

day 12

Exam 2

Email Monday night

Due by Email Thursday 5 pm

(or in class)

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black ink

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Multiple Integrals

Double Integrals

Given $f: A \rightarrow \mathbb{R}$ with $A \subseteq \mathbb{R}^2$ with

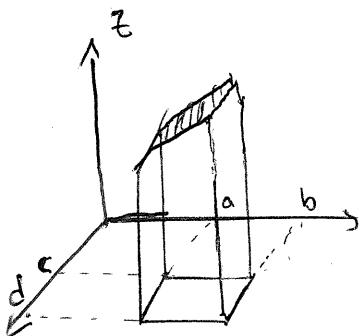
$$A = [a, b] \times [c, d] = \{(x, y) \mid x \in [a, b] \wedge y \in [c, d]\}$$

Thm: If f continuous on A

$$\int_a^b \int_c^d f(x, y) dx dy = \int_c^d \int_a^b f(x, y) dx dy = I$$

Then we define

$$\iint_A f(x, y) dx dy = I$$



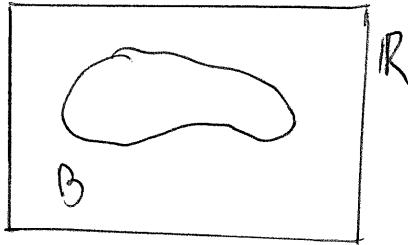
Think of it as a volume under a surface

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Let $B \subseteq A$ be a closed bounded region

Then there is a rectangle $R = [a, b] \times [c, d]$

such that $B \subseteq R$



define $g(x, y) = \begin{cases} f(x, y) & \text{if } (x, y) \in B \\ 0 & \text{if } (x, y) \in R - B \end{cases}$

Then we define $\iint_B f(x, y) dx dy = \iint_R g(x, y) dx dy$

and $\iint_B f(x, y) dx dy = 0$
 empty set

Examples

a) Evaluate the integral

$$I = \iint_A \frac{1+x^2}{1+y^2} dx dy \quad \text{for } A = [0, 1] \times [0, 1]$$

Solution

$$\begin{aligned} I &= \iint_A \frac{1+x^2}{1+y^2} dx dy = \int_0^1 dx \int_0^1 dy \frac{1+x^2}{1+y^2} = \int_0^1 dx (1+x^2) \int_0^1 \frac{dy}{1+y^2} = \int_0^1 dx (1+x^2) [\arctan y]_0^1 \\ &= \int_0^1 dx (1+x^2) (\arctan 1 - \arctan 0) = \left(\frac{\pi}{4} - 0\right) \int_0^1 dx (1+x^2) = \frac{\pi}{4} \left[x + \frac{x^3}{3}\right]_0^1 \end{aligned}$$

$$= \frac{\pi}{4} \left[(1-0) + \frac{1^3 - 0^3}{3} \right] = \frac{\pi}{4} \cdot \frac{4}{3} = \frac{\pi}{3}$$

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b) Find the volume of the solid under the surface

$$(S): z = x\sqrt{x^2+y} \text{ and above the rectangle}$$

$$A = [0, 1] \times [0, 1] \text{ on the } xy\text{-plane}$$

Solution

$$V = \iint_A dx dy x \sqrt{x^2+y} = \int_0^1 dx \int_0^1 dy x \sqrt{x^2+y} = \int_0^1 dx x \left[\int_0^1 dy \sqrt{x^2+y} \right]$$

$$\text{Let } t = g(y) = \sqrt{x^2+y} \Leftrightarrow t^2 = x^2+y \Leftrightarrow y = t^2 - x^2$$

thus: $dy = 2t dt$ and furthermore:

$$\text{for } y=0: g(0) = \sqrt{x^2+0} = \sqrt{x^2}$$

$$\text{for } y=1: g(1) = \sqrt{x^2+1}$$

It follows that

$$\begin{aligned} V &= \int_0^1 dx x \left[\int_{\sqrt{x^2}}^{\sqrt{1+x^2}} dt t(2t) \right] = 2 \int_0^1 dx x \left[\int_x^{\sqrt{1+x^2}} t^2 dt \right] = 2 \int_0^1 dx x \left[\frac{t^3}{3} \right]_{x}^{\sqrt{1+x^2}} \\ &= 2 \int_0^1 dx x \left[\frac{(\sqrt{1+x^2})^3 - x^3}{3} \right] = \frac{2}{3} \int_0^1 dx x \left[(1+x^2)\sqrt{1+x^2} - x^3 \right] \\ &= \frac{2}{3} \int_0^1 dx x (1+x^2)\sqrt{1+x^2} - \frac{2}{3} \int_0^1 dx x^4 \end{aligned}$$

$$= \frac{2}{3} (I_1 - I_2) \text{ with}$$

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$$I_1 = \int_0^1 dx x(1+x^2)\sqrt{1+x^2} \quad \text{and} \quad I_2 = \int_0^1 x^4 dx$$

• For I_2 :

$$I_2 = \int_0^1 x^4 dx = \left[\frac{x^5}{5} \right]_0^1 = \frac{1^5 - 0^5}{5} = \frac{1}{5}$$

• For I_1 ,

$$\text{Let } x = \tan \theta \Rightarrow \begin{cases} dx = \frac{d\theta}{\cos^2 \theta} \\ \text{For } x=0 : \theta=0 \\ \text{For } x=1 : \theta = \frac{\pi}{4} \end{cases} \Rightarrow$$

$$\Rightarrow I_1 = \int_0^{\frac{\pi}{4}} \frac{d\theta}{\cos^2 \theta} \tan \theta (1 + \tan^2 \theta) \sqrt{1 + \tan^2 \theta}$$

$$= \int_0^{\frac{\pi}{4}} \frac{d\theta}{\cos^2 \theta} \tan \theta \cdot \frac{1}{\cos^2 \theta} \sqrt{\frac{1}{\cos \theta}}$$

$$= \int_0^{\frac{\pi}{4}} d\theta \frac{\tan \theta}{\cos^4 \theta |\cos \theta|} \cdot \int_0^{\frac{\pi}{4}} \frac{d\theta \tan \theta}{\cos^5 \theta}$$

$$= \int_0^{\frac{\pi}{4}} d\theta \frac{\sin \theta}{\cos^5 \theta \cos \theta} = \int_0^{\frac{\pi}{4}} d\theta \frac{\sin \theta}{\cos^6 \theta}$$

$$\text{Let } s = \cos \theta = g(\theta) \Rightarrow \begin{cases} ds = -\sin \theta d\theta \Rightarrow \sin \theta d\theta = -ds \\ g(0) = \cos 0 = 1 \\ g\left(\frac{\pi}{4}\right) = \cos\left(\frac{\pi}{4}\right) = \frac{\sqrt{2}}{2} \end{cases}$$

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Double Integrals over simple regions

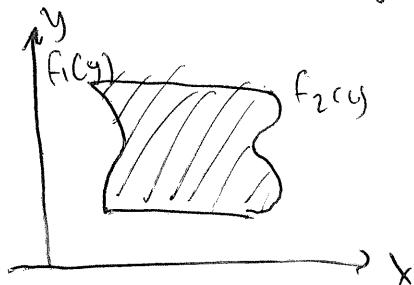
x-Simple region

- Let $A \subseteq \mathbb{R}^2$. we say that A is x-simple if and only if it can be written as

$$A = \{(x, y) \in \mathbb{R}^2 \mid f_1(y) \leq x \leq f_2(y) \wedge y \in [a, b]\}$$

with f_1, f_2 function with $f_1: [a, b] \rightarrow \mathbb{R}$ and $f_2: [a, b] \rightarrow \mathbb{R}$

$$\iint_A f(x, y) dx dy = \int_a^b dy \int_{f_1(y)}^{f_2(y)} f(x, y) dx$$

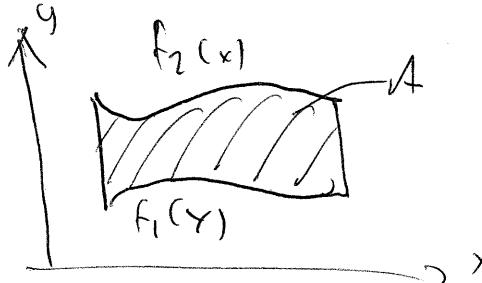


y-Simple region

- Let $A \subseteq \mathbb{R}^2$. we say that A is y-simple if and only if it can be written as

$$A = \{(x, y) \in \mathbb{R}^2 \mid x \in [a, b] \wedge f_1(x) \leq y \leq f_2(x)\}$$

with f_1, f_2 function with $f_1: [a, b] \rightarrow \mathbb{R}$ and $f_2: [a, b] \rightarrow \mathbb{R}$

