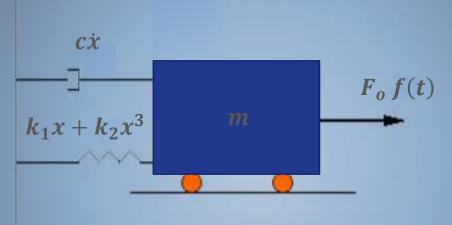
# 34th Annual Texas Differential Equations Conference University of Texas-Pan American

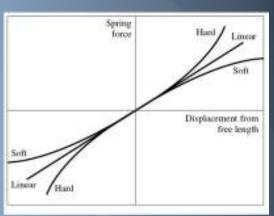
One Solution of the Duffing Equation by Using the Finite Element Method

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# Duffing Equation Mechanical Vibrations





$$\ddot{x} + \delta \dot{x} + \gamma x + \beta x^3 = a_0 f(t)$$

$$\boldsymbol{\delta} = \frac{c}{m}$$
 ,  $\gamma = \frac{k_1}{m}$  ,  $\beta = \frac{k_2}{m}$  ,  $\alpha_o = \frac{F_o}{m}$ 

m mass of the body

c damping coefficient

 $k_1$  spring coefficient

 $k_2 > 0$  hard spring

 $k_2 < 0$  soft spring

# Duffing Equation We propose an approximate solution

$$\tilde{x} = \sum_{j=1}^{n} a_j \ \varphi_j(t)$$

 $a_i$  unknown parameters

 $\varphi_i$  known functions

*n* number of terms

$$R = \ddot{\tilde{x}} + \delta \dot{\tilde{x}} + \gamma \tilde{x} + \beta \tilde{x}^3 - a_0 f(t)$$

**R** Residual function

We divide the domain of the time in finite elements



For each element we can propose the following:

The average weighted of the residual function will be equal to zero

$$\int_{a}^{b} R(t) \, \varphi_i(t) \, dt = 0$$

$$i = 1, 2, ..., n$$

We obtain an integral equation

$$\int_{a}^{b} \ddot{x} \varphi_{i}(t) dt + \int_{a}^{b} \delta \dot{x} \varphi_{i}(t) dt + \int_{a}^{b} \gamma \tilde{x} \varphi_{i}(t) dt +$$

$$\int_a^b \beta \, \tilde{x}^3 \, \varphi_i(t) \, dt - \int_a^b a_o \, f(t) \, \varphi_i(t) \, dt = 0$$

Now we perform a parts integration with the first term of the integral equation

$$-\int_{a}^{b} \dot{\tilde{x}} \, \dot{\varphi}_{i}(t) \, dt + \int_{a}^{b} \delta \, \dot{\tilde{x}} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{a}^{b} \gamma \, \tilde{x} \, \varphi_{i}(t) \, dt + \int_{$$

$$\int_{a}^{b} \beta \, \tilde{x}^{3} \, \varphi_{i}(t) \, dt = \int_{a}^{b} a_{o} \, f(t) \, \varphi_{i}(t) \, dt - \dot{\tilde{x}} \varphi_{i} \Big|_{a}^{b}$$

# Duffing Equation The approximate solution

$$\widetilde{x} = \sum_{j=1}^{n} a_j \, \varphi_j$$

$$\dot{\tilde{x}} = \sum_{j=1}^{n} a_j \, \dot{\varphi}_j$$

We obtain the following elemental equation

$$\sum_{j=1}^{n} R_{ij} \ a_j = F_i$$

#### The terms

$$R_{ij} = -M_{ij} + C_{ij} + K_{ij} + D_{ij}$$

$$M_{ij} = \int_a^b \dot{\varphi}_i \ \dot{\varphi}_j \ dt$$

$$C_{ij} = \int_{a}^{b} \delta \, \varphi_i \, \dot{\varphi}_j \, dt$$

$$K_{ij} = \int_{a}^{b} \gamma \; \varphi_{i} \; \varphi_{j} \; dt$$

$$K_{ij} = \int_a^b \gamma \, \varphi_i \, \varphi_j \, dt \qquad D_{ij} = \int_a^b \beta \left( \sum_{l=1}^n a_l \, \varphi_l \right)^2 \, \varphi_i \, \varphi_j \, dt$$

