{AB}$  and  $\vec{CD}$  be two vectors with  
 $\vec{AB} = (a_1, a_2, a_3)$  and  $\vec{CD} = (b_1, b_2, b_3)$

Then:

$$\vec{AB} = \vec{CD} \Leftrightarrow a_1 = b_1 \wedge a_2 = b_2 \wedge a_3 = b_3$$

$$\Leftrightarrow (a_1, a_2, a_3) = (b_1, b_2, b_3)$$

Proof

We note that

$$\vec{AB} = (a_1, a_2, a_3) \Rightarrow \begin{cases} a_1 = x_B - x_A \\ a_2 = y_B - y_A \\ a_3 = z_B - z_A \end{cases}$$

$$\vec{CD} = (b_1, b_2, b_3) \Rightarrow \begin{cases} b_1 = x_D - x_C \\ b_2 = y_D - y_C \\ b_3 = z_D - z_C \end{cases}$$

Let  $M$  be the midpoint of  $AD$  and let  $N$  be the midpoint of  $BC$ . Then:

$$\begin{cases} x_M = (1/2)(x_A + x_D) \\ y_M = (1/2)(y_A + y_D) \\ z_M = (1/2)(z_A + z_D) \end{cases} \wedge \begin{cases} x_N = (1/2)(x_B + x_C) \\ y_N = (1/2)(y_B + y_C) \\ z_N = (1/2)(z_B + z_C) \end{cases}$$

It follows that

$$a_1 = b_1 \Leftrightarrow x_B - x_A = x_D - x_C \Leftrightarrow x_A + x_D = x_B + x_C \Leftrightarrow$$

$$\Leftrightarrow (1/2)(x_A + x_D) = (1/2)(x_B + x_C) \Leftrightarrow$$

$$\Leftrightarrow x_M = x_N$$

and similarly, we have:

$$a_2 = b_2 \Leftrightarrow y_M = y_N$$

$$a_3 = b_3 \Leftrightarrow z_M = z_N$$

It follows that

$$\vec{AB} = \vec{CD} \Leftrightarrow M = N \Leftrightarrow$$

$$\Leftrightarrow x_M = x_N \wedge y_M = y_N \wedge z_M = z_N$$

$$\Leftrightarrow a_1 = b_1 \wedge a_2 = b_2 \wedge a_3 = b_3$$

$$\Leftrightarrow (a_1, a_2, a_3) = (b_1, b_2, b_3)$$

□

## ▼ Vector operations

Vector operations are defined in terms of a particular coordinate system but result in a vector or number that is independent of our choice of coordinate system.

### ① → Vector addition/subtraction

Def: Let  $u, v \in \mathbb{R}^3$  be two vectors with  $u = (u_1, u_2, u_3)$  and  $v = (v_1, v_2, v_3)$  in some coordinate system.

We define the vectors  $u+v$  and  $u-v$  such that

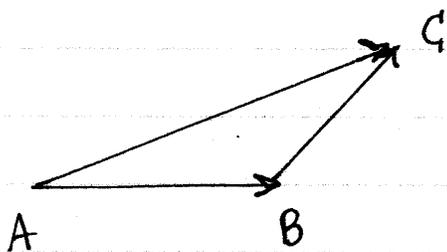
$$u+v = (u_1+v_1, u_2+v_2, u_3+v_3)$$

$$u-v = (u_1-v_1, u_2-v_2, u_3-v_3)$$

The following statement shows that the result of adding two vectors is independent of the choice of coordinate system.

Prop: Given three points  $A, B, C$ :

$$\vec{AB} + \vec{BC} = \vec{AC}$$



## Proof

$$\begin{aligned}\vec{AB} + \vec{BC} &= (x_B - x_A, y_B - y_A, z_B - z_A) + (x_C - x_B, y_C - y_B, z_C - z_B) \\ &= (x_B - x_A + x_C - x_B, y_B - y_A + y_C - y_B, z_B - z_A + z_C - z_B) = \\ &= (x_C - x_A, y_C - y_A, z_C - z_A) = \\ &= \vec{AC} \quad \square\end{aligned}$$

## ► Properties of vector addition

$$\forall u, v \in \mathbb{R}^3 : u + v = v + u$$

(Commutative)

$$\forall u, v, w \in \mathbb{R}^3 : u + (v + w) = (u + v) + w$$

(Associative)

$$\forall u \in \mathbb{R}^3 : u + \mathbf{0} = u$$

(Neutral element)

## ② → Scalar multiplication

Def : Let  $\lambda \in \mathbb{R}$  and let  $u = (u_1, u_2, u_3) \in \mathbb{R}^3$  be a vector represented in some coordinate system. We define the scalar  $\lambda u \in \mathbb{R}^3$  such that

$$\lambda u = (\lambda u_1, \lambda u_2, \lambda u_3)$$

We also define:

$$-u = (-1)u = (-u_1, -u_2, -u_3)$$

▷ Properties of scalar multiplication

1)  $-u$  additive inverse of  $u$

$$\forall u \in \mathbb{R}^3 : u + (-u) = \mathbf{0}$$

2) Distributive over a vector sum

$$\forall \lambda \in \mathbb{R} : \forall u, v \in \mathbb{R}^3 : \lambda(u+v) = \lambda u + \lambda v$$

3) Distributive over a scalar sum

$$\forall \lambda, \mu \in \mathbb{R} : \forall u \in \mathbb{R}^3 : (\lambda + \mu)u = \lambda u + \mu u$$

4) Associative property on a mixed product

$$\forall \lambda, \mu \in \mathbb{R} : \forall u \in \mathbb{R}^3 : (\lambda\mu)u = \lambda(\mu u) = \mu(\lambda u)$$

## EXAMPLES

a) Let  $u = (1 + \sqrt{2}, 2 - \sqrt{2}, 3)$  and  $v = (1 - \sqrt{2}, 3 - 2\sqrt{2}, 1)$  and define  $p = u + v$  and  $q = u - v$ . Evaluate the vector  $w = 2p - 3q - u$

Solution

$$\begin{aligned} w &= 2p - 3q - u = 2(u + v) - 3(u - v) - u = \\ &= 2u + 2v - 3u + 3v - u = (2 - 3 - 1)u + (2 + 3)v = \\ &= -2u + 5v \\ &= -2(1 + \sqrt{2}, 2 - \sqrt{2}, 3) + 5(1 - \sqrt{2}, 3 - 2\sqrt{2}, 1) = \\ &= (-2 - 2\sqrt{2}, -4 + 2\sqrt{2}, -6) + (5 - 5\sqrt{2}, 15 - 10\sqrt{2}, 5) \\ &= (-2 - 2\sqrt{2} + 5 - 5\sqrt{2}, -4 + 2\sqrt{2} + 15 - 10\sqrt{2}, -6 + 5) \\ &= (3 - 7\sqrt{2}, 11 - 8\sqrt{2}, -1) \end{aligned}$$

b) Prove:  $\forall \lambda, \mu \in \mathbb{R} : \forall u \in \mathbb{R}^3 : (\lambda + \mu)u = \lambda u + \mu u$

Solution

Let  $\lambda, \mu \in \mathbb{R}$  and  $u \in \mathbb{R}^3$  be given with  $u = (u_1, u_2, u_3)$ .

Then:

$$\begin{aligned} (\lambda + \mu)u &= (\lambda + \mu)(u_1, u_2, u_3) = \\ &= ((\lambda + \mu)u_1, (\lambda + \mu)u_2, (\lambda + \mu)u_3) = \\ &= (\lambda u_1 + \mu u_1, \lambda u_2 + \mu u_2, \lambda u_3 + \mu u_3) \\ &= (\lambda u_1, \lambda u_2, \lambda u_3) + (\mu u_1, \mu u_2, \mu u_3) = \\ &= \lambda(u_1, u_2, u_3) + \mu(u_1, u_2, u_3) = \lambda u + \mu u. \end{aligned}$$

### EXAMPLE

- ⑦ Let  $u = (1, 3, 2)$  and  $v = (-2, 1, 5)$  and define  $p = u + \sqrt{2}v$  and  $q = 2u - \sqrt{2}v$ . Evaluate the vectors  $w = 2p - q$  and  $x = p + 3q$ .
- ⑧ Let  $u = (1, -1, 3)$  and  $v = (2, 0, -1)$ , and define the vectors  $p = u + \sqrt{3}v$  and  $q = v - 2\sqrt{3}u$  and  $r = u + 2v$ . Evaluate the vectors
- a)  $w = p + q + r$                       c)  $y = p - \sqrt{3}q - \sqrt{3}r$   
b)  $x = 2p + \sqrt{3}q - r$                 d)  $z = \sqrt{3}p + 2q - 3\sqrt{3}r$
- ⑨ Prove the following properties of vector addition and scalar multiplication
- a)  $\forall u, v \in \mathbb{R}^3 : u + v = v + u$   
b)  $\forall u, v, w \in \mathbb{R}^3 : u + (v + w) = (u + v) + w$   
d)  $\forall \lambda \in \mathbb{R} : \forall u, v \in \mathbb{R}^3 : \lambda(u + v) = \lambda u + \lambda v$   
e)  $\forall \lambda, \mu \in \mathbb{R} : \forall u \in \mathbb{R}^3 : (\lambda\mu)u = \lambda(\mu u)$ .