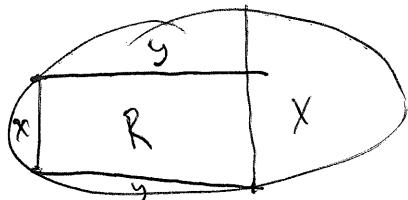


If A is y-simple then

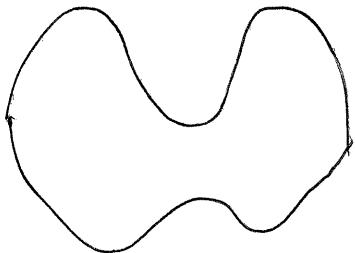
$$\iint_A f(x, y) dx dy = \int_a^b dx \int_{f_1(x)}^{f_2(x)} dy f(x, y)$$

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We can always divide a convex region in x-simple and y-simple



Convex region too but we need to be careful



Examples

a) Evaluate the integral $I = \iint_A 2y e^x dx dy$ with

$$A = \{(x, y) \in \mathbb{R}^2 \mid 0 \leq y \leq 1 \wedge 0 \leq x \leq y^2\}$$

$$\begin{aligned} I &= \iint_A 2y e^x dx dy = \int_0^1 dy \int_0^{y^2} dx 2y e^x = \int_0^1 dy 2y \left[e^x \right]_0^{y^2} \\ &= \int_0^1 dy 2y [e^{y^2} - e^0] = \int_0^1 dy 2y (e^{y^2} - 1) \end{aligned}$$

$$\begin{aligned} &= \int_0^1 2y e^{y^2} dy - \int_0^1 2y dy = I_1 - I_2 \quad (1) \end{aligned}$$

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Example #1

find the min and max values for

$$f(x, y, z) = x + 2y + 3z \quad \text{①}$$

$$\begin{cases} x^2 + y^2 = 2 & \text{②} \\ y + z = 1 & \text{③} \end{cases}$$

Solution:

$$\text{define } g_1(x, y, z) = 2 - x^2 - y^2.$$

$$g_2(x, y, z) = y + z - 1$$

Note that

$$\nabla f(x, y, z) = (1, 2, 3)$$

$$\nabla g_1(x, y, z) = (-2x, -2y, 0)$$

$$\nabla g_2(x, y, z) = (0, 1, 1)$$

for linear independence.

$$\nabla g_1 \times \nabla g_2 = (-2x, -2y, 0) \times (0, 1, 1)$$

$$= \begin{vmatrix} i & j & k \\ -2x & -2y & 0 \\ 0 & 1 & 1 \end{vmatrix} = \begin{vmatrix} i & j & k \\ -2x & -2y & 2y \\ 0 & 1 & 0 \end{vmatrix}$$

$$= 1 \cdot (-1)^{3+2} \cdot \begin{vmatrix} i & -j+k \\ -2x & 2y \end{vmatrix}$$

$$= -1 (i \cdot 2y - (-j+k)(-2x))$$

$$= -(2y, -2x, +2x)$$

$$= (-2y, +2x, -2x)$$

$\therefore \nabla g_1, \nabla g_2$ are linearly independent iff. $\nabla g_1 \times \nabla g_2 \neq \vec{0}$

$\therefore x \neq 0$ or $y \neq 0$ ($x \neq 0 \vee y \neq 0$).

\therefore this linear independence fails at $(x, y, z) = (0, 0, 1)$.

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by (4) $z = 1 - y$, and since $x = -\frac{1}{2\lambda_1}$, $y = \frac{1}{2\lambda_1}$

$$\therefore \begin{cases} x = \frac{-1}{2\lambda_1} \\ y = \frac{1}{2\lambda_1} \\ \lambda_1 = \frac{1}{2} \vee \lambda_1 = -\frac{1}{2} \\ z = 1 - y \end{cases}$$

$$\therefore \begin{cases} x = -1 \\ y = 1 \\ z = 0 \end{cases} \quad \vee \quad \begin{cases} x = 1 \\ y = -1 \\ z = 2 \end{cases}$$

$$\therefore (x, y, z) = (-1, 1, 0) \vee (x, y, z) = (1, -1, 2)$$

Note that both point satisfy the linear independence condition

considering $f(x, y, z) = x + 2y + 3z$, then.

$$f(-1, 1, 0) = -1 + 2 = 1.$$

$$f(1, -1, 2) = 1 - 2 + 6 = 5$$

$(-1, 1, 0)$ is the minimum. and.

$(1, -1, 2)$ is the maximum

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Example #2. find the stationary point.

$$f(x, y, z) = XYZ, \text{ with } x, y, z \in (0, +\infty).$$

under constraint

$$xy + yz + zx = 1$$

$$\therefore \text{define } g(x, y, z) = xy + yz + zx - 1.$$

$$\therefore \nabla f = (yz, xz, xy) \quad \because x, y, z \in (0, +\infty)$$

$$\nabla g = (y+z, x+z, y+x) \quad \therefore \nabla g \neq \vec{0} \quad \therefore \nabla g \text{ is linearly independent.}$$

$\therefore (x, y, z)$ is stationary iff.

$$\begin{cases} \nabla f = \lambda \nabla g \\ g(x, y, z) = 0 \end{cases} \quad \therefore \begin{cases} yz = \lambda(y+z) \\ xz = \lambda(x+z) \\ xy = \lambda(x+y) \\ xy + yz + zx - 1 = 0 \end{cases}$$

$$\therefore \begin{cases} xy = \lambda x(y+z) & (7) \\ xy = \lambda y(x+z) & (8) \\ xy = \lambda z(x+y) & (9) \\ xy + yz + zx = 1 & (10) \end{cases}$$

by (7)(8),

$$\lambda x(y+z) - \lambda y(x+z) = 0$$

$$\therefore \lambda(xy + xz - yx - yz) = 0$$

$$\therefore \lambda(y-x) = 0$$

$$\therefore \lambda = 0 \vee y = x$$

if $\lambda = 0$ then

$$\begin{cases} yz = 0 \\ xz = 0 \\ xy = 0 \\ xy + yz + zx = 1 \end{cases} \quad \therefore 0+0+0=1 \quad \text{inconsistent.}$$

$$\therefore \lambda \neq 0$$

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optimization problem on a bounded set

Def $\forall A \subset \mathbb{R}^n$, A is said to be bounded iff.
 $\exists p \in \mathbb{R}^n, \exists r \in (0, \infty)$ st. $A \subset B(p, r)$

Thm Let $f: A \rightarrow \mathbb{R}$ with $A \subset \mathbb{R}^n$. Assume that

- a) f is continuous on A
- b) A is closed ($\partial A \subset A$)
- c) A is bounded

then $\exists p_1, p_2 \in A$, such that $\forall x \in A, f(p_1) \leq f(x) \leq f(p_2)$

Example find the min and max of

$$f(x, y) = 2 + x^2 + y^2.$$

under the constraint

$$x^2 + \frac{y^2}{4} \leq 1$$

solution Define $S = \{(x, y) \in \mathbb{R}^2 \mid x^2 + y^2/4 \leq 1\}$ (interior points)
 $\nabla f(x, y) = (2x, 2y)$
let $\nabla f = 0, \therefore (x, y) = (0, 0)$

boundary

$$\text{let } g(x, y) = x^2 + \frac{y^2}{4} - 1 \quad \because x^2 + \frac{y^2}{4} = 1 \therefore \nabla g \neq \vec{0}$$

$$\therefore \nabla g = (2x, \frac{y}{2}) \quad \therefore \nabla g \text{ is linearly independent.}$$

$$\therefore \begin{cases} \nabla f = \lambda \nabla g \\ g(x, y) = 0 \end{cases} \quad \begin{cases} 2x = \lambda \cdot 2x \\ 2y = \lambda \cdot \frac{y}{2} \end{cases} \quad (1)$$

$$2x = \lambda \cdot 2x \quad (2)$$

$$2y = \lambda \cdot \frac{y}{2} \quad (3)$$

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2nd method

$$\therefore x^2 + \frac{y^2}{4} \leq 1$$

\therefore let $\begin{cases} x(t) = \cos t \\ y(t) = 2 \sin t \end{cases}$ $t \in [0, 2\pi]$

\therefore it follows that

$$g(t) = f(\cos t, 2 \sin t) = 2 + \cos^2 t + 4 \sin^2 t \\ = 3 + 3 \sin^2 t$$

$$g'(t) = (3 + 3 \sin^2 t)' = (3 \sin^2 t)' = 3 \cdot 2 \sin t \cdot (\sin t)' = 6 \sin t \cos t \\ = 3 \sin(2t)$$

$$\text{let } g'(t) = 0 \quad \therefore \sin(2t) = 0$$

$$\therefore 2t = n\pi, \quad \therefore t = \frac{n\pi}{2} \\ \because t \in [0, 2\pi] \quad \therefore t = 0, \frac{\pi}{2}, \pi, \frac{3\pi}{2}$$

$$\therefore \text{for } t = 0 \quad (x, y) = (\cos t, 2 \sin t) = (1, 0).$$

$$t = \frac{\pi}{2} \quad (x, y) = \dots = (0, 2)$$

$$t = \pi \quad (x, y) = \dots = (-1, 0)$$

$$t = \frac{3\pi}{2} \quad (x, y) = \dots = (0, -2).$$

Change of variables in double Integrals

Given $x_1, x_2, \dots, x_n \in \mathbb{R}$ we define

$$\begin{cases} y_1 = f_1(x_1, x_2, \dots, x_n) \\ y_2 = f_2(x_1, x_2, \dots, x_n) \\ \vdots \\ y_n = f_n(x_1, x_2, \dots, x_n) \end{cases}$$