$$F_i = \int_a^b a_o f(t) \varphi_i dt - \dot{\tilde{x}} \varphi_i \Big|_a^b$$

Non linear term

## First Approximation

$$n=2$$

$$n=2 \tilde{x} = a_1 \varphi_1 + a_2 \varphi_2$$

$$\varphi_1 = \frac{b-t}{L} \qquad \qquad \varphi_2 = \frac{t-a}{L}$$

$$\varphi_2 = \frac{t - a}{L}$$

$$L = b - a$$

$$\begin{bmatrix} R_{11} & R_{12} \\ R_{21} & R_{22} \end{bmatrix} \begin{Bmatrix} a_1 \\ a_2 \end{Bmatrix} = \begin{Bmatrix} F_1 \\ F_2 \end{Bmatrix}$$

**Elemental Matrix** 

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### **Duffing Equation**

#### The terms of the elemental matrix

$$R_{11} = \frac{1}{3}\gamma L - \frac{1}{2}\delta - \frac{1}{L} + \frac{1}{30}\beta L (6 a_1^2 + 3 a_1 a_2 + a_2^2)$$

$$R_{12} = \frac{1}{6}\gamma L + \frac{1}{2}\delta + \frac{1}{L} + \frac{1}{60}\beta L (3 a_1^2 + 4 a_1 a_2 + 3 a_2^2)$$

$$R_{21} = \frac{1}{6}\gamma L - \frac{1}{2}\delta + \frac{1}{L} + \frac{1}{60}\beta L (3 a_1^2 + 4 a_1 a_2 + 3 a_2^2)$$

$$R_{22} = \frac{1}{3}\gamma L + \frac{1}{2}\delta - \frac{1}{L} + \frac{1}{30}\beta L (a_1^2 + 3 a_1 a_2 + 6 a_2^2)$$

$$F_1 = \left(\frac{a_o}{L}\right) \int_a^b f(t) (b-t) dt + v_a \qquad F_2 = \left(\frac{a_o}{L}\right) \int_a^b f(t) (t-a) dt \quad v_b$$

# **Duffing Equation** The assembly of the elements

$$\begin{bmatrix} R_{11}^{(1)} & R_{12}^{(1)} & 0 \\ R_{21}^{(1)} & R_{22}^{(1)} + R_{11}^{(2)} & R_{12}^{(2)} \\ 0 & R_{21}^{(2)} & R_{22}^{(2)} \end{bmatrix} \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix} = \begin{pmatrix} g_1 + v_1 \\ g_2 \\ g_3 - v_3 \end{pmatrix}$$