### ③ → Scalar Product

Def : Let  $u, v \in \mathbb{R}^3$  be two vectors with  
 $u = (u_1, u_2, u_3)$  and  $v = (v_1, v_2, v_3)$   
in some coordinate system. We define:

a) The dot product  $u \cdot v \in \mathbb{R}$

$$u \cdot v = u_1 v_1 + u_2 v_2 + u_3 v_3$$

b) The vector norm  $\|u\| \in \mathbb{R}$

$$\|u\| = \sqrt{u_1^2 + u_2^2 + u_3^2} = \sqrt{u \cdot u}$$

► Immediate properties of the dot product

$$\forall u, v \in \mathbb{R}^3 : u \cdot v = v \cdot u$$

$$\forall u, v, w \in \mathbb{R}^3 : u \cdot (v + w) = u \cdot v + u \cdot w$$

$$\forall \lambda \in \mathbb{R} : \forall u, v \in \mathbb{R}^3 : (\lambda u) \cdot v = u \cdot (\lambda v) = \lambda (u \cdot v)$$

$$\forall u \in \mathbb{R}^3 : \mathbf{0} \cdot u = 0$$

► Immediate properties of the vector norm

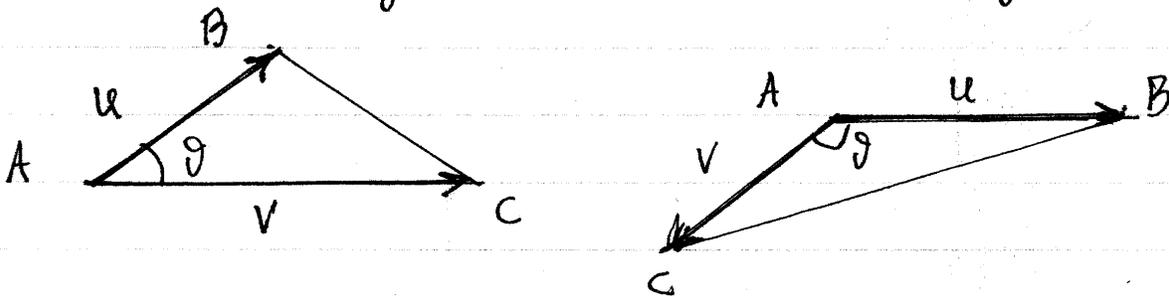
$$\forall u \in \mathbb{R}^3 : \|u\|^2 = u \cdot u$$

$$\forall \lambda \in \mathbb{R} : \forall u \in \mathbb{R}^3 : \|\lambda u\| = |\lambda| \|u\|$$

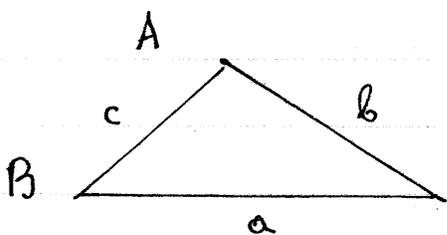
We will now use these properties to show that the dot product  $u \cdot v = u_1 v_1 + u_2 v_2 + u_3 v_3$  is independent of our choice of coordinate system.

## ► Geometric interpretation of the dot product

Def: Given two vectors  $u, v \in \mathbb{R}^3$  with  $u = \vec{AB}$  and  $v = \vec{AC}$ , we define the interior angle  $\vartheta(u, v)$  as the angle  $\vartheta(u, v) = \hat{A}$  of the triangle  $ABC$



Our main result is based on the law of cosines from Precalculus:



Define:  $a = BC \wedge b = CA \wedge c = AB$

$$\begin{cases} a^2 = b^2 + c^2 - 2bc \cos A \\ b^2 = c^2 + a^2 - 2ca \cos B \\ c^2 = a^2 + b^2 - 2ab \cos C \end{cases}$$

Thm:  $\forall u, v \in \mathbb{R}^3 : u \cdot v = \|u\| \|v\| \cos \vartheta(u, v)$

Proof

Let  $u = \vec{AB}$  and  $v = \vec{AC}$  for some points  $A, B, C$  and let  $\vartheta(u, v)$  be the interior angle of the vectors  $u, v$ .

For the triangle  $ABC$  we have

$$\begin{aligned} a = BC &= \|\vec{BC}\| = \|(\vec{AB} + \vec{BC}) - \vec{AB}\| = \|\vec{AC} - \vec{AB}\| = \\ &= \|v - u\| \end{aligned}$$

$$b = CA = \|\vec{AC}\| = \|v\|$$

$$c = AB = \|\vec{AB}\| = \|u\|$$

and therefore, from the law of cosines,

$$\cos \vartheta(u, v) = \cos \hat{A} = \frac{b^2 + c^2 - a^2}{2bc} = \frac{\|v\|^2 + \|u\|^2 - \|v-u\|^2}{2\|v\|\|u\|} =$$

$$= \frac{\|u\|^2 + \|v\|^2 - (v-u) \cdot (v-u)}{2\|u\|\|v\|} =$$

$$= \frac{\|u\|^2 + \|v\|^2 - v \cdot (v-u) + u \cdot (v-u)}{2\|u\|\|v\|} =$$

$$= \frac{\|u\|^2 + \|v\|^2 - v \cdot v + v \cdot u + u \cdot v - u \cdot u}{2\|u\|\|v\|}$$

$$= \frac{\|u\|^2 + \|v\|^2 - \|v\|^2 + u \cdot v + u \cdot v - \|u\|^2}{2\|u\|\|v\|}$$

$$= \frac{2u \cdot v}{2\|u\|\|v\|} = \frac{u \cdot v}{\|u\|\|v\|} \Rightarrow$$

$$\Rightarrow u \cdot v = \|u\|\|v\| \cos \vartheta(u, v).$$

□

► Triangle inequalities.

$$1) \boxed{\forall u, v \in \mathbb{R}^3: |u \cdot v| \leq \|u\| \|v\|}$$

Proof

Let  $u, v \in \mathbb{R}^3$  be given. Then

$$\begin{aligned} |u \cdot v| &= |\|u\| \|v\| \cos \vartheta(u, v)| = [ \|u\| \|v\| ] |\cos \vartheta(u, v)| \\ &= \|u\| \|v\| |\cos \vartheta(u, v)| \leq \|u\| \|v\|. \quad \square \end{aligned}$$

$$2) \boxed{\forall u, v \in \mathbb{R}^3: \|u+v\| \leq \|u\| + \|v\|}$$

Proof

Let  $u, v \in \mathbb{R}^3$  be given. Then:

$$\begin{aligned} \|u+v\|^2 &= (u+v) \cdot (u+v) = u \cdot (u+v) + v \cdot (u+v) = \\ &= u \cdot u + u \cdot v + v \cdot u + v \cdot v = \\ &= \|u\|^2 + u \cdot v + u \cdot v + \|v\|^2 = \\ &= \|u\|^2 + 2u \cdot v + \|v\|^2 = \\ &= \|u\|^2 + 2\|u\| \|v\| \cos \vartheta(u, v) + \|v\|^2 \leq \\ &\leq \|u\|^2 + 2\|u\| \|v\| + \|v\|^2 = (\|u\| + \|v\|)^2 \end{aligned}$$

$$\Rightarrow 0 \leq \|u+v\|^2 \leq (\|u\| + \|v\|)^2 \Rightarrow$$

$$\Rightarrow \|u+v\| \leq \|u\| + \|v\| \quad \square$$

## EXERCISES

⑩ Let  $u = (1 + \sqrt{2}, 1 - \sqrt{2}, \sqrt{2})$  and  $v = (\sqrt{2} + 2, 2 + 3\sqrt{2}, 1 + \sqrt{2})$  be given.

a) Evaluate  $u \cdot v$ ,  $\|u\|$ ,  $\|v\|$

b) Use the previous results to calculate

1)  $(2u - v) \cdot (u + 3v)$       3)  $(u \cdot v + \|u\|)v$

2)  $[v \cdot (u + v)] \|u\|$       4)  $[3\|u\|v] \cdot (u - 2v)$

⑪ Find the interior angle  $\vartheta(u, v)$  between the vectors

a)  $u = (1, 0, 3)$  and  $v = (2, 1, 0)$

b)  $u = (\sqrt{2}, 1 - \sqrt{2}, 0)$  and  $v = (\sqrt{2}, 1 + \sqrt{2}, 1)$

c)  $u = (1 + \sqrt{3}, 1 - \sqrt{3}, \sqrt{3})$  and  $v = (1 - \sqrt{3}, 1 + \sqrt{3}, -\sqrt{3})$

⑫ Let  $\hat{ABC}$  be a triangle with  $A(1, 2, 3)$ ,  $B(-4, 5, 6)$ ,  $C(1, 0, 1)$ . Evaluate  $\cos \hat{A}$ ,  $\cos \hat{B}$ ,  $\cos \hat{C}$ .

⑬ Show that

a)  $\|u + v\|^2 + \|u - v\|^2 = 2(\|u\|^2 + \|v\|^2)$

b)  $4(u \cdot v) = \|u + v\|^2 - \|u - v\|^2$

⑭ Prove the following properties

a)  $\forall u, v, w \in \mathbb{R}^3 : u \cdot (v + w) = u \cdot v + u \cdot w$

b)  $\forall \lambda \in \mathbb{R} : \forall u, v \in \mathbb{R}^3 : (\lambda u) \cdot v = \lambda(u \cdot v)$

c)  $\forall \lambda \in \mathbb{R} : \forall u \in \mathbb{R}^3 : \|\lambda u\| = |\lambda| \|u\|$

## Orthogonality condition

Def: Let  $u, v \in \mathbb{R}^3 - \{0\}$  be two vectors. We say that  
 $u \perp v \Leftrightarrow \vartheta(u, v) = \pi/2$

Terminology:

$u \perp v$  reads:  $u$  is orthogonal to  $v$ .



Prop:  $\forall u, v \in \mathbb{R}^3 - \{0\} : u \perp v \Leftrightarrow u \cdot v = 0$

Proof

Since

$$\cos \vartheta(u, v) = \frac{\|u\| \|v\| \cos \vartheta(u, v)}{\|u\| \|v\|} = \frac{u \cdot v}{\|u\| \|v\|}$$

it follows that

$$\begin{aligned} u \perp v &\Leftrightarrow \vartheta(u, v) = \pi/2 \Leftrightarrow \cos \vartheta(u, v) = 0 \Leftrightarrow \\ &\Leftrightarrow \frac{u \cdot v}{\|u\| \|v\|} = 0 \Leftrightarrow u \cdot v = 0 \quad \square \end{aligned}$$

### EXAMPLE

Find all  $x \in \mathbb{R}$  such that  $u = (0, x, x+1)$  and  $v = (x, x-1, x-2)$  are orthogonal.