Notation $x = (x_1, x_2, \dots, x_n)$

$$f(x) = (f_1(x), f_2(x), \dots, f_n(x))$$

Def: f differentiable on $X \Leftrightarrow \forall k \in [n]: f_k$ differentiable at x_0

Derivative matrix:

$$\begin{bmatrix} \frac{\partial f_1}{\partial x_1} & \frac{\partial f_1}{\partial x_2} & \dots & \frac{\partial f_1}{\partial x_n} \\ \frac{\partial f_2}{\partial x_1} & \frac{\partial f_2}{\partial x_2} & \dots & \frac{\partial f_2}{\partial x_n} \\ \vdots & & & \\ \frac{\partial f_n}{\partial x_1} & \frac{\partial f_n}{\partial x_2} & \dots & \frac{\partial f_n}{\partial x_n} \end{bmatrix}$$

Jacobian of $f(x)$

$$\frac{\partial(f_1, f_2, \dots, f_n)}{\partial(x_1, x_2, \dots, x_n)} = \det(Df(x))$$

Def: f one-to-one $\Leftrightarrow \forall x, y \in A: (f(x) = f(y) \Rightarrow x = y)$ with $f: A \rightarrow \mathbb{R}^n$ and $A \subseteq \mathbb{R}^n$

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Def. $f: A \rightarrow \mathbb{R}^n$ with $A \subseteq \mathbb{R}^n$ is a smooth change of variables

If and only if f_1, f_2, \dots, f_n continuously differentiable on A

f one-to-one

$$\frac{\partial(f_1, f_2, \dots, f_n)}{\partial(x_1, x_2, \dots, x_n)} \neq 0, \forall x \in A$$

Change of variables in \mathbb{R}^2

Consider $x = g_1(u, v)$ and $y = g_2(u, v)$ with $g(u, v) = (g_1(u, v), g_2(u, v))$

and $g: A \rightarrow \mathbb{R}^2$ with $A \subseteq \mathbb{R}^2$. Let $B \subseteq \mathbb{R}^2$ with $B \cup \partial B \subseteq A$ and let $f: g(B) \rightarrow \mathbb{R}$. Assume that g smooth change of variables.

Then:

$$\iint_{g(B)} f(x, y) dx dy = \iint_B f(g_1(u, v), g_2(u, v)) \left| \frac{\partial(g_1, g_2)}{\partial(u, v)} \right| du dv$$

$$\text{Note } dx dy = \left| \frac{\partial(g_1, g_2)}{\partial(u, v)} \right| du dv$$

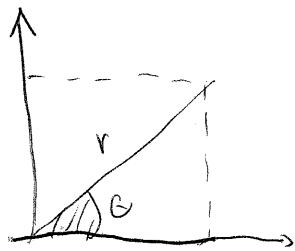
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Application to polar coordinates

- Consider the change of variables

$$x = g_1(r, \theta) = r \cos \theta$$

$$y = g_2(r, \theta) = r \sin \theta$$



or equivalently

$$(x, y) = g(r, \theta) = r(\cos \theta, \sin \theta)$$

- Jacobian: $\frac{\partial(g_1, g_2)}{\partial(r, \theta)} = \begin{vmatrix} \frac{\partial g_1}{\partial r} & \frac{\partial g_1}{\partial \theta} \\ \frac{\partial g_2}{\partial r} & \frac{\partial g_2}{\partial \theta} \end{vmatrix} = \begin{vmatrix} \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{vmatrix} = r(\cos^2 \theta + \sin^2 \theta) = r \neq 0$

$$\forall r > 0$$

Thus changing to polar coordinates is a smooth change of variables provided the origin is excluded and

$$dx dy = r dr d\theta$$

- Double integral over a polar rectangle



Consider the polar rectangle

$$R \cdot [r_1, r_2] \times [\theta_1, \theta_2] = \{(r, \theta) | r \in [r_1, r_2], \theta \in [\theta_1, \theta_2]\}$$

The image of R under change to cartesian coordinates given by

$$g(r, \theta) = (r \cos \theta, r \sin \theta)$$

gives the polar coordinates

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$$g(R) : g([r_1, r_2] \times [\theta_1, \theta_2]) = \{(r \cos \theta, r \sin \theta) \mid r_1 \leq r \leq r_2 \wedge \theta_1 \leq \theta \leq \theta_2\}$$

Let $f: R \rightarrow \mathbb{R}$ be a scalar field. It follows that

$$\iint_{g(R)} f(x, y) dx dy = \iint_R f(r \cos \theta, r \sin \theta) r dr d\theta = \int_{r_1}^{r_2} dr \int_{\theta_1}^{\theta_2} df(r \cos \theta, r \sin \theta) r$$

EXAMPLES

Evaluate the integral $I = \iint_A \cos(\alpha x + \beta y^2) dx dy$ with A given by

$$A = \{(x, y) \in \mathbb{R}^2 \mid 1 \leq x^2 + y^2 \leq 4\}$$

Solution

We note that

$$A = \{(x, y) \in \mathbb{R}^2 \mid 1 \leq x^2 + y^2 \leq 4\} = \{(r \cos \theta, r \sin \theta) \mid r \in [1, 2] \wedge \theta \in [0, 2\pi]\}$$

and it follows that.

$$\begin{aligned} I &= \iint_A \cos(\alpha x + \beta y^2) dx dy = \int_1^2 dr \int_0^{2\pi} d\theta r \cos(\alpha r^2) = \int_1^2 dr r \cos(\alpha r^2) \left[\int_0^{2\pi} d\theta \right] \\ &= \int_1^2 dr r \cos(\alpha r^2) 2\pi = 2\pi \int_1^2 r \cos(\alpha r^2) dr \end{aligned}$$

$$\text{Let } t = \alpha r^2 \Rightarrow \begin{cases} dt = 2\alpha r dr \\ g(1) = \alpha \cdot 1^2 = \alpha \\ g(2) = \alpha \cdot 2^2 - 4\alpha \end{cases}$$

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$$\Rightarrow I = \int_{0\pi}^{4\pi} \cos(t) dt = [\sin(t)]_{0\pi}^{4\pi} = \sin(4\pi) - \sin(0\pi) \\ = \sin(0) - \sin(0) \\ = 0 - 0 \\ = 0$$

Application: Gaussian Integral

$$\int_{-\infty}^{+\infty} e^{-x^2} dx = \sqrt{\pi}$$

Proof

Define $I = \int_{-\infty}^{+\infty} e^{-x^2} dx$ and note that

$$\begin{aligned} \text{II} &= \iint_{\mathbb{R}^2} e^{-(x^2+y^2)} dx dy = \int_{-\infty}^{+\infty} dx \int_{-\infty}^{+\infty} e^{-(x^2+y^2)} dy = \int_{-\infty}^{+\infty} dx e^{-x^2} \left[\int_{-\infty}^{+\infty} e^{-y^2} dy \right] \\ &= \int_{-\infty}^{+\infty} dx e^{-x^2} \\ &= I \int_{-\infty}^{+\infty} dx e^{-x^2} \\ &= I \cdot I \\ &= I^2 \end{aligned}$$

We now calculate I

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$$\begin{aligned}
 I &= \iint_{\mathbb{R}^2} e^{-(x^2+y^2)} dx dy = \int_0^{+\infty} dr \int_0^{2\pi} d\theta r e^{-r^2} \\
 &= \int_0^{+\infty} dr r e^{-r^2} \left[\int_0^{2\pi} d\theta \right] \\
 &= \int_0^{+\infty} 2\pi r e^{-r^2} dr \\
 &= 2\pi \int_0^{+\infty} r e^{-r^2} dr
 \end{aligned}$$

$$\begin{aligned}
 \text{Let } P &= -r^2 \Rightarrow \begin{cases} dP = -2r dr \Rightarrow r dr = (-\frac{1}{2})dP \\ g(\theta) = 0 \\ g(t\theta) = \ln(-r^2) = -2 \end{cases} \\
 &= g(r)
 \end{aligned}$$

$$\begin{aligned}
 \Rightarrow I &= 2\pi \int_0^{+\infty} e^{P(-\frac{1}{2})} dP = -\pi \int_0^{+\infty} e^P dP = -\pi \left[e^P \right]_0^{+\infty} \\
 &= -\pi \left[\lim_{P \rightarrow +\infty} e^P - e^0 \right] \\
 &= -\pi [0 - 1] = \pi
 \end{aligned}$$

$$\Rightarrow I^2 = \pi \Rightarrow I = \sqrt{\pi} \vee I = -\sqrt{\pi}$$

$$\text{Since } \forall x \in \mathbb{R}: e^{x^2} > 0 \Rightarrow \int_{-\infty}^{+\infty} e^{x^2} dx > 0 \Rightarrow I > 0$$

and therefore $I = \sqrt{\pi}$

(the solution $I = -\sqrt{\pi}$ is rejected)

Definition of the triple integral

- Let $A \subseteq \mathbb{R}^3$ be a rectangular region given by

$$A = [a_1, a_2] \times [b_1, b_2] \times [c_1, c_2]$$

$$= \{(x, y, z) \in \mathbb{R}^3 \mid x \in [a_1, a_2] \wedge y \in [b_1, b_2] \wedge z \in [c_1, c_2]\}$$

and consider a scalar field $f: A \rightarrow \mathbb{R}$, such as f continuous on A . We define the triple integral of f over A as,

$$\iiint_A f(x, y, z) dx dy dz = \int_{a_1}^{a_2} dx \int_{b_1}^{b_2} dy \int_{c_1}^{c_2} dz f(x, y, z)$$

It can be shown that permuting the order of the integrals gives the same result.

- Consider now a more general closed and bounded region $A \subseteq \mathbb{R}^3$ and let $f: A \rightarrow \mathbb{R}$ be a scalar field. Thus there is a rectangular region

$$A: [a_1, a_2] \times [b_1, b_2] \times [c_1, c_2]$$

Thus we may define the integral of f over A as,

$$\iiint_A f(x, y, z) dx dy dz = \iint_R f(x, y, z) dx dy dz$$

EXAMPLE

Evaluate $I = \iiint_A x^2yz \, dx \, dy \, dz$ with

$$A = [1, 2] \times [0, 1] \times [0, 2]$$

Solution

$$\begin{aligned} I &= \iiint_A x^2yz \, dx \, dy \, dz = \int_1^2 dx \int_0^1 dy \int_0^2 dz x^2yz \\ &= \int_1^2 dx x^2 \left[\int_0^1 dy \int_0^2 dz yz \right] \\ &= \left[\int_1^2 x^2 dx \right] \left[\int_0^1 dy y \left(\int_0^2 dz z \right) \right] \\ &= \left[\int_1^2 x^3 dx \right] \left[\int_0^1 y^2 dy \right] \left[\int_0^2 z^2 dz \right] \end{aligned}$$

with

$$f_1 = \int_1^2 x^3 dx = \left[\frac{x^4}{4} \right]_1^2 = \frac{2^4 - 1^4}{4} = \frac{15}{4} = \frac{7}{3}$$

$$f_2 = \int_0^1 y^2 dy = \left[\frac{y^3}{3} \right]_0^1 = \frac{1^3 - 0^3}{3} = \frac{1}{3}$$

$$f_3 = \int_0^2 z^2 dz = \left[\frac{z^3}{3} \right]_0^2 = \frac{2^3 - 0^3}{3} = \frac{8}{3}$$

and therefore

$$I = f_1 f_2 f_3 = \frac{7}{3} \cdot \frac{1}{3} \cdot \frac{8}{3} = \frac{56}{27}$$

Tuesday Week 9

In general, given a region

$$A = [a_1, b_1] \times [a_2, b_2] \times [a_3, b_3]$$

It can be shown that

$$\begin{aligned} I &= \iiint_A f_1(x) f_2(y) f_3(z) dx dy dz \\ &= \left[\int_{a_1}^{b_1} f_1(x) dx \right] \left[\int_{a_2}^{b_2} f_2(y) dy \right] \left[\int_{a_3}^{b_3} f_3(z) dz \right] \end{aligned}$$

Evaluation of triple Integrals

① \mathbb{Z} -Simple Regions

For $A = \{(x, y, z) \in \mathbb{R}^3 \mid (x, y) \in S_{xy}, g_1(x, y) \leq z \leq g_2(x, y)\}$

$$\Rightarrow \iiint_A f(x, y, z) dx dy dz = \iint_{S_{xy}} dx dy \int_{g_1(x, y)}^{g_2(x, y)} dz \cdot f(x, y, z)$$

② x -Simple

For $A = \{(x, y, z) \in \mathbb{R}^3 \mid (y, z) \in S_{yz}, g_1(y, z) \leq x \leq g_2(y, z)\}$

$$\Rightarrow \iiint_A f(x, y, z) dx dy dz = \iint_{S_{yz}} dy dz \int_{g_1(y, z)}^{g_2(y, z)} dx \cdot f(x, y, z)$$

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③ y -simple regions

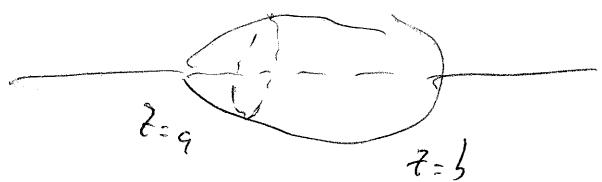
For $A = \{(x, y, z) \in \mathbb{R}^3 \mid (x, z) \in S_{xz}, g_1(x, z) \leq y \leq g_2(x, z)\} \Rightarrow$

$$\iiint_A f(x, y, z) dx dy dz = \iint_{S_{xz}} dx dz \int_{g_1(x, z)}^{g_2(x, z)} dy f(x, y, z)$$

④ xy -Simple regions

For $A = \{(x, y, z) \in \mathbb{R}^3 \mid z \in [a, b] \wedge (x, y) \in S_{xy}(z)\} \Rightarrow$

$$\iiint_A f(x, y, z) dx dy dz = \int_a^b dz \iint_{S_{xy}(z)} dx dy f(x, y, z)$$



⑤ yz -Simple regions

For $A = \{(x, y, z) \in \mathbb{R}^3 \mid x \in [a, b] \wedge (y, z) \in S_{yz}(x)\} \Rightarrow$

$$\iiint_A f(x, y, z) dx dy dz = \int_a^b dx \iint_{S_{yz}(x)} dy dz f(x, y, z)$$

⑥ xz -Simple regions

For $A = \{(x, y, z) \in \mathbb{R}^3 \mid y \in [a, b] \wedge z \in S_{xz}(y)\} \Rightarrow$

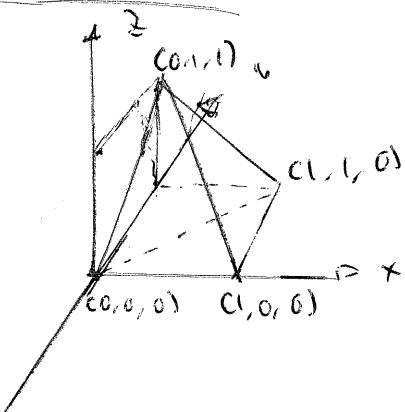
$$\iiint_A f(x, y, z) dx dy dz = \int_a^b dy \iint_{S_{xz}(y)} dx dz f(x, y, z)$$

Wednesday week 4

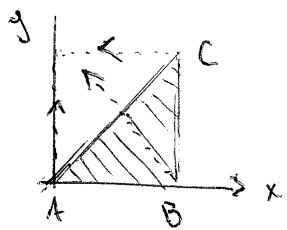
$$\text{Evaluate } I = \iiint_A xy \, dx \, dy \, dz$$

with A a tetrahedron with vertices $(0,0,0)$, $(1,0,0)$, $(1,1,0)$, $(0,1,1)$

Solution



xy cross-section at $z=0$

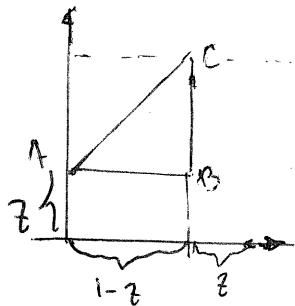


$$A: (0,0,0) \rightarrow (0,1,1) \Rightarrow (0,z,z)$$

$$B: (1,0,0) \rightarrow (0,1,1) \Rightarrow (1-z,z,z)$$

$$C: (0,1,0) \rightarrow (0,1,1) \Rightarrow (1-z,1,z)$$

xy cross-section at $z \in \text{Conv}$



$$A = \{(x,y,z) \in \mathbb{R}^3 \mid z \in [0,1] \wedge (x,y) \in S_{xy}(z)\}$$

$$S_{xy} = \{(x,y) \in \mathbb{R}^2 \mid y \in [z,1] \wedge f_1(y,z) \leq x \leq 1-z\}$$

To determine $f_1(y, z)$ and $f_2(y, z)$, let $D \in AC$ and $E \in BC$ such that $y_D = y_E = y$. Then we see that $f_1(y, z) = x_D$ and $f_2(y, z) = x_E$.