Solution

Since,

$$\begin{aligned} u \cdot v &= u_1 v_1 + u_2 v_2 + u_3 v_3 = \\ &= 0x + x(x-1) + (x+1)(x-2) = \\ &= x^2 - x + x^2 + (1-2)x + 1 \cdot (-2) = \\ &= x^2 - x + x^2 - x - 2 = 2x^2 - 2x - 2 \end{aligned}$$

it follows that

$$\begin{aligned} u \perp v &\Leftrightarrow u \cdot v = 0 \Leftrightarrow 2x^2 - 2x - 2 = 0 \Leftrightarrow \\ &\Leftrightarrow x^2 - x - 1 = 0 \end{aligned}$$

From the quadratic formula

$$\begin{aligned} (a, b, c) &= (1, -1, -1) \Rightarrow \Delta = b^2 - 4ac = (-1)^2 - 4 \cdot 1 \cdot (-1) = \\ &= 1 + 4 = 5 \Rightarrow \end{aligned}$$

$$\Rightarrow x_{1,2} = \frac{-b \pm \sqrt{\Delta}}{2a} = \frac{-(-1) \pm \sqrt{5}}{2 \cdot 1} = \frac{1 \pm \sqrt{5}}{2}$$

and therefore

$$u \perp v \Leftrightarrow x = \frac{1 + \sqrt{5}}{2} \vee x = \frac{1 - \sqrt{5}}{2}$$

### EXAMPLE

Let  $u, v \in \mathbb{R}^3$ . Show that

$$u+v \perp u-2v \Rightarrow u \cdot v = \|u\|^2 - 2\|v\|^2$$

Solution

Assume that  $u+v \perp u-2v$ . Since

$$\begin{aligned}(u+v) \cdot (u-2v) &= u \cdot (u-2v) + v \cdot (u-2v) = \\ &= u \cdot u + u \cdot (-2v) + v \cdot u + v \cdot (-2v) = \\ &= \|u\|^2 - 2(u \cdot v) + u \cdot v - 2\|v\|^2 = \\ &= \|u\|^2 - u \cdot v - 2\|v\|^2\end{aligned}$$

it follows that

$$\begin{aligned}u+v \perp u-2v &\Rightarrow (u+v) \cdot (u-2v) = 0 \Rightarrow \\ &\Rightarrow \|u\|^2 - u \cdot v - 2\|v\|^2 = 0 \Rightarrow \\ &\Rightarrow u \cdot v = \|u\|^2 - 2\|v\|^2\end{aligned}$$

## EXERCISES

(15) Find all  $a \in \mathbb{R}$  such that  $u \perp v$  when

a)  $u = (a+1, a, a-1)$  and  $v = (3, 1, 2)$

b)  $u = (a^2-1, 3, a+1)$  and  $v = (2, a+2, a)$

c)  $u = (a, 3a+1, 2a-3)$  and  $v = (3, a, a-1)$

(16) Let  $u = (a-1, a+1, 2)$  and  $v = (2, 0, a)$  be given.

Find all  $a \in \mathbb{R}$  such that

a)  $u \perp v$

c)  $u-v \perp u+v$

b)  $u \perp (2u+3v)$

d)  $2u+v \perp u+2v$

(Hint: It is useful to precalculate  $\|u\|^2$ ,  $\|v\|^2$ ,  $u \cdot v$ , before doing any of the subquestions).

(17) Let  $v = (1, -2, -3)$  and  $w = (-3, 2, 0)$ . Find all vectors  $u \in \mathbb{R}^3$  such that  $u \perp v$  and  $u \perp w$ .

(Hint: You will find that

$$u \perp v \wedge u \perp w \Leftrightarrow u \in \{tp \mid t \in \mathbb{R}\}$$

for some  $p \in \mathbb{R}^3$ .)

(18) Let  $u = (x, 0, 1)$ ,  $v = (0, 2, y)$ , and  $w = (1, z, 1)$ .

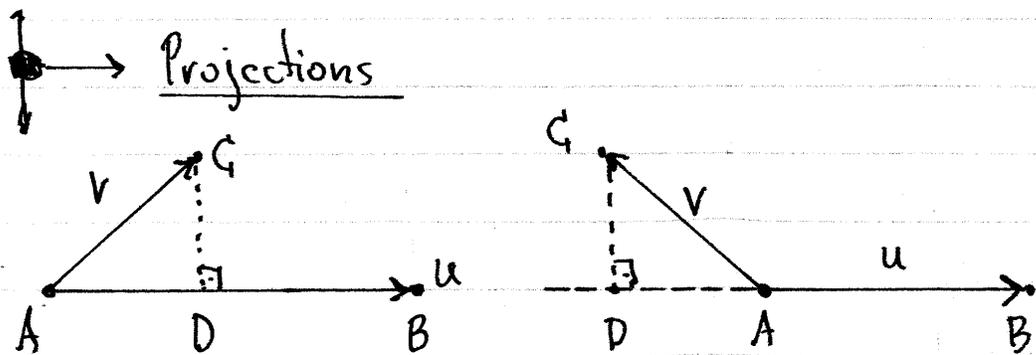
Find all  $x, y, z \in \mathbb{R}$  such that  $u \perp v \wedge v \perp w \wedge w \perp u$ .

(19) Show that

a)  $u \perp v \wedge u \perp w \Rightarrow \forall a, b \in \mathbb{R}: u \perp (av + bw)$

b)  $u + v \perp u - v \Rightarrow \|u\| = \|v\|$

c)  $\left. \begin{array}{l} u + v \perp u - w \\ u \perp v \wedge u \perp w \end{array} \right\} \Rightarrow \|u\|^2 = v \cdot w$



Def: Let  $u, v \in \mathbb{R}^3 - \{0\}$  be two vectors and write  $u = \vec{AB}$  and  $v = \vec{AC}$ . Let  $(l)$  be the line defined by  $A, B$  and choose the unique  $D \in (l)$  such that  $CD \perp AB$ . Then, we define

a) The projection of  $v$  onto  $u$ :

$$\text{proj}_u(v) = \vec{AD}$$

b) The component  $\text{comp}_u(v)$  of  $v$  onto  $u$ :

$$\text{proj}_u(v) = \left[ \text{comp}_u(v) \right] \frac{u}{\|u\|}$$

The dot product can be used to calculate both the projection and the component of  $v$  onto  $u$ :

Prop:  $\forall u, v \in \mathbb{R}^3 - \{0\} : \text{proj}_u(v) = \frac{u \cdot v}{\|u\|^2} u$

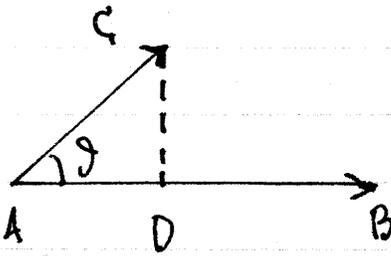
$$\forall u, v \in \mathbb{R}^3 - \{0\} : \text{comp}_u(v) = \frac{u \cdot v}{\|u\|}$$

## Proof

Let  $u, v \in \mathbb{R}^3 - \{0\}$  be given and let  $\vartheta = \vartheta(u, v)$ .

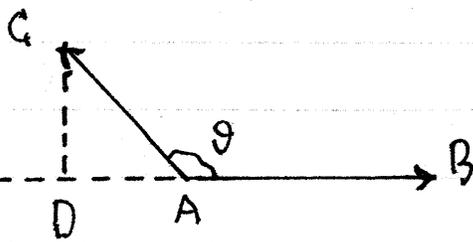
We distinguish between the following cases:

Case 1: Assume  $0 \leq \vartheta \leq \pi/2$ . Then



$$\begin{aligned} \text{proj}_u(v) &= \vec{AD} = AD \left[ \frac{1}{AB} \vec{AB} \right] = \\ &= \frac{AC \cos \vartheta}{AB} \vec{AB} = \end{aligned}$$

Case 2: Assume that  $\pi/2 < \vartheta \leq \pi$ . Then



$$\begin{aligned} \text{proj}_u(v) &= \vec{AD} = AD \left[ \frac{-1}{AB} \vec{AB} \right] = \\ &= \frac{-AC \cos(\pi - \vartheta)}{AB} \vec{AB} = \\ &= \frac{-AC [-\cos(-\vartheta)]}{AB} : \vec{AB} = \\ &= \frac{AC \cos(-\vartheta)}{AB} \vec{AB} = \\ &= \frac{AC \cos \vartheta}{AB} \vec{AB} = \end{aligned}$$

In both cases, we have:

$$\begin{aligned} \text{proj}_u(v) &= \frac{AC \cos \vartheta}{AB} \vec{AB} = \frac{\|\vec{AC}\| \cos \vartheta}{\|\vec{AB}\|} \vec{AB} = \\ &= \frac{\|v\| \cos \vartheta}{\|u\|} u = \frac{\|u\| \|v\| \cos \vartheta}{\|u\|^2} u = \\ &= \frac{u \cdot v}{\|u\|^2} u \end{aligned}$$

Furthermore,

$$\begin{aligned} \text{proj}_u(v) &= \frac{u \cdot v}{\|u\|^2} u = \frac{u \cdot v}{\|u\|} \frac{u}{\|u\|} = \\ &= \text{comp}_u(v) \frac{u}{\|u\|} \Rightarrow \end{aligned}$$

$$\Rightarrow \text{comp}_u(v) = \frac{u \cdot v}{\|u\|}$$

## EXAMPLES

a) Let  $u = (x-1, 2, 0)$  and  $v = (1, 2x+1, 3)$ .  
Evaluate  $\text{proj}_u(v)$  and  $\text{comp}_u(v)$ .

Solution

Since

$$\begin{aligned}u \cdot v &= (x-1, 2, 0) \cdot (1, 2x+1, 3) = \\&= (x-1) \cdot 1 + 2(2x+1) + 0 \cdot 3 = \\&= x-1 + 4x+2 = 5x+1\end{aligned}$$

and

$$\begin{aligned}\|u\|^2 &= u \cdot u = (x-1, 2, 0) \cdot (x-1, 2, 0) = \\&= (x-1)(x-1) + 2 \cdot 2 + 0 \cdot 0 = (x-1)^2 + 4\end{aligned}$$

then

$$\begin{aligned}\text{proj}_u(v) &= \frac{u \cdot v}{\|u\|^2} u = \frac{5x+1}{(x-1)^2 + 4} (x-1, 2, 0) = \\&= \left( \frac{(5x+1)(x-1)}{(x-1)^2 + 4}, \frac{2(5x+1)}{(x-1)^2 + 4}, 0 \right)\end{aligned}$$

and

$$\text{comp}_u(v) = \frac{u \cdot v}{\|u\|} = \frac{5x+1}{\sqrt{(x-1)^2 + 4}}$$

b) Let  $u, v \in \mathbb{R}^3 - \{0\}$ . Show that  $\text{proj}_{(au)}(v) = \text{proj}_u(v)$ .