We note that

$$\begin{aligned} D \in AC &\Leftrightarrow \frac{y_D - y_A}{x_D - x_A} = \frac{y_C - y_A}{x_C - x_A} \Leftrightarrow \\ &\Leftrightarrow \frac{y - z}{f_1(y, z) - 0} = \frac{1 - z}{(1 - z) - 0} \Leftrightarrow \\ &\Leftrightarrow \frac{y - z}{f_1(y, z)} = 1 \Leftrightarrow f_1(y, z) = y - z \end{aligned}$$

Since BC is vertical (i.e. $x_B = x_C = 1 - z$) it follows that $f_2(y, z) = x_E = x_B = 1 - z$

and therefore

$$S_{xy}(z) = \{(x, y) \in \mathbb{R}^2 \mid z \leq y \leq 1 \wedge y - z \leq x \leq 1 - z\}$$

The trapezoid itself is represented by

$$A = \{(x, y, z) \in \mathbb{R}^3 \mid (x, y) \in S_{xy}(z), z \in [0, 1]\}$$

we may now evaluate the integral

$$\begin{aligned} I &= \iiint_A xy \, dx \, dy \, dz = \int_0^1 dz \iint_{S_{xy}(z)} xy \, dx \, dy = \int_0^1 dz \int_z^1 dy \int_{y-z}^{1-z} dx \, xy = \int_0^1 dz \int_z^1 dy \, y \left[\int_{y-z}^{1-z} x \, dy \right] \\ &= \int_0^1 dz \int_z^1 dy \, y \left[\frac{x^2}{2} \right]_{y-z}^{1-z} = \int_0^1 dz \int_z^1 dy \, y \left[\frac{(1-z)^2 - (y-z)^2}{2} \right] = \frac{1}{2} \int_0^1 dz \int_z^1 dy \, y \left[(1-z^2 + z^2) - (y^2 - 2yz + z^2) \right] \\ &= \frac{1}{2} \int_0^1 dz \int_z^1 dy \, y (1 - 2z - y^2 + 2yz) = \frac{1}{2} \int_0^1 dz \int_z^1 dy (y - z) y^2 (1 - z^2 + 2z) = \\ &= \frac{1}{2} \int_0^1 dz \left[\frac{y^2}{2} - y^2 z - \frac{y^4}{4} + \frac{2y^3 z}{3} \right]_z^1 = \frac{1}{2} \int_0^1 dz \left[6y^2 - 12y^2 z - 3y^4 + 8y^3 z \right]_z^1 = \end{aligned}$$

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$$= \frac{1}{24} \int_0^1 dz [6(1-z^2) - 12(1-z^2)z - 3(1-z^4) + 8(1-z^3)z] =$$

$$= \frac{1}{24} \int_0^1 dz [6 - \underline{6z^2} - \underline{12z} + \underline{12z^3} - 3 + \underline{3z^4} + \underline{8z} - \underline{8z^4}] =$$

$$= \frac{1}{24} \int_0^1 dz [(3-8)z^4 + 12z^3 - 6z^2 + (-12+8)z + (6-3)] =$$

$$= \frac{1}{24} \int_0^1 dz (-5z^4 + 12z^3 - 6z^2 - 4z + 3) =$$

$$= \frac{1}{24} \left[-\frac{5z^5}{5} + 12\frac{z^4}{4} - 6\frac{z^3}{3} - 4\frac{z^2}{2} + 3z \right]_0^1 :$$

$$= \frac{1}{24} \left[-z^5 + 3z^4 - 2z^3 - 2z^2 + 3z \right]_0^1 =$$

$$= \frac{1}{24} [-1 + 3 - 2 - 2 + 3]$$

$$= \frac{1}{24}$$

Evaluation of a 3×3 determinant

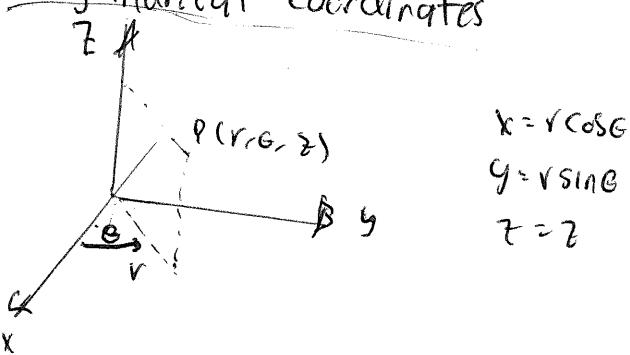
Wednesday week 4

3×3 determinant can be evaluated as

$$\begin{vmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{vmatrix} = (a_1 b_2 c_3 + b_1 c_2 a_3 + c_1 a_2 b_3) - (a_3 b_2 c_1 + b_3 c_2 a_1 + c_3 a_2 b_1)$$

$\downarrow \quad \downarrow \quad \downarrow$
 $\downarrow \quad \downarrow \quad \downarrow$
 $+ \quad + \quad +$

Cylindrical coordinates



$$\begin{aligned} x &= r \cos \theta \\ y &= r \sin \theta \\ z &= z \end{aligned}$$

$$\text{Jacobian: } \frac{\partial(x, y, z)}{\partial(r, \theta, z)} = r \quad \text{Differential: } dx dy dz = r dr d\theta dz$$

Proof

For $x = r \cos \theta$, $y = r \sin \theta$, $z = z$, we have

$$\frac{\partial(x, y, z)}{\partial(r, \theta, z)} = \begin{vmatrix} \frac{\partial x}{\partial r} & \frac{\partial x}{\partial \theta} & \frac{\partial x}{\partial z} \\ \frac{\partial y}{\partial r} & \frac{\partial y}{\partial \theta} & \frac{\partial y}{\partial z} \\ \frac{\partial z}{\partial r} & \frac{\partial z}{\partial \theta} & \frac{\partial z}{\partial z} \end{vmatrix} = \begin{vmatrix} \cos \theta & -r \sin \theta & 0 \\ \sin \theta & r \cos \theta & 0 \\ 0 & 0 & 1 \end{vmatrix}$$

$$= \begin{vmatrix} \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{vmatrix} = \cos \theta (r \cos \theta) - \sin \theta (-r \sin \theta) = r (\cos^2 \theta + \sin^2 \theta) = r$$

Let $A = \{(r\cos\theta, r\sin\theta, z) | (r, \theta), z \in S\} = g(S)$ Wednesday week 4

Let $f: A \rightarrow \mathbb{R}$ with $A \subseteq \mathbb{R}^3$ be a scalar field.

Let $g(r, \theta, z) = (r\cos\theta, r\sin\theta, z) = (x, y, z)$ be the transformation

$g: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ to cylindrical coordinates.

Let $S \subseteq \mathbb{R}^2$ with $g(S) \subseteq A$. Then

$$\iiint_{g(S)} f(x, y, z) dx dy dz = \iiint_S f(r\cos\theta, r\sin\theta, z) r dr d\theta dz$$

Example

Evaluate the integral $I = \iiint_A (x^2 + y^2) dx dy dz$

with A given by

$$A = \{(x, y, z) \in \mathbb{R}^3 | x \in [-2, 2], y \in [-\sqrt{4-x^2}, \sqrt{4-x^2}], z \in [\sqrt{x^2+y^2}, 2]\}$$

by converting to cylindrical coordinates

Solution

First we determine the domain B of the cylindrical integral

$$\text{Let } x = r\cos\theta, y = r\sin\theta, z = z. \text{ Then } x^2 + y^2 = r^2$$

we note that

$$y \in [-\sqrt{4-x^2}, \sqrt{4-x^2}] \Leftrightarrow -\sqrt{4-x^2} \leq y \leq \sqrt{4-x^2} \Leftrightarrow |y| \leq \sqrt{4-x^2} = \sqrt{r^2-x^2}$$

$$\Leftrightarrow |y| \leq (\sqrt{4-x^2})^2 \Leftrightarrow y^2 \leq 4-x^2 \Leftrightarrow x^2+y^2 \leq 4 \Leftrightarrow 0 \leq r^2 \leq 4$$

$$\Leftrightarrow 0 \leq r \leq 2. \text{ (since } x^2+y^2 \geq 0 \text{ } \forall x, y \in \mathbb{R}\text{)}$$

Wednesday week 4

and

$$z \in [\sqrt{x^2+y^2}, 2] \Leftrightarrow \sqrt{x^2+y^2} \leq z \leq 2 \Leftrightarrow r \leq z \leq 2$$

The condition $x \in [-2, 2]$ is implied by the condition on y via the domain restriction $4-x^2 \geq 0$, so it is redundant and does not introduce further restrictions.

$$\text{Indeed: } |x| = |\operatorname{rcos}\theta| = |r||\cos\theta| \leq |r| = r \leq 2 \Rightarrow |x| \leq 2 \Rightarrow x \in [-2, 2]$$

Since there are no restriction on the angle θ we have $\theta \in [0, 2\pi]$

It follows that

$$A = \{(r\cos\theta, r\sin\theta, z) \mid \theta \in [0, 2\pi] \wedge r \in [0, 2] \wedge z \in [r, 2]\}$$