Solution

$$\begin{aligned}\text{proj}_{(au)}(v) &= \frac{(au) \cdot v}{\|au\|^2} (au) = \frac{a(u \cdot v)}{[|a| \|u\|]^2} (au) = \\ &= \frac{a^2 (u \cdot v)}{|a|^2 \|u\|^2} u = \frac{a^2 (u \cdot v)}{a^2 \|u\|^2} u = \\ &= \frac{u \cdot v}{\|u\|^2} u = \text{proj}_u(v).\end{aligned}$$

## EXERCISES

20) Let  $u, v, w \in \mathbb{R}^3 - \{0\}$ . Show that

a)  $\text{proj}_u(v+w) = \text{proj}_u(v) + \text{proj}_u(w)$

b)  $\forall a \in \mathbb{R}: \text{proj}_u(av) = a \text{proj}_u(v)$

c)  $\forall a \in \mathbb{R} - \{0\}: \text{proj}_{(au)}(v) = \text{proj}_u(v)$

d)  $u \perp v \Rightarrow \text{proj}_u(v) = 0$

e)  $\forall a \in \mathbb{R} - \{0\}: \text{comp}_{(au)}(v) = (a/|a|) \text{comp}_u(v)$

f)  $\text{comp}_u(u) = \|u\|$

g)  $\text{proj}_u(u) = u$

#### ④ → Cross-product

The cross-product can only be defined between 3D vectors, as follows:

Def: Let  $u, v \in \mathbb{R}^3$  with  $u = (u_1, u_2, u_3)$  and  $v = (v_1, v_2, v_3)$ . We define the cross-product  $u \times v$  such that

$$(u \times v)_1 = u_2 v_3 - u_3 v_2$$

$$(u \times v)_2 = u_3 v_1 - u_1 v_3$$

$$(u \times v)_3 = u_1 v_2 - u_2 v_1$$

An alternate practical definition of the cross-product is using  $3 \times 3$  determinants. Recall that a  $3 \times 3$  determinant can be evaluated via the Sarrus rule as follows:

$$\begin{vmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix} = \begin{vmatrix} a_1 & a_2 \\ b_1 & b_2 \\ c_1 & c_2 \end{vmatrix} = a_1 b_2 c_3 + a_2 b_3 c_1 + a_3 b_1 c_2 - a_3 b_2 c_1 - a_1 b_3 c_2 - a_2 b_1 c_3$$

We define the unit vectors

$$e_1 = (1, 0, 0), \quad e_2 = (0, 1, 0), \quad e_3 = (0, 0, 1)$$

noting that in general any vector can be written as:

$$u = (u_1, u_2, u_3) = u_1 e_1 + u_2 e_2 + u_3 e_3$$

It can be shown that

$$\begin{aligned} u \times v &= (u_1, u_2, u_3) \times (v_1, v_2, v_3) = \\ &= \begin{vmatrix} e_1 & e_2 & e_3 \\ u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \end{vmatrix} \end{aligned}$$

In terms of unit vectors, we can show that

$e_1 \times e_2 = -e_2 \times e_1 = e_3$	$e_1 \times e_1 = 0$
$e_2 \times e_3 = -e_3 \times e_2 = e_1$	$e_2 \times e_2 = 0$
$e_3 \times e_1 = -e_1 \times e_3 = e_2$	$e_3 \times e_3 = 0$

### EXAMPLE

Evaluate  $u \times v$  with  $u = (1, 3, 4)$  and  $v = (2, 1, 1)$ .

Solution

$$u \times v = (1, 3, 4) \times (2, 1, 1) =$$

$$= \begin{vmatrix} e_1 & e_2 & e_3 & | & e_1 & e_2 \\ 1 & 3 & 4 & | & 1 & 3 \\ 2 & 1 & 1 & | & 2 & 1 \end{vmatrix} =$$

$$= e_1 3 \cdot 1 + e_2 4 \cdot 2 + e_3 1 \cdot 1 - e_1 4 \cdot 1 - e_2 1 \cdot 1 - e_3 3 \cdot 2$$

$$= 3e_1 + 8e_2 + e_3 - 4e_1 - e_2 - 6e_3 =$$

$$= (3-4)e_1 + (8-1)e_2 + (1-6)e_3 =$$

$$= -e_1 + 7e_2 - 5e_3 = (-1, 7, -5)$$

## ► Norm of the cross-product

$$\text{Thm: } \forall u, v \in \mathbb{R}^3 : \|u \times v\| = \|u\| \|v\| \sin \vartheta(u, v)$$

The proof of this result is based on the Lagrange identity, which reads:

$$\begin{aligned} (a_1^2 + a_2^2 + a_3^2)(b_1^2 + b_2^2 + b_3^2) - (a_1 b_1 + a_2 b_2 + a_3 b_3)^2 &= \\ = \begin{vmatrix} a_1 & a_2 \\ b_1 & b_2 \end{vmatrix}^2 + \begin{vmatrix} a_2 & a_3 \\ b_2 & b_3 \end{vmatrix}^2 + \begin{vmatrix} a_3 & a_1 \\ b_3 & b_1 \end{vmatrix}^2 \end{aligned}$$

### Proof

Let  $u, v \in \mathbb{R}^3$  be given. Then; for  $\vartheta = \vartheta(u, v)$ , we have:

$$\begin{aligned} \|u \times v\|^2 &= \|(u_1, u_2, u_3) \times (v_1, v_2, v_3)\|^2 = \\ &= \|(u_2 v_3 - u_3 v_2, u_3 v_1 - u_1 v_3, u_1 v_2 - u_2 v_1)\|^2 \\ &= (u_2 v_3 - u_3 v_2)^2 + (u_3 v_1 - u_1 v_3)^2 + (u_1 v_2 - u_2 v_1)^2 = \\ &= \begin{vmatrix} u_2 & u_3 \\ v_2 & v_3 \end{vmatrix}^2 + \begin{vmatrix} u_3 & u_1 \\ v_3 & v_1 \end{vmatrix}^2 + \begin{vmatrix} u_1 & u_2 \\ v_1 & v_2 \end{vmatrix}^2 = \\ &= (u_1^2 + u_2^2 + u_3^2)(v_1^2 + v_2^2 + v_3^2) - (u_1 v_1 + u_2 v_2 + u_3 v_3)^2 \\ &= \|u\|^2 \|v\|^2 - (u \cdot v)^2 = \\ &= \|u\|^2 \|v\|^2 - [\|u\| \|v\| \cos \vartheta]^2 = \\ &= \|u\|^2 \|v\|^2 - \|u\|^2 \|v\|^2 \cos^2 \vartheta = \\ &= \|u\|^2 \|v\|^2 (1 - \cos^2 \vartheta) = \|u\|^2 \|v\|^2 \sin^2 \vartheta \end{aligned}$$

and since  $\vartheta \in [0, \pi] \Rightarrow \sin \vartheta \geq 0$ .

It follows that

$$\begin{aligned}\|u \times v\| &= \sqrt{\|u\|^2 \|v\|^2 \sin^2 \theta} = \sqrt{[\|u\| \|v\| \sin \theta]^2} = \\ &= |\|u\| \|v\| \sin \theta| = \|u\| \|v\| |\sin \theta| = \\ &= \|u\| \|v\| \sin \theta.\end{aligned}$$

□

### ► Algebraic properties of the cross product

We can show that the cross-product satisfies the following properties:

$$\forall u \in \mathbb{R}^3: u \times u = \mathbf{0}$$

$$\forall u, v \in \mathbb{R}^3: u \times v = -v \times u$$

$$\forall u, v \in \mathbb{R}^3: \forall \lambda \in \mathbb{R}: (\lambda u) \times v = u \times (\lambda v) = \lambda (u \times v)$$

$$\forall u, v, w \in \mathbb{R}^3: \begin{cases} u \times (v+w) = u \times v + u \times w \\ (v+w) \times u = v \times u + w \times u \end{cases}$$

$$\forall u, v, w \in \mathbb{R}^3: u \cdot (v \times w) = v \cdot (w \times u) = w \cdot (u \times v)$$

$$\forall u, v, w \in \mathbb{R}^3: u \times (v \times w) = (u \cdot w)v - (u \cdot v)w$$

To prove these properties we use tensor notation, as follows:

a)  $u_a$  with  $a \in \{1, 2, 3\}$  will represent the  $a^{\text{th}}$  component of the vector  $u$

b) Repeating indices are automatically summed over all components when associated with

a product

e.g.  $u_a v_a = u_1 v_1 + u_2 v_2 + u_3 v_3$  (dot product)

However, for the vector sum  $u+v$  we write

$$(u+v)_a = u_a + v_a$$

and no summation over  $a \in \{1, 2, 3\}$  is implied.

c) We define the Levi-Civita tensor  $\epsilon_{abc}$ :

$$\epsilon_{abc} = \frac{1}{2} (a-b)(b-c)(c-a) = \begin{cases} +1, & \text{if } (a,b,c) \in \{(1,2,3), (2,3,1), (3,1,2)\} \\ -1, & \text{if } (a,b,c) \in \{(3,2,1), (2,1,3), (1,3,2)\} \\ 0, & \text{if } a=b \vee b=c \vee c=a \end{cases}$$

and note that the cross-product definition can be rewritten as:

$$(u \times v)_a = \epsilon_{abc} u_b v_c$$

where summation is implied over  $b, c$ .

d) We define the Kronecker tensor  $\delta_{ab}$  as

$$\delta_{ab} = \begin{cases} 1, & \text{if } a=b \\ 0, & \text{if } a \neq b \end{cases}$$

and note the following basic properties:

$$1) \quad \begin{cases} \delta_{ab} u_b = u_a \\ \epsilon_{abc} u_b u_c = 0_a \end{cases}$$

$$2) \quad \begin{cases} \epsilon_{abc} = \epsilon_{bca} = \epsilon_{cab} \\ \epsilon_{abc} = -\epsilon_{cba} \end{cases}$$

3) Relation to Kronecker delta

$$\epsilon_{abc} \epsilon_{pqr} = \begin{vmatrix} \delta_{ap} & \delta_{aq} & \delta_{ar} \\ \delta_{bp} & \delta_{bq} & \delta_{br} \\ \delta_{cp} & \delta_{cq} & \delta_{cr} \end{vmatrix}$$

4) Contracted epsilon identities

$$\begin{aligned} \epsilon_{abc} \epsilon_{apq} &= \delta_{bp} \delta_{cq} - \delta_{bq} \delta_{cp} \\ \epsilon_{abp} \epsilon_{abq} &= 2\delta_{pq} \\ \epsilon_{abc} \epsilon_{abc} &= 6 \end{aligned}$$

Note that (4) is consequence of (3). All properties of the cross-product are consequences of (1), (2), (3), (4).

### EXAMPLE

a) Prove  $u \times (v + w) = u \times v + u \times w$

Proof

$$\begin{aligned} [u \times (v + w)]_a &= \varepsilon_{abc} u_b (v + w)_c \\ &= \varepsilon_{abc} u_b (v_c + w_c) = \\ &= \varepsilon_{abc} u_b v_c + \varepsilon_{abc} u_b w_c = \\ &= (u \times v)_a + (u \times w)_a = \\ &= (u \times v + u \times w)_a \Rightarrow \end{aligned}$$

$$\Rightarrow u \times (v + w) = u \times v + u \times w.$$

b) Prove  $u \cdot (v \times w) = v \cdot (w \times u)$

Proof

$$\begin{aligned} u \cdot (v \times w) &= u_a (v \times w)_a = u_a \varepsilon_{abc} v_b w_c = \\ &= v_b \varepsilon_{abc} w_c u_a = v_b \varepsilon_{bca} w_c u_a = \\ &= v_b (w \times u)_b = v \cdot (w \times u) \end{aligned}$$

c) Prove  $u \times (v \times w) = (u \cdot w)v - (u \cdot v)w$

Proof

$$\begin{aligned} [u \times (v \times w)]_a &= \varepsilon_{abc} u_b (v \times w)_c = \\ &= \varepsilon_{abc} u_b \varepsilon_{cpq} v_p w_q = \\ &= \varepsilon_{cab} \varepsilon_{cpq} u_b v_p w_q = \end{aligned}$$

$$\begin{aligned}
&= (\delta_{ap}\delta_{bq} - \delta_{aq}\delta_{bp}) u_b v_p w_q = \\
&= (\delta_{ap} v_p) (\delta_{bq} w_q) u_b - (\delta_{aq} w_q) (\delta_{bp} v_p) u_b \\
&= u_b v_a w_b - u_b v_b w_a = \\
&= (u \cdot w) v_a - (u \cdot v) w_a = \\
&= [(u \cdot w)v]_a - [(u \cdot v)w]_a = \\
&= [(u \cdot w)v - (u \cdot v)w]_a
\end{aligned}$$

d) Let  $u, v, w \in \mathbb{R}^3$  with  $\|u\| = 4$ ,  $\|v\| = \sqrt{5}$ ,  $\|w\| = 1 + \sqrt{2}$ ,  
 $\vartheta(u, w) = \pi/6$ , and  $\vartheta(v, w \times u) = \pi/4$ .

Evaluate  $u \cdot (v \times w)$ .

Solution

$$\begin{aligned}
u \cdot (v \times w) &= v \cdot (w \times u) = \|v\| \|w \times u\| \cos \vartheta(v, w \times u) = \\
&= \|v\| [\|w\| \|u\| \sin \vartheta(u, w)] \cos \vartheta(v, w \times u) = \\
&= \sqrt{5} [(1 + \sqrt{2}) 4 \sin(\pi/6)] \cos(\pi/4) = \\
&= \sqrt{5} [(1 + \sqrt{2}) 4 (1/2)] (\sqrt{2}/2) = \\
&= \sqrt{2} \sqrt{5} (1 + \sqrt{2}) = \sqrt{5} (\sqrt{2} + 2).
\end{aligned}$$

## EXERCISES

21) Let  $u = (\sqrt{2}, \sqrt{2} + \sqrt{3}, 1)$ , and  $v = (2, \sqrt{3}, \sqrt{2})$ , and  $w = (1, \sqrt{2}, \sqrt{3})$  be given. Evaluate the following:

- a)  $u \times v$                       c)  $u \cdot (v \times w)$   
b)  $u \times (v + w)$             d)  $u \times (v \times w)$

22) Let  $u = (x, 2y - 1, 1)$ ,  $v = (2, 1, z)$ , and  $w = (1, 1, 2)$ . Find all  $x, y, z \in \mathbb{R}$  such that  $u \times (v \times w) = \mathbf{0}$ . (Hint: Use the identity for  $u \times (v \times w)$  to expedite your calculations)

23) Let  $u, v \in \mathbb{R}^3$  with  $\|u\| = \|v\| = 1$ . Show that:  $(u \cdot v)^2 + \|u \times v\|^2 = 1$ .

24) Let  $u, v, w \in \mathbb{R}^3$  with  $\|u\| = 2$ ,  $\|v\| = 3$ , and  $\|w\| = 1$ . If the angle  $\varphi$  from  $u$  to  $v$  is  $\pi/4$ , and the angle  $\vartheta$  from  $w$  to  $u \times v$  is  $\pi/3$ , then show that:

- a)  $u \cdot v = 3\sqrt{2}$                       c)  $\|u \times v\| = 3\sqrt{2}$   
b)  $\|u + v\| = \sqrt{13 + 6\sqrt{2}}$             d)  $u \cdot (v \times w) = 3\sqrt{6}/2$

## ► Parallel vectors

Def: Let  $u, v \in \mathbb{R}^3 - \{0\}$  be two vectors. We say that  $u \parallel v \Leftrightarrow \exists a \in \mathbb{R}: u = av$

Thm:  $\forall u, v \in \mathbb{R}^3 - \{0\}: (u \parallel v \Leftrightarrow u \times v = 0)$

### Proof

Let  $u, v \in \mathbb{R}^3 - \{0\}$  be given.

( $\Rightarrow$ ): Assume that  $u \parallel v$ . Then

$$u \parallel v \Rightarrow \exists a \in \mathbb{R}: u = av$$

Choose  $a \in \mathbb{R}$  such that  $u = av$ . It follows that

$$u \times v = (av) \times v = a(v \times v) = a \cdot 0 = 0$$

( $\Leftarrow$ ): Assume that  $u \times v = 0$ , and define

$$u = (u_1, u_2, u_3) \text{ and } v = (v_1, v_2, v_3). \text{ Then:}$$

$$u \times v = 0 \Rightarrow (u_1, u_2, u_3) \times (v_1, v_2, v_3) = (0, 0, 0) \Rightarrow$$

$$\Rightarrow (u_2 v_3 - u_3 v_2, u_3 v_1 - u_1 v_3, u_1 v_2 - u_2 v_1) = (0, 0, 0) \Rightarrow$$

$$\Rightarrow \begin{cases} u_1 v_2 - u_2 v_1 = 0 \\ u_2 v_3 - u_3 v_2 = 0 \\ u_3 v_1 - u_1 v_3 = 0 \end{cases}$$

Since  $v \in \mathbb{R}^3 - \{0\} \Rightarrow v \neq 0 \Rightarrow v_1 \neq 0 \vee v_2 \neq 0 \vee v_3 \neq 0$

With no loss of generality, let us assume that  $v_1 \neq 0$

We choose an  $a \in \mathbb{R}$  such that  $u_1 = av_1$ . Then, it follows that:

$$u_1 v_2 - u_2 v_1 = 0 \Rightarrow a v_1 v_2 - u_2 v_1 = 0 \Rightarrow v_1 (a v_2 - u_2) = 0$$

$$\Rightarrow v_1 = 0 \vee a v_2 - u_2 = 0 \Rightarrow \underline{u_2 = a v_2}$$

and

$$u_3 v_1 - u_1 v_3 = 0 \Rightarrow u_3 v_1 - (a v_1) v_3 = 0 \Rightarrow v_1 (u_3 - a v_3) = 0$$

$$\Rightarrow v_1 = 0 \vee u_3 - a v_3 = 0 \Rightarrow \underline{u_3 = a v_3}$$

and therefore

$$u = (u_1, u_2, u_3) = (a v_1, a v_2, a v_3) = a (v_1, v_2, v_3) = a v$$

$$\Rightarrow (\exists a \in \mathbb{R} : u = a v) \Rightarrow u \parallel v.$$

### ▷ Scalar triple product

$$\forall u, v, w \in \mathbb{R}^3 : u \cdot (v \times w) = \begin{vmatrix} u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \\ w_1 & w_2 & w_3 \end{vmatrix}$$

Proof

$$\begin{aligned} u \cdot (v \times w) &= (u_1, u_2, u_3) \cdot [(v_1, v_2, v_3) \times (w_1, w_2, w_3)] = \\ &= (u_1, u_2, u_3) \cdot (v_2 w_3 - v_3 w_2, v_3 w_1 - v_1 w_3, v_1 w_2 - v_2 w_1) = \\ &= u_1 (v_2 w_3 - v_3 w_2) + u_2 (v_3 w_1 - v_1 w_3) + u_3 (v_1 w_2 - v_2 w_1) = \\ &= u_1 v_2 w_3 + u_2 v_3 w_1 + u_3 v_1 w_2 - u_3 v_2 w_1 - u_2 v_1 w_3 \\ &\quad - u_1 v_3 w_2 = \end{aligned}$$

$$= \begin{vmatrix} u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \\ w_1 & w_2 & w_3 \end{vmatrix}$$

► Vectors perpendicular to the same vector are parallel

**Thm**: Let  $u, v, w \in \mathbb{R}^3 - \{0\}$  be given. Then  
 $(u \perp w \wedge v \perp w) \Leftrightarrow w \parallel u \times v$

Proof

( $\Rightarrow$ ): Assume that  $u \perp w$  and  $v \perp w$ . Then:

$$\begin{cases} u \perp w \\ v \perp w \end{cases} \Rightarrow \begin{cases} u \cdot w = 0 \\ v \cdot w = 0 \end{cases} \Rightarrow$$

$$\begin{aligned} \Rightarrow w \times (u \times v) &= (w \cdot v)u - (w \cdot u)v = \\ &= (v \cdot w)u - (u \cdot w)v = \\ &= 0u - 0v = \mathbf{0} - \mathbf{0} = \mathbf{0} \Rightarrow \end{aligned}$$

$$\Rightarrow w \parallel u \times v.$$

( $\Leftarrow$ ): Assume that  $w \parallel u \times v$ . Then:

$$w \parallel u \times v \Rightarrow \exists \lambda \in \mathbb{R} : w = \lambda (u \times v)$$

Choose an  $\lambda \in \mathbb{R}$  such that  $w = \lambda (u \times v)$ .

It follows that:

$$\begin{aligned} u \cdot w &= u \cdot [\lambda (u \times v)] = \lambda [u \cdot (u \times v)] = \\ &= \lambda [v \cdot (u \times u)] = \lambda (v \cdot \mathbf{0}) \\ &= \lambda \mathbf{0} = 0 \Rightarrow u \perp w \end{aligned}$$

and

$$\begin{aligned} v \cdot w &= v \cdot [\lambda (u \times v)] = \lambda [v \cdot (u \times v)] = \lambda [u \cdot (v \times v)] \\ &= \lambda (u \cdot \mathbf{0}) = \lambda \mathbf{0} = 0 \Rightarrow v \perp w \end{aligned}$$

and therefore:  $u \perp w \wedge v \perp w$ .

## EXERCISES

95) Use the cross-product to find the set of all vectors  $u$  such that  $u \perp v$  and  $u \perp w$ , for  $v = (1, 2, 3)$  and  $w = (-2, 2, -4)$ .