Define

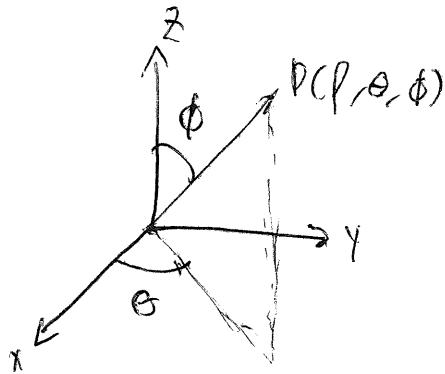
$$B = \{(r\cos\theta, z) \mid \theta \in [0, 2\pi] \wedge r \in [0, 2] \wedge z \in [r, 2]\}$$

Now we change variables and evaluate the integral

$$\begin{aligned} I &= \iiint_A (x^2 + y^2) dx dy dz = \iiint_B r^2 r dr d\theta dz = \iiint_B r^3 dr d\theta dz = \int_0^{2\pi} d\theta \int_0^2 dr \int_r^2 r^3 dr \\ &= \int_0^{2\pi} d\theta \int_0^2 dr r^3 \left[\frac{r^2}{2} \right]_r^2 = \int_0^{2\pi} d\theta \int_0^2 dr r^3 (2-r) = \int_0^{2\pi} d\theta \int_0^2 dr (2r^3 - r^4) = \int_0^{2\pi} d\theta \left[\frac{2r^4}{4} - \frac{r^5}{5} \right]_0^2 \\ &= \left[\frac{r^4}{2} - \frac{r^5}{5} \right]_0^2 \int_0^{2\pi} d\theta = 2\pi \left[\frac{2^4 - 0^4}{2} - \frac{2^5}{5} \right] = 2\pi \left[8 - \frac{32}{5} \right] = 2\pi \frac{40-32}{5} = 2\pi \frac{8}{5} \end{aligned}$$

Thursday week 4

Spherical coordinates



• we define

ρ = distance from origin to P

θ = angle from x -axis to projection of OP onto the xy plane

ϕ = angle fro z -axis to OP .

Note that:

$$\rho \in (0, +\infty) \quad \theta \in [0, 2\pi], \quad \phi \in [0, \pi]$$

we define the transformation from spherical to cartesian coordinates

$$g: (\rho, \theta, \phi) \in (0, +\infty) \times [0, 2\pi] \times [0, \pi] \rightarrow (x, y, z) \in \mathbb{R}^3$$

as follows

$$x = [\rho \sin \phi] \cos \theta$$

$$y = [\rho \sin \phi] \sin \theta$$

$$z = \rho \cos \phi$$

Differential: $dx dy dz = \rho^2 \sin \phi d\rho d\theta d\phi$

Thursday Week 4

- Let $g: [0, +\infty) \times [0, 2\pi) \times [0, \pi] \rightarrow \mathbb{R}^3$ be the transformation from spherical to cartesian coordinates with

$$g(\rho, \theta, \phi) = (\rho \sin \theta \cos \phi, \rho \sin \theta \sin \phi, \rho \cos \theta)$$

Let $B \subseteq \mathbb{R}^3$ such that $g(B) \subseteq A$. Then, it follows that:

$$I = \iiint_{g(B)} f(x, y, z) dx dy dz = \iiint_B f(\rho \sin \theta \cos \phi, \rho \sin \theta \sin \phi, \rho \cos \theta) \rho^2 \sin \theta d\rho d\theta d\phi$$

Proof

Consider the coordinate transformation

$$\begin{cases} x = \rho \sin \theta \cos \phi \\ y = \rho \sin \theta \sin \phi \\ z = \rho \cos \theta \end{cases} \quad \text{with } \rho \in [0, +\infty), \theta \in [0, 2\pi) \text{ and } \phi \in [0, \pi]$$

it follows that

$$\begin{aligned} \frac{\partial(x, y, z)}{\partial(\rho, \theta, \phi)} &= \begin{vmatrix} \frac{\partial x}{\partial \rho} & \frac{\partial x}{\partial \theta} & \frac{\partial x}{\partial \phi} \\ \frac{\partial y}{\partial \rho} & \frac{\partial y}{\partial \theta} & \frac{\partial y}{\partial \phi} \\ \frac{\partial z}{\partial \rho} & \frac{\partial z}{\partial \theta} & \frac{\partial z}{\partial \phi} \end{vmatrix} = \begin{vmatrix} \sin \theta \cos \phi & -\rho \sin \theta \sin \phi & \rho \cos \theta \cos \phi \\ \sin \theta \sin \phi & \rho \sin \theta \cos \phi & \rho \cos \theta \sin \phi \\ 0 & 0 & -\rho \sin \theta \end{vmatrix} \\ &= \cos \theta \begin{vmatrix} -\rho \sin \theta \sin \phi & \rho \cos \theta \cos \phi \\ \rho \sin \theta \cos \phi & \rho \cos \theta \sin \phi \end{vmatrix} = \begin{vmatrix} -\rho \sin \theta & \sin \theta \cos \phi & -\rho \sin \theta \sin \phi \\ \sin \theta \sin \phi & \rho \cos \theta \cos \phi & \sin \theta \cos \phi \end{vmatrix} \\ &= \cos \theta (\rho \sin \theta)(\rho \cos \theta) \begin{vmatrix} -\sin \theta \cos \phi & -\rho \sin \theta (\sin \theta \cos \phi) & (\cos \theta - \sin \theta \sin \phi) \\ \cos \theta \sin \phi & \sin \theta \cos \phi & \sin \theta \cos \phi \end{vmatrix} \end{aligned}$$

Thursday week 4

$$= l^2 \sin \phi \cos^2 \epsilon (-\sin^2 \epsilon - \cos^2 \epsilon) - l^2 \sin^3 \phi (\cos^2 \epsilon + \sin^2 \epsilon) \\ = l^2 \sin \phi \cos^2 \epsilon - l^2 \sin^3 \phi = -l^2 \sin \phi (\cos^2 \epsilon + \sin^2 \epsilon) = -l^2 \sin \phi$$

Alternative calculation for 3×3 matrices

$$\frac{\partial(x, y, z)}{\partial(p, \theta, \phi)} = \begin{vmatrix} \sin \theta \cos \epsilon & -l \sin \phi \sin \epsilon & l \cos \theta \cos \epsilon \\ \sin \theta \sin \epsilon & l \sin \phi \cos \epsilon & l \cos \theta \sin \epsilon \\ \cos \theta & 0 & -l \sin \phi \end{vmatrix} \begin{vmatrix} \sin \theta \cos \epsilon & -l \sin \phi \sin \epsilon \\ \sin \theta \sin \epsilon & l \sin \phi \cos \epsilon \\ \cos \theta & 0 \end{vmatrix}$$

$$= (\sin \theta \cos \epsilon)(l \sin \phi \cos \epsilon)(-l \sin \phi) + (-l \sin \phi \sin \epsilon)(l \cos \theta \sin \epsilon) \cos \theta + \\ - (\cos \theta)(l \sin \phi \cos \epsilon)(l \cos \theta \cos \epsilon) - 0 - (l \sin \phi)(\sin \theta \sin \epsilon)(-l \sin^2 \phi \sin \epsilon)$$

$$= -l^2 \sin^3 \phi \cos^2 \epsilon - l^2 \sin \phi (\cos^2 \phi \sin^2 \epsilon) - l^2 (\cos^2 \phi \sin \theta \cos^2 \epsilon) - l^2 \sin^3 \phi \sin^2 \theta$$

$$= -l^2 \sin \phi [\sin^2 \theta \cos^2 \epsilon + \cos^2 \phi \sin^2 \epsilon + \cos^2 \theta \sin^2 \epsilon + \sin^2 \phi \sin^2 \epsilon]$$

$$= -l^2 \sin \phi [\sin^2 \phi (\cos^2 \epsilon + \sin^2 \epsilon) + \cos^2 \phi (\sin^2 \epsilon + \cos^2 \epsilon)]$$

$$= -l^2 \sin \phi [\sin^2 \phi + \cos^2 \phi]$$

$$= -l^2 \sin \phi$$

$$\Rightarrow dx dy dz = \left| \frac{\partial(x, y, z)}{\partial(p, \theta, \phi)} \right| d\theta d\phi = -l^2 \sin \phi |d\theta d\phi| = l^2 |\sin \phi| d\theta d\phi \\ = l^2 \sin \phi d\theta d\phi$$

Note that $\epsilon \in [0, \pi] \Rightarrow \sin \theta \geq 0 \Rightarrow |\sin \theta| = \sin \theta$

Thursday week 4

Example

use spherical coordinates to evaluate the integral

$$I = \iiint_A e^{(x^2+y^2+z^2)^{3/2}} dx dy dz$$

over the region $A = \{(x, y, z) \in \mathbb{R}^3 \mid x^2 + y^2 + z^2 \leq 1\}$

Solution

$$\begin{cases} x = \rho \sin \phi \cos \theta \\ y = \rho \sin \phi \sin \theta \\ z = \rho \cos \phi \end{cases} \quad \begin{array}{l} \text{with } \rho \in [0, +\infty) \\ \theta \in [0, 2\pi) \\ \phi \in [0, \pi] \end{array}$$

We note that

$$x^2 + y^2 + z^2 \leq 1 \Leftrightarrow \rho^2 \leq 1 \Leftrightarrow 0 \leq \rho \leq 1$$

There are no constraints on θ and ϕ

Then let us define

$$B = \{(\rho, \theta, \phi) \mid \rho \in [0, 1], \theta \in [0, 2\pi), \phi \in [0, \pi]\} = [0, 1] \times [0, 2\pi) \times [0, \pi]$$

It follows that

$$\begin{aligned} I &= \iiint_A e^{(x^2+y^2+z^2)^{3/2}} dx dy dz = \iiint_B e^{\rho^3} \rho^2 \sin \phi d\rho d\theta d\phi = \iiint_B \rho^3 \sin \phi d\rho d\theta d\phi \\ &= \int_0^1 d\rho \int_0^{2\pi} d\theta \int_0^\pi \rho^3 \sin \phi d\phi = \left[\int_0^1 d\rho \rho^3 \right] \left[\int_0^\pi d\phi \sin \phi \right] \left[\int_0^\pi d\theta \right] = 2\pi I_1 I_2 \end{aligned}$$

$$\text{with } I_1 = \int_0^1 d\rho \rho^3 \quad \text{and } I_2 = \int_0^\pi d\phi \sin \phi$$

Thursday week 4

This comes from the trick

$$A = [a_1, a_2] \times [b_1, b_2] \times [c_1, c_2]$$

$$\iiint_A f(x) g(y) h(z) dx dy dz = \left[\int_{a_1}^{a_2} f(x) \right] \left[\int_{b_1}^{b_2} g(y) \right] \left[\int_{c_1}^{c_2} h(z) \right]$$

Returning to the problem

To evaluate I_1 :

$$\text{Let } u = e^{\ell^3} = g(\ell) \Rightarrow \begin{cases} du = 3\ell^2 e^{\ell^3} d\ell \\ g(0) = e^0 = 1 \\ g(1) = e^1 = \ell \end{cases}$$

$$\Rightarrow I_1 = \int_1^e \left(\frac{1}{3} \right) du = \frac{1}{3} \int_1^e du = \frac{e-1}{3}$$

To evaluate I_2 :

$$I_2 = \int_0^{\pi} d\phi \sin \phi = \left[-\cos \phi \right]_0^{\pi} = (-\cos \pi) - (-\cos 0) = (-(-1)) - (-1) = 1 + 1 = 2$$

It follows that:

$$I = 2\pi I_1 F, I_2 = 2\pi \left(\frac{e-1}{3} \right) \cdot 2 = \frac{4\pi(e-1)}{3}$$

Thursday Week 4

Vector Fields

Definition

- A three-dimensional vector field f is a mapping $f: A \rightarrow \mathbb{R}^3$ with $A \subseteq \mathbb{R}^3$
- If f is a vector field, we write:
 $f(x, y, z) = (f_1(x, y, z), f_2(x, y, z), f_3(x, y, z))$
- The scalar fields f_1, f_2, f_3 are the components of the vector field f .

Derivative of a vector field

- Let $f: A \rightarrow \mathbb{R}^3$ be a vector with components f_1, f_2, f_3 that are assumed to be partially differentiable. Then we define

a) The divergence of f : $\nabla = (\partial/\partial x, \partial/\partial y, \partial/\partial z)$

$$\nabla \cdot f = \frac{\partial f_1}{\partial x} + \frac{\partial f_2}{\partial y} + \frac{\partial f_3}{\partial z} = \operatorname{div}(f) \leftarrow \text{Divergence}$$

- b) The curl of f

$$\nabla \times f = \begin{vmatrix} e_1 & e_2 & e_3 \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ f_1 & f_2 & f_3 \end{vmatrix}$$

$(\nabla \times f)_1 = \frac{\partial f_3}{\partial y} - \frac{\partial f_2}{\partial z}$
 $(\nabla \times f)_2 = \frac{\partial f_1}{\partial z} - \frac{\partial f_3}{\partial x} = \operatorname{curl}(f)$
 $(\nabla \times f)_3 = \frac{\partial f_2}{\partial x} - \frac{\partial f_1}{\partial y}$

Note that

$\nabla \cdot f$ is a scalar field

$\nabla \times f$ is a vector field

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* Let $\phi: A \rightarrow \mathbb{R}$ be a scalar field with $A \subseteq \mathbb{R}^3$ then we define:

a) The gradient of ϕ

$$\nabla \phi = \left(\frac{\partial \phi}{\partial x}, \frac{\partial \phi}{\partial y}, \frac{\partial \phi}{\partial z} \right)$$

Laplacian

$$\nabla^2 \phi = \nabla \cdot \nabla \phi = \frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} + \frac{\partial^2 \phi}{\partial z^2}$$

$$\nabla^2 f = (\nabla^2 f_1, \nabla^2 f_2, \nabla^2 f_3)$$

Tensor notation

Tensor notation makes it easier to work with the derivatives of vector fields. We follow the following guidelines.

a) We write the vector field "f" as " f_a ", representing the "a" component of f. With tensor notation we always work in terms of the components of the involved vector fields

b) Repeating indices are automatically summed over all components when associated with a product.

$$\text{Example: } f_{a}g_a = f_1g_1 + f_2g_2 + f_3g_3 = f \cdot g$$

represents the dot product However, for the vector sum

$$(f+g)g = f_g + g_g$$

no summation is implied

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c) we abbreviate the partial derivative $\partial/\partial x_a$ as ∂_a
we may thus write:

$$\nabla \cdot f = \partial_a f_a; (\nabla \phi)_a = \partial_a \phi; \nabla^2 \phi = \partial_a \partial_a \phi$$

Notice a scalar - no index

Vector - 1 index

Matrix = 2 indexes

etc

d) To define the curl, we introduce the Levi-Civita tensor ϵ_{abc} as

$$\epsilon_{abc} = \frac{(a-b)(b-c)(c-a)}{2}$$

$$= \begin{cases} +1, & \text{if } (a,b,c) \in \{(1,2,3), (2,3,1), (3,1,2)\} \\ -1, & \text{if } (a,b,c) \in \{(3,2,1), (1,3,2), (2,1,3)\} \\ 0, & \text{if } a=b \vee b=c \vee c=a \end{cases}$$

Then the curl reads

$$(\nabla \times f)_a = \epsilon_{abc} \partial_b$$

Likewise for two vector fields f, g , the cross-product
reads.

$$(f \times g)_a = \epsilon_{abc} f_b g_c$$

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To summarize: Given the vector fields f, g and the scalar field ϕ :

$$(f+g)_a = f_a + g_a$$

$$\nabla \phi = \partial_a \phi$$

$$\nabla \cdot f = \partial_a f_a$$

$$f \cdot g = f_a g_a$$

$$\nabla^2 \phi = \partial_a \partial_a \phi$$

$$\nabla \times f = \epsilon_{abc} \partial_b f_c$$

$$f \times g = \epsilon_{abc} f_b g_c$$

Kronecker delta

we define

$$\delta_{ab} = \begin{cases} 1 & \text{if } a=b \\ 0 & \text{if } a \neq b \end{cases} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

It follows that $\delta_{ab} f_a = \delta_{a1} f_1 + \delta_{a2} f_2 + \delta_{a3} f_3 = f_a$

(because in the implied summation $b=1, 2, 3$, the only non-zero contribution occurs when $a=b$)

Similar contractions are possible. For example

$$\delta_{ab} \epsilon_{acd} = \epsilon_{bcd}$$

(because in the implied summation $a=1, 2, 3$, the only non-zero contribution occurs when $a=b$).