96) Let  $u, v, w \in \mathbb{R}^3$  be given. Show that:

a)  $u \parallel v \wedge v \parallel w \Rightarrow u \parallel w$

b)  $u \parallel v \wedge u \parallel w \Rightarrow u \parallel (v+w)$

c)  $u \cdot (u \times v) = 0$

d)  $u \perp v \Rightarrow u \times (u \times v) = -\|u\|^2 v$

e)  $(u \times v) \times (v \times w) = [(w \times u) \cdot v] v$

f)  $u \times (v \times w) + v \times (w \times u) + w \times (u \times v) = \mathbf{0}$

g)  $(a \times b) \cdot (c \times d) = (a \cdot c)(b \cdot d) - (b \cdot c)(a \cdot d)$

h)  $(u-v) \times (u+v) = 2(u \times v)$

## ▼ Lines in $\mathbb{R}^3$

Let  $O$  be the origin of our coordinate system.

- Def: The parametric equation for a line  $(\ell)$  going through the points  $A, B$  is:

$$\boxed{(\ell): \vec{r} = \vec{OA} + t\vec{AB}, \forall t \in \mathbb{R}}$$

The above statement is equivalent to:

$$\boxed{M \in (\ell) \Leftrightarrow \exists t \in \mathbb{R} : \vec{OM} = \vec{OA} + t\vec{AB}}$$

- $\vec{AB}$  = direction vector of  $(\ell)$ .
- For  $\vec{r} = (x, y, z)$ ,  $\vec{OA} = (x_0, y_0, z_0)$ , and  $\vec{AB} = (a, b, c)$ , the parametric equation is equivalent to:

$$(\ell): \begin{cases} x = x_0 + at \\ y = y_0 + bt \\ z = z_0 + ct \end{cases}, \forall t \in \mathbb{R}.$$

- Eliminating  $t$  from the above equations gives the symmetric equations representation of the line  $(\ell)$ :

$$(l): \frac{x-x_0}{a} = \frac{y-y_0}{b} = \frac{z-z_0}{c}$$

The symmetric equations can be reduced to a system of the form

$$(l): \begin{cases} A_1x + B_1y + C_1 = 0 \\ A_2y + B_2z + C_2 = 0 \end{cases}$$

which essentially defines the line  $(l)$  as an intersection of two planes.

↪ Relative position of two lines

Consider the lines:

$$(l_1): \vec{r} = \vec{a}_1 + t\vec{b}_1, \quad \forall t \in \mathbb{R}$$

$$(l_2): \vec{r} = \vec{a}_2 + t\vec{b}_2, \quad \forall t \in \mathbb{R}$$

Then:

$$(l_1) \parallel (l_2) \Leftrightarrow \vec{b}_1 \parallel \vec{b}_2 \Leftrightarrow \vec{b}_1 \times \vec{b}_2 = \vec{0}$$

## EXAMPLES

a) Write the symmetric equations for the line (AB) with  $A(1, 2, -1)$  and  $B(5, 4, 1)$ .

Solution

$$\left. \begin{array}{l} A(1, 2, -1) \\ B(5, 4, 1) \end{array} \right\} \Rightarrow \begin{cases} \vec{OA} = (1, 2, -1) \\ \vec{AB} = (5-1, 4-2, 1-(-1)) = (4, 2, 2) \end{cases}$$

therefore:

$$(l): (x, y, z) = \vec{OA} + t \vec{AB} = (1, 2, -1) + t(4, 2, 2) = (1+4t, 2+2t, -1+2t) \Leftrightarrow$$

$$\Leftrightarrow \begin{cases} x = 1+4t \\ y = 2+2t \\ z = -1+2t \end{cases} \Leftrightarrow \frac{x-1}{4} = \frac{y-2}{2} = \frac{z+1}{2} \Leftrightarrow$$

$$\Leftrightarrow \begin{cases} 2(x-1) = 4(y-2) \\ 2(y-2) = 2(z+1) \end{cases} \Leftrightarrow \begin{cases} 2x-2 = 4y-8 \\ 2y-4 = 2z+2 \end{cases} \Leftrightarrow$$

$$\Leftrightarrow \begin{cases} 2x-4y+6=0 \\ 2y-2z-6=0 \end{cases} \Leftrightarrow \boxed{\begin{cases} x-2y+3=0 \\ y-z-3=0 \end{cases}}$$

b) Write the parametric equation for the line  $(\ell)$  defined by

$$(\ell): \begin{cases} x - 3y + 2 = 0 \\ 2y - z + 5 = 0 \end{cases}$$

Solution

Since,

$$(x, y, z) \in (\ell) \Leftrightarrow \begin{cases} x - 3y + 2 = 0 \\ 2y - z + 5 = 0 \end{cases} \Leftrightarrow \begin{cases} x = 3y - 2 \\ z = 2y + 5 \end{cases} \Leftrightarrow$$

$$\begin{aligned} \Leftrightarrow (x, y, z) &= (3y - 2, y, 2y + 5) = \\ &= (3y, y, 2y) + (-2, 0, 5) = \\ &= y(3, 1, 2) + (-2, 0, 5) \end{aligned}$$

$$\Leftrightarrow \exists t \in \mathbb{R}: (x, y, z) = (3, 1, 2)t + (-2, 0, 5)$$

it follows that

$$(\ell): (x, y, z) = (-2, 0, 5) + (3, 1, 2)t$$

## EXERCISES

- 97) Write and simplify the symmetric equations for the line (AB) with
- a)  $A(1, 1, 3)$  and  $B(2, 1, 1)$
  - b)  $A(5, 3, 2)$  and  $B(7, 2, 4)$
  - c)  $A(1, 9, 7)$  and  $B(6, 2, 2)$
  - d)  $A(2, 1, 6)$  and  $B(5, 3, 2)$

↑ To confirm your results, check whether your symmetric equations are satisfied by the points A and B. Since two points define a unique line, if the answer is yes, then you have in fact proved that your answer is correct.

- 98) Write the parametric equations for the following lines, defined by symmetric equations

a)  $(\ell): \begin{cases} 2x + y - 3 = 0 \\ y + 2z + 1 = 0 \end{cases}$

b)  $(\ell): \begin{cases} 3x - 2y + 2 = 0 \\ y + 2z - 5 = 0 \end{cases}$

c)  $(\ell): \begin{cases} 5x + 3y - 6 = 0 \\ 2y - 6z + 1 = 0 \end{cases}$

d)  $(\ell): \begin{cases} 2x + 5y + 3 = 0 \\ 4y - 3z - 2 = 0 \end{cases}$

↳ To confirm your results, use the parametric equations to obtain two points  $A, B$  (e.g. try  $t=0$  and  $t=2$ ). Then confirm that the points  $A, B$  satisfy the original symmetric equations. If they do, then you have shown that your answer is correct.

## Planes in $\mathbb{R}^3$

- Let  $A, B, C$  be three non-collinear points (i.e.  $A, B, C$  are not on the same line). Then, these three points define a unique plane with equation:

$$(p): \vec{r} = \vec{OA} + t\vec{AB} + s\vec{AC}, \forall t, s \in \mathbb{R}$$

Equivalently, if we let

$\vec{OA} = (x_0, y_0, z_0)$ ,  $\vec{AB} = (a_1, a_2, a_3)$ ,  $\vec{AC} = (b_1, b_2, b_3)$   
then:

$$(p): \begin{cases} x = x_0 + a_1 t + b_1 s \\ y = y_0 + a_2 t + b_2 s \\ z = z_0 + a_3 t + b_3 s \end{cases}, \forall t, s \in \mathbb{R}$$

Similarly, the belonging condition for  $(p)$  is:

$$M \in (p) \Leftrightarrow \exists t, s \in \mathbb{R}: \vec{OM} = \vec{OA} + t\vec{AB} + s\vec{AC}$$

- Eliminating  $t, s$  gives an equivalent equation of the form:

$$(p): Ax + By + Cz + D = 0$$

which is called the scalar equation of  $(p)$ .

## → Scalar equation for plane from 3 points

Let  $A, B, C$  be three points with  $\vec{AB} \times \vec{AC} \neq \vec{0}$ .  
The plane  $(p)$  defined by  $A, B, C$  has scalar equation:

$$(p): (\vec{AB} \times \vec{AC}) \cdot (\vec{r} - \vec{OA}) = 0$$

with  $r = (x, y, z)$ . Equivalently:

$$M \in (p) \Leftrightarrow (\vec{AB} \times \vec{AC}) \cdot (\vec{OM} - \vec{OA}) = 0$$

Here  $\vec{n} \equiv \vec{AB} \times \vec{AC}$  = normal vector of  $(p)$ .  
 $\vec{n}$  is  $\perp$  to every line of  $(p)$ .

To prove this we use the following lemma:

Lemma:  $\boxed{\text{If } \vec{AB} \times \vec{AC} \neq \vec{0}, \text{ then}$   
 $\forall u \in \mathbb{R}^3 : \exists ! x_1, x_2, x_3 \in \mathbb{R} : u = x_1 \vec{AB} + x_2 \vec{AC} + x_3 (\vec{AB} \times \vec{AC})}$

Proof

Define:  $(a_1, a_2, a_3) = \vec{AB}$ ,  $(b_1, b_2, b_3) = \vec{AC}$ , and  
 $(c_1, c_2, c_3) = \vec{AB} \times \vec{AC}$ .

Let  $u = (u_1, u_2, u_3) \in \mathbb{R}^3$  be given. Then:

$$u = x_1 \vec{AB} + x_2 \vec{AC} + x_3 (\vec{AB} \times \vec{AC}) \Leftrightarrow$$

$$\Leftrightarrow \begin{cases} a_1 x_1 + a_2 x_2 + a_3 x_3 = u_1 \\ b_1 x_1 + b_2 x_2 + b_3 x_3 = u_2 \\ c_1 x_1 + c_2 x_2 + c_3 x_3 = u_3 \end{cases} \quad (1).$$

Since:

$$D = \begin{vmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix} =$$

$$= [(a_1, a_2, a_3) \times (b_1, b_2, b_3)] \cdot (c_1, c_2, c_3) =$$

$$= (\vec{AB} \times \vec{AC}) \cdot (\vec{AB} \times \vec{AC}) = \|\vec{AB} \times \vec{AC}\|^2 > 0,$$

because  $\vec{AB} \times \vec{AC} \neq \vec{0}$ .  $\Rightarrow$

$\Rightarrow$  equation (1) has a unique solution

$(x_1, x_2, x_3) \in \mathbb{R}^3$ , which proves the claim.  $\square$

$\downarrow$  It follows that the vectors  $\vec{AB}$ ,  $\vec{AC}$ , and  $\vec{AB} \times \vec{AC}$  can be used to define a non-orthogonal coordinate system in which the coordinates of the vector  $\vec{u}$  are  $(x_1, x_2, x_3)$ . We say therefore that  $\vec{AB}$ ,  $\vec{AC}$ ,  $\vec{AB} \times \vec{AC}$  are linearly independent.