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$$(f+g)_\alpha = f_\alpha + g_\alpha$$

$$f \circ g = f_\alpha g_\alpha$$

$$(f \times g) = \epsilon_{\alpha b c} f_b g_c$$

$$\nabla \cdot f = \partial_\alpha f_\alpha$$

$$(\nabla \times f)_\alpha = \epsilon_{abc} \partial_b f_c$$

$$(\nabla \phi)_\alpha = \partial_\alpha \phi$$

$$\nabla^2 \phi = \partial_\alpha \partial_\alpha \phi$$

$$\delta_{\alpha b} = \begin{cases} 1 & \text{if } \alpha = b \\ 0 & \text{if } \alpha \neq b \end{cases}$$

$$\delta_{\alpha b} f_b = f_\alpha$$

Properties $\epsilon_{\alpha b c}$ (Levi-Civita tensor)

$$1) \epsilon_{\alpha b c} f_b f_c = \partial_\alpha$$

$$\epsilon_{\alpha b c} \partial_b \partial_c = \partial_\alpha$$

$$2) \epsilon_{\alpha b c} = \epsilon_{b \alpha c} = \epsilon_{c \alpha b}$$

$$\epsilon_{\alpha b c} = -\epsilon_{c b \alpha}$$

$$3) \epsilon_{\alpha b c} \epsilon_{p q r} = \begin{vmatrix} \delta_{\alpha p} & \delta_{\alpha q} & \delta_{\alpha r} \\ \delta_{b p} & \delta_{b q} & \delta_{b r} \\ \delta_{c p} & \delta_{c q} & \delta_{c r} \end{vmatrix}$$

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$$4) \epsilon_{abc} \epsilon_{\alpha pq} = \delta_{bp} \delta_{cq} - \delta_{bq} \delta_{cp}$$

$$\epsilon_{abc} \epsilon_{abq} = 2 \delta_{pq}$$

$$\epsilon_{abc} \epsilon_{abc} = 6$$

$$1) \nabla \times (\nabla \phi) = 0$$

Proof

$$\begin{aligned} [\nabla \times (\nabla \phi)]_c &= \epsilon_{abc} \partial_b (\nabla \phi)_c = \epsilon_{abc} \partial_b (\partial_c \phi) \\ &= [\epsilon_{abc} \partial_b \partial_c] \phi \\ &= 0 \quad \text{as } \epsilon_{abc} \partial_b \partial_c = 0 \\ &= 0 \end{aligned}$$

$$\Rightarrow \nabla \times (\nabla \phi) = 0$$

$$2) \nabla \cdot (\nabla \times f) = 0$$

Proof

$$\begin{aligned} \nabla \cdot (\nabla \times f) &= \partial_a (\nabla \times f)_a = \partial_a [\epsilon_{abc} \partial_b f_c] \\ &= \epsilon_{abc} \partial_a \partial_b f_c \\ &= [\epsilon_{cab} \partial_a \partial_b] f_c \\ &= 0 \quad \text{as } \epsilon_{cab} \partial_a \partial_b = 0 \\ &= 0 \end{aligned}$$

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$$3) \nabla \times (\nabla \times f) = \nabla(\nabla \cdot f) - \nabla^2 f$$

$$\hookrightarrow \operatorname{curl}(\operatorname{curl}(f)) = \operatorname{grad}(\operatorname{div}(f)) - \Delta f$$

Proof

$$\begin{aligned}
 [\nabla \times (\nabla \times f)]_\alpha &= \epsilon_{abc} \partial_b (\nabla \times f)_c \\
 &= \epsilon_{abc} \partial_b [\epsilon_{cpq} \partial_p f_q] \\
 &= \epsilon_{abc} \epsilon_{cpq} \partial_b \partial_p f_q \\
 &= \epsilon_{cab} \epsilon_{cpq} \partial_b \partial_p f_q \\
 &= [\delta_{ap} \delta_{bq} - \delta_{aq} \delta_{bp}] \partial_b \partial_p f_q \\
 &= \underbrace{\delta_{ap} \delta_{bq} \partial_b \partial_p f_q}_{\partial_b \partial_a f_b} - \underbrace{\delta_{aq} \delta_{bp} \partial_b \partial_p f_q}_{\partial_b \partial_b f_a} \\
 &= \partial_a (\partial_b f_b) - \nabla^2 f_\alpha \\
 &= \partial_\alpha (\nabla \cdot f) - (\nabla^2 f)_\alpha \\
 &= [\nabla(\nabla \cdot f)]_\alpha - (\nabla^2 f)_\alpha \\
 &= [\nabla(\nabla \cdot f) - \nabla^2 f]_\alpha
 \end{aligned}$$

Another property

$$\partial \cdot (b \times c) = b \cdot (c \times \partial)$$

$$\nabla \cdot (\phi f) = f \cdot \nabla \phi + \phi \nabla \cdot f \rightarrow \operatorname{div}(\phi f) = f \cdot \operatorname{grad}(\phi) + \phi \operatorname{div}(f)$$

Proof

$$\begin{aligned}\nabla \cdot (\phi f) &= \partial_\alpha (\phi f)_\alpha = \partial_\alpha (\phi f_\alpha) \\ &= f_\alpha (\partial_\alpha \phi) + \phi \partial_\alpha f_\alpha \\ &= f_\alpha (\nabla \phi)_\alpha + \phi \nabla \cdot f \\ &= f \cdot (\nabla \phi) + \phi \nabla \cdot f\end{aligned}$$

Line Integrals

- Line integrals are integrals of vector fields over a path
- Definition concerning paths
- Let $a: I \rightarrow \mathbb{R}^n$ be a vector-valued function

a is a path $\iff \begin{cases} \exists t_1, t_2 \in \mathbb{R}: I = [t_1, t_2] \\ a \text{ continuous at } [t_1, t_2] \end{cases}$

Furthermore, if a is a path we say that

a is a closed path $\iff a(t_1) = a(t_2)$

a is an open path $\iff a(t_1) \neq a(t_2)$

We say that: $a(t_1)$ = initial point

$a(t_2)$ = final point

- (Contd.) a path $a: [t_1, t_2] \rightarrow \mathbb{R}^n$ we say that

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a smooth path \Leftrightarrow $\begin{cases} a \text{ continuous at } [t_1, t_2] \\ a \text{ differentiable at } (t_1, t_2) \\ a \text{ continuous at } (t_1, t_2) \end{cases}$

- Let $a: [t_1, t_2] \rightarrow \mathbb{R}^n$ be a path and let $B \subseteq [t_1, t_2]$.
The restriction of " a " to B is denoted as,

$$b = a|_B \Leftrightarrow \begin{cases} b: B \rightarrow \mathbb{R}^n \\ \forall t \in B: b(t) = a(t) \end{cases}$$

- Let $a: [t_1, t_2] \rightarrow \mathbb{R}^n$ be a path we say that a piecewise smooth path \Leftrightarrow

$\Leftrightarrow \exists \exists \tau_0, \tau_1, \dots, \tau_n \in [t_1, t_2]: t_1 = \tau_0 < \tau_1 < \tau_2 < \dots < \tau_n = t_2$
 $\forall n \in \mathbb{N}_0: a|_{[\tau_{k-1}, \tau_k]}$ is a smooth path

Example

A piecewise smooth path may look like this



Connected Sets

Friday week 4

- Let $x, y \in \mathbb{R}^n$ be given points. we define

$P_A(x, y)$ = The set of all piecewise smooth paths in A with initial point x and final point y

- Let $A \subseteq \mathbb{R}^n$ be a given region. We say that

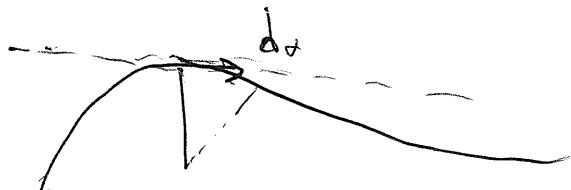
- A path-connected $\Leftrightarrow \forall x, y \in A : P_A(x, y) \neq \emptyset$
- A path-disconnected $\Leftrightarrow \exists x, y \in A : P_A(x, y) = \emptyset$

Interpretation: In a path-connected set A , every two points $x, y \in A$ are connected by at least one.

Definition of line integral

Let $\alpha: [t_1, t_2] \rightarrow \mathbb{R}^n$ be piecewise smooth path, and let $f: A \rightarrow \mathbb{R}^n$ such that $\alpha([t_1, t_2]) \subseteq A$.
We define

$$\int f \cdot d\alpha = \int_{t_1}^{t_2} dt \left[f(\alpha(t)) \cdot \dot{\alpha}(t) \right]$$



$$f \cdot \int d\alpha$$

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Notation

$$C: \alpha(t) = (\alpha_1(t), \alpha_2(t), \dots, \alpha_n(t))$$

$$\int f \cdot d\alpha = \int_C f \cdot d\lambda$$

$$f(x) = (f_1(x), f_2(x), \dots, f_n(x))$$

$$\int f \cdot d\alpha = \int f_1 d\alpha_1 + f_2 d\alpha_2 + \dots + f_n d\alpha_n = \int_C f_1 dx_1 + f_2 dx_2 + \dots + f_n dx_n$$

For a two dimensional field $f(x,y)$ and on path

$$C: \alpha(t) = (\alpha_1(t), \alpha_2(t)) \quad t \in [t_1, t_2]$$

$$f(x,y) = (f_1(x,y), f_2(x,y))$$

$$\int f \cdot d\alpha = \int_C f_1(x,y) dx + f_2(x,y) dy$$

$$= \int_{t_1}^{t_2} dt [f_1(\alpha_1(t), \alpha_2(t)) \alpha_1'(t) + f_2(\alpha_1(t), \alpha_2(t)) \alpha_2'(t)]$$