Now we prove the main result:

$$M \in (p) \Leftrightarrow (\vec{AB} \times \vec{AC}) \cdot (\vec{OM} - \vec{OA}) = 0$$

Proof

( $\Rightarrow$ )

$$\begin{aligned} \text{Assume } M \in (p) &\Rightarrow \exists t, s \in \mathbb{R} : \vec{OM} = \vec{OA} + t\vec{AB} + s\vec{AC} \Rightarrow \\ \Rightarrow (\vec{AB} \times \vec{AC}) \cdot (\vec{OM} - \vec{OA}) &= \\ &= (\vec{AB} \times \vec{AC}) \cdot (\vec{OA} + t\vec{AB} + s\vec{AC} - \vec{OA}) = \\ &= (\vec{AB} \times \vec{AC}) \cdot (t\vec{AB} + s\vec{AC}) = \\ &= (\vec{AB} \times \vec{AC}) \cdot (t\vec{AB}) + (\vec{AB} \times \vec{AC}) \cdot (s\vec{AC}) = \\ &= t\vec{AB} \cdot (\vec{AB} \times \vec{AC}) + s\vec{AC} \cdot (\vec{AB} \times \vec{AC}) = \\ &= t\vec{AC} \cdot (\vec{AB} \times \vec{AB}) + s\vec{AB} \cdot (\vec{AC} \times \vec{AC}) = \\ &= t\vec{AC} \cdot \vec{0} + s\vec{AB} \cdot \vec{0} = t \cdot 0 + s \cdot 0 = 0 \end{aligned}$$

( $\Leftarrow$ )

$$\text{Assume that } (\vec{AB} \times \vec{AC}) \cdot (\vec{OM} - \vec{OA}) = 0 \quad (1)$$

By the lemma above, let  $x_1, x_2, x_3 \in \mathbb{R}$  such that

$$\vec{AM} = x_1\vec{AB} + x_2\vec{AC} + x_3(\vec{AB} \times \vec{AC}).$$

Also note that from the ( $\Rightarrow$ ) proof:

$$(\vec{AB} \times \vec{AC}) \cdot (x_1\vec{AB} + x_2\vec{AC}) = 0$$

Since:

$$\begin{aligned} (\vec{AB} \times \vec{AC}) \cdot (\vec{OM} - \vec{OA}) &= (\vec{AB} \times \vec{AC}) \cdot (\vec{OA} + \vec{AM} - \vec{OA}) = \\ &= (\vec{AB} \times \vec{AC}) \cdot \vec{AM} = \\ &= (\vec{AB} \times \vec{AC}) \cdot (x_1\vec{AB} + x_2\vec{AC} + x_3(\vec{AB} \times \vec{AC})) = \\ &= (\vec{AB} \times \vec{AC}) \cdot [x_3(\vec{AB} \times \vec{AC})] = \\ &= x_3(\vec{AB} \times \vec{AC}) \cdot (\vec{AB} \times \vec{AC}) = x_3 \|\vec{AB} \times \vec{AC}\|^2. \end{aligned}$$

it follows from (1) that

$$\left. \begin{aligned} x_3 \|\vec{AB} \times \vec{AC}\|^2 &= 0 \\ \vec{AB} \times \vec{AC} &\neq \vec{0} \end{aligned} \right\} \Rightarrow x_3 = 0 \Rightarrow \vec{AM} = x_1\vec{AB} + x_2\vec{AC}$$

$$\Rightarrow \vec{OM} = \vec{OA} + \vec{AM} = \vec{OA} + x_1 \vec{AB} + x_2 \vec{AC} \Rightarrow$$

$$\Rightarrow M \in (p) \quad \square$$

### EXAMPLES

Find the equation of the plane  $(p)$  containing the points  $A(3,1,2)$ ,  $B(4,3,1)$ , and  $C(2,5,6)$

Solution

$$\left. \begin{array}{l} A(3,1,2) \\ B(4,3,1) \end{array} \right\} \Rightarrow \vec{AB} = (4-3, 3-1, 1-2) = (1, 2, -1) \quad (1)$$

$$\left. \begin{array}{l} A(3,1,2) \\ C(2,5,6) \end{array} \right\} \Rightarrow \vec{AC} = (2-3, 5-1, 6-2) = (-1, 4, 4) \quad (2)$$

From Eq. (1) and Eq. (2):

$$\vec{AB} \times \vec{AC} = (1, 2, -1) \times (-1, 4, 4) =$$

$$= \begin{vmatrix} e_1 & e_2 & e_3 \\ 1 & 2 & -1 \\ -1 & 4 & 4 \end{vmatrix} \begin{vmatrix} e_1 & e_2 \\ 1 & 2 \\ -1 & 4 \end{vmatrix} =$$

$$= (2 \cdot 4)e_1 + (-1)(-1)e_2 + (1 \cdot 4)e_3 - (-1)2e_3 - 4(-1)e_1 - (4 \cdot 1)e_2 =$$

$$= 8e_1 + e_2 + 4e_3 + 2e_3 + 4e_1 - 4e_2 =$$

$$= (8+4)e_1 + (1-4)e_2 + (4+2)e_3 = 12e_1 - 3e_2 + 6e_3$$

$$= (12, -3, 6), \quad \text{and therefore}$$

$$(p): (\vec{AB} \times \vec{AC}) \cdot [(x, y, z) - \vec{OA}] = 0 \Leftrightarrow$$

$$\Leftrightarrow (12, -3, 6) \cdot (x-3, y-1, z-2) = 0$$

$$\Leftrightarrow 12(x-3) - 3(y-1) + 6(z-2) = 0 \Leftrightarrow$$

$$\Leftrightarrow 4(x-3) - (y-1) + 2(z-2) = 0 \Leftrightarrow$$

$$\Leftrightarrow 4x - 12 - y + 1 + 2z - 4 = 0 \Leftrightarrow$$

$$\Leftrightarrow 4x - y + 2z - 15 = 0 \Leftrightarrow$$

$$\Leftrightarrow 4x - y + 2z = 15.$$

Thus:  $(p): 4x - y + 2z = 15.$

↑  $\rightarrow$  Note that the plane  $(p): Ax + By + Cz + D = 0$  has normal vector  $\vec{n} = (A, B, C).$

### ► Plane equation to parametric equation

The first step is to solve the plane equation for one of the 3 variables and use the result to rewrite  $(x, y, z)$  as in the following example.

b) Write the parametric equations for the plane  $(p): 2x + y + 3z = 7.$

Solution

We note that

$$2x + y + 3z = 7 \Leftrightarrow y = 7 - 2x - 3z \Leftrightarrow$$

$$\Leftrightarrow (x, y, z) = (x, 7 - 2x - 3z, z) =$$

$$= (0, 7, 0) + (x, -2x, 0) + (0, -3z, z)$$

$$= (0, 7, 0) + x(1, -2, 0) + z(0, -3, 1)$$

$\Leftrightarrow \exists t, s \in \mathbb{R}: (x, y, z) = (0, 7, 0) + t(1, -2, 0) + s(0, -3, 1)$   
and therefore

$$(p): (x, y, z) = (0, 7, 0) + t(1, -2, 0) + s(0, -3, 1), \forall t, s \in \mathbb{R}.$$

## ► Parametric equation to plane equations

We use the parametric equation to obtain 3 collinear  
3 non-collinear points  $A, B, C$  (e.g. use  $(t, s) =$   
 $(0, 0), (1, 0), (0, 1)$ ). From the 3 points we then  
derive the plane equation.

c) Write the plane equation for the plane

$$(p): \begin{cases} x = 1 + 2t + s \\ y = 3 - t - 2s \\ z = 2 + 3t + s \end{cases}$$

### Solution

We obtain 3 points:

$$(t, s) = (0, 0) \rightarrow A(1, 3, 2)$$

$$(t, s) = (1, 0) \rightarrow B(3, 2, 5)$$

$$(t, s) = (0, 1) \rightarrow C(2, 1, 3)$$

It follows that

$$\vec{AB} = (3-1, 2-3, 5-2) = (2, -1, 3) \left. \vphantom{\vec{AB}} \right\} \Rightarrow$$

$$\vec{AC} = (2-1, 1-3, 3-2) = (1, -2, 1) \left. \vphantom{\vec{AC}} \right\}$$

$$\Rightarrow \vec{AB} \times \vec{AC} = (2, -1, 3) \times (1, -2, 1) =$$

$$= \begin{vmatrix} e_1 & e_2 & e_3 & | & e_1 & e_2 \\ 2 & -1 & 3 & | & 2 & -1 \\ 1 & -2 & 1 & | & 1 & -2 \end{vmatrix} =$$

$$= (-1)1e_1 + 3 \cdot 1e_2 + 2(-2)e_3 - 1(-1)e_3 - (-2)3e_1 - 1 \cdot 2e_2$$

$$= -e_1 + 3e_2 - 4e_3 + e_3 + 6e_1 - 2e_2 =$$

$$= (-1+6)e_1 + (3-2)e_2 + (-4+1)e_3 =$$
$$= 5e_1 + e_2 - 3e_3 = (5, 1, -3)$$

and therefore

$$(p): (\vec{AB} \times \vec{AC}) \cdot [(x, y, z) - \vec{OA}] = 0 \Leftrightarrow$$

$$\Leftrightarrow (5, 1, -3) \cdot [(x, y, z) - (1, 3, 2)] = 0 \Leftrightarrow$$

$$\Leftrightarrow (5, 1, -3) \cdot (x-1, y-3, z-2) = 0 \Leftrightarrow$$

$$\Leftrightarrow 5(x-1) + (y-3) - 3(z-2) = 0 \Leftrightarrow$$

$$\Leftrightarrow 5x - 5 + y - 3 - 3z + 6 = 0 \Leftrightarrow$$

$$\Leftrightarrow 5x + y - 3z - 2 = 0 \Leftrightarrow 5x + y - 3z = 2$$

and therefore

$$\underline{(p): 5x + y - 3z = 2}$$

## EXERCISES

Write the plane equation  $(p): Ax + By + Cz + D = 0$   
(29) for the plane  $(p)$  defined by three non-collinear points  $A, B, C$  with coordinates:

- a)  $A(1, 2, 1), B(4, 1, 0), C(0, 3, 5)$
- b)  $A(0, 0, 0), B(1, 1, 1), C(1, -1, 1)$
- c)  $A(3, 0, 0), B(0, 1, 2), C(1, 0, 2)$
- d)  $A(3, 2, 2), B(3, 5, 3), C(0, 1, 2)$

↑  
→ To confirm your answers, it is sufficient to verify that the plane equation is satisfied by the coordinates of the points  $A, B, C$ . Note that 3 collinear points define a unique plane.

Write the parametric equations for the  
(30) planes  $(p)$  defined by the following plane equations:

- a)  $(p): 2x + y + 7z = 3$
- b)  $(p): x + 3y - 2z = 6$
- c)  $(p): 3x - 2y - z = 5$

- d)  $(p): x - y + 3z = -1$
- e)  $(p): 2x + 5y + 3z = 2$

↳ To confirm your work, use the parametric equations to generate 3 noncollinear points and confirm that these 3 points satisfy the original plane equation.

31 Write the plane equations for the planes (p) defined by the following parametric equations:

$$a) (p): \begin{cases} x = 2 + 3t + 5s \\ y = 1 - t - 2s \\ z = 3 + t + s \end{cases}$$

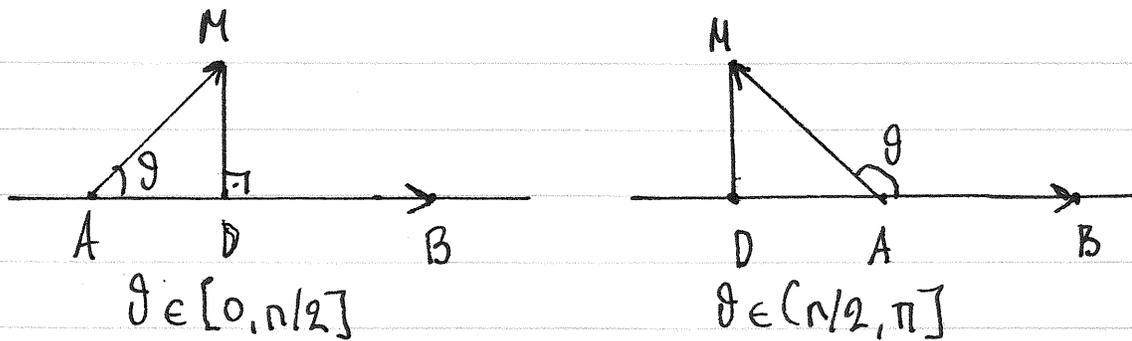
$$b) (p): \begin{cases} x = 1 + 2t + s \\ y = 7 + t - 3s \\ z = 2 - t - 9s \end{cases}$$

$$c) (p): \begin{cases} x = t - s \\ y = t + 2s \\ z = 3t - 2s \end{cases}$$

↳ To confirm your work, substitute  $x, y, z$  in terms of  $t, s$  from the parametric equations into the plane equation, and confirm that the plane equation is satisfied for all values of  $t$  and  $s$ .

## Distances between points, lines, and planes

① → Distance of point M from line (AB)



$$d(M, AB) = \frac{\|\vec{AB} \times \vec{AM}\|}{\|\vec{AB}\|}$$

Proof

Let  $D \in (AB)$  such that  $MD \perp AB$ . Define the interior angle  $\vartheta = \widehat{MAB}$ . We distinguish between the following cases:

Case 1: Assume  $\vartheta \in [0, \pi/2]$ .

$$\text{Then } d(M, AB) = MD = AM \sin \vartheta.$$

Case 2: Assume  $\vartheta \in (\pi/2, \pi]$ . Then:

$$\begin{aligned} d(M, AB) &= MD = AM \sin(\pi - \vartheta) = -AM \sin(-\vartheta) = \\ &= AM \sin \vartheta \end{aligned}$$

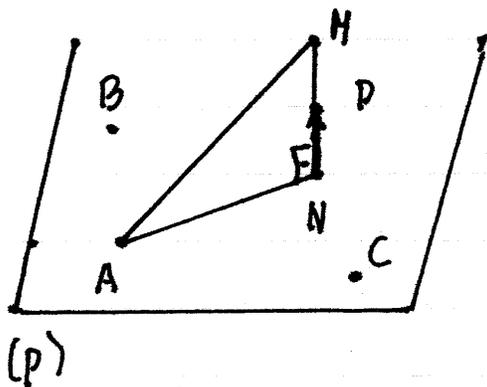
In both cases we find  $d(M, AB) = AM \sin \vartheta$ .

It follows that:

$$\begin{aligned} \|\vec{AB} \times \vec{AM}\| &= \|\vec{AB}\| \|\vec{AM}\| \sin \vartheta = \|\vec{AB}\| [AM \sin \vartheta] = \\ &= \|\vec{AB}\| d(M, AB) \Rightarrow d(M, AB) = \frac{\|\vec{AB} \times \vec{AM}\|}{\|\vec{AB}\|} \end{aligned}$$

② → Distance of point from plane  
 ↓

Case 1 : The distance  $d(M, (p))$  between the point  $M$  and the plane  $(p)$  defined by the points  $A, B, C$  is given by



$$d(M, (p)) = \frac{|(\vec{AB} \times \vec{AC}) \cdot \vec{MA}|}{\|\vec{AB} \times \vec{AC}\|}$$

(p)  
Proof

Let  $N \in (p)$  be the projection of  $M$  on  $(p)$  such that  $MN \perp (p)$ . Let  $D \in (MN)$  such that  $\vec{ND} = \vec{AB} \times \vec{AC}$ . It follows that:

$$\begin{aligned} d(M, (p)) &= MN = \|\vec{MN}\| = \|\text{proj}_{\vec{ND}}(\vec{AM})\| = \\ &= |\text{comp}_{\vec{ND}}(\vec{AM})| = \left| \frac{\vec{AM} \cdot \vec{ND}}{\|\vec{ND}\|} \right| = \\ &= \frac{|\vec{AM} \cdot \vec{ND}|}{\|\vec{ND}\|} = \frac{|\vec{AM} \cdot (\vec{AB} \times \vec{AC})|}{\|\vec{AB} \times \vec{AC}\|} = \\ &= \frac{|(\vec{AB} \times \vec{AC}) \cdot \vec{MA}|}{\|\vec{AB} \times \vec{AC}\|} \end{aligned}$$

Case 2: The distance between  $M(x_0, y_0, z_0)$  and the plane  $(p): Ax + By + Cz + D = 0$  is given by:

$$d(M, (p)) = \frac{|Ax_0 + By_0 + Cz_0 + D|}{\sqrt{A^2 + B^2 + C^2}}$$

Proof

Let  $N, P, Q \in (p)$  be three non-collinear points on the plane  $(p)$  with  $N(x_1, y_1, z_1)$ . Since  $N(x_1, y_1, z_1) \in (p) \Rightarrow Ax_1 + By_1 + Cz_1 + D = 0 \Rightarrow Ax_1 + By_1 + Cz_1 = -D$ . (1)

We also note that:

$$(p): Ax + By + Cz + D = 0 \Rightarrow \vec{u} = (A, B, C) \perp (p) \left. \begin{array}{l} \Rightarrow \\ \vec{NP} \times \vec{NQ} \perp (p) \end{array} \right\} \Rightarrow$$

$$\Rightarrow \vec{u} \parallel \vec{NP} \times \vec{NQ} \Rightarrow \exists \lambda \in \mathbb{R}: \vec{NP} \times \vec{NQ} = \lambda \vec{u} \quad (2)$$

and

$$\left. \begin{array}{l} M(x_0, y_0, z_0) \\ N(x_1, y_1, z_1) \end{array} \right\} \Rightarrow \vec{NM} = (x_0 - x_1, y_0 - y_1, z_0 - z_1) \quad (3)$$

From (1), (2), (3), using the previous result, it follows that

$$d(M, (p)) = \frac{|\vec{NM} \cdot (\vec{NP} \times \vec{NQ})|}{\|\vec{NP} \times \vec{NQ}\|} = \frac{|\vec{NM} \cdot (\lambda \vec{u})|}{\|\lambda \vec{u}\|} =$$

$$\begin{aligned}
&= \frac{|\lambda (\vec{NM} \cdot \vec{u})|}{\|\lambda \vec{u}\|} = \frac{|\lambda| \cdot |\vec{NM} \cdot \vec{u}|}{|\lambda| \|\vec{u}\|} = \frac{|\vec{NM} \cdot \vec{u}|}{\|\vec{u}\|} = \\
&= \frac{|(x_0 - x_1, y_0 - y_1, z_0 - z_1) \cdot (A, B, C)|}{\|(A, B, C)\|} = \\
&= \frac{|A(x_0 - x_1) + B(y_0 - y_1) + C(z_0 - z_1)|}{\sqrt{A^2 + B^2 + C^2}} \\
&= \frac{|(Ax_0 + By_0 + Cz_0) - (Ax_1 + By_1 + Cz_1)|}{\sqrt{A^2 + B^2 + C^2}} \\
&= \frac{|Ax_0 + By_0 + Cz_0 - (-D)|}{\sqrt{A^2 + B^2 + C^2}} = \\
&= \frac{|Ax_0 + By_0 + Cz_0 + D|}{\sqrt{A^2 + B^2 + C^2}} \quad \square
\end{aligned}$$

## EXERCISES

32) Find the distance between

a) The point  $M(3,1,5)$  and the line  $(AB)$  passing through  $A(1,2,1)$  and  $B(0,0,4)$ .

b) The point  $M(1,1,-2)$  and the line  $(AB)$  given by

$$(AB): \begin{cases} x+y-3=0 \\ y+2z+1=0 \end{cases}$$

c) The point  $M(2,2,1)$  and the plane  $(p)$  defined by the points  $A(1,1,0)$ ,  $B(3,2,4)$ , and  $C(-1,2,0)$

d) The point  $M(1,3,-1)$  and the plane  $(p)$  given by

$$(p): \begin{cases} x = 2+t+s \\ y = 1-2t+3s \\ z = 3-t-s \end{cases}$$

e) The point  $M(1,2,1)$  and the plane  $(p): 2x+3y-z=3$ .

33) Find all  $a \in \mathbb{R}$  such that:

a) The distance of  $M(1,1,a)$  from the line  $(AB)$  passing through  $A(0,2,2)$  and  $B(3,1,1)$  is equal to 10

b) The distance of  $M(a,a,3)$  from the line

$$(AB): \begin{cases} 2x+y-1=0 \\ y+5z-2=0 \end{cases}$$

is minimized

- c) The distance between the point  $M(1, a, 2a+1)$  and the plane defined by the points  $A(2, 0, 2)$ ,  $B(3, 0, 0)$ ,  $C(1, -1, 3)$  is equal to 6.
- d) The distance between the point  $M(1, 1, 2)$  and the plane  $(p): x - 3y + 2z = a$  is equal to  $a$ .