#### **Initial Conditions**

$$a_1 = x_o$$

$$v_1 = v_o$$

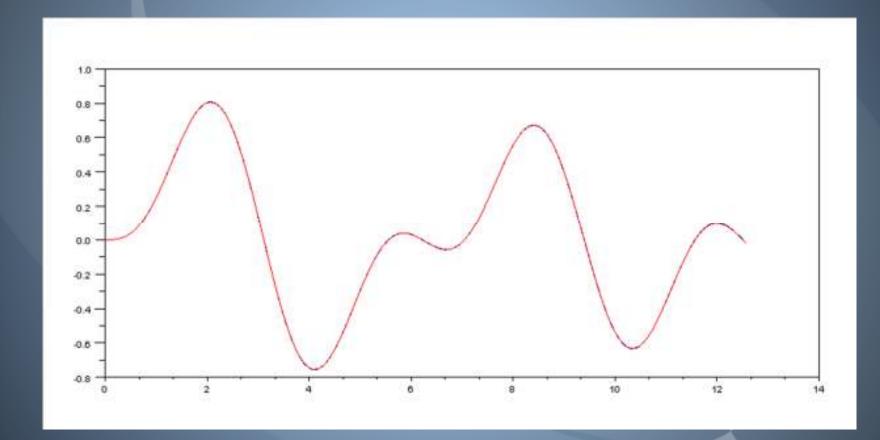
### Applying the initial conditions

$$\begin{bmatrix} R_{12}^{(1)} & 0 & 0 \\ R_{22}^{(1)} + R_{11}^{(2)} & R_{12}^{(2)} & 0 \\ R_{21}^{(2)} & R_{22}^{(2)} & 1 \end{bmatrix} \begin{pmatrix} a_2 \\ a_3 \\ v_3 \end{pmatrix} = \begin{pmatrix} g_1 + v_1 - R_{11}^{(1)} a_1 \\ g_2 - R_{21}^{(1)} a_1 \\ g_3 \end{pmatrix}$$

One case (Linear Problem)

$$\delta = 0.1$$
  $\gamma = 1$   $\beta = 0$   $a_0 = 1$ 

$$f(t) = \sin 2t$$



### <sup>6</sup>it

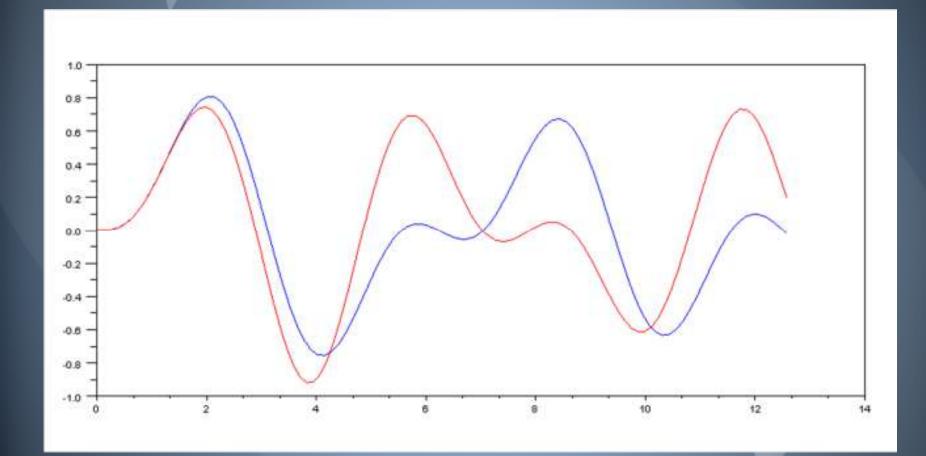
# Duffing Equation Applying the initial conditions

$$\begin{bmatrix} R_{12}^{(1)} & 0 & 0 \\ R_{22}^{(1)} + R_{11}^{(2)} & R_{12}^{(2)} & 0 \\ R_{21}^{(2)} & R_{22}^{(2)} & 1 \end{bmatrix} \begin{Bmatrix} a_2 \\ a_3 \\ v_3 \end{Bmatrix} = \begin{Bmatrix} g_1 + v_1 - R_{11}^{(1)} a_1 \\ g_2 - R_{21}^{(1)} a_1 \\ g_3 \end{bmatrix}$$

Another case

$$\delta = 0.1$$
  $\gamma = 1$   $\beta = 1$   $a_0 = 1$ 

$$f(t) = \sin 2t$$



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# Duffing Equation Applying the initial conditions

$$\begin{bmatrix} R_{12}^{(1)} & 0 & 0 \\ R_{22}^{(1)} + R_{11}^{(2)} & R_{12}^{(2)} & 0 \\ R_{21}^{(2)} & R_{22}^{(2)} & 1 \end{bmatrix} \begin{Bmatrix} a_2 \\ a_3 \\ v_3 \end{Bmatrix} = \begin{Bmatrix} g_1 + v_1 - R_{11}^{(1)} a_1 \\ g_2 - R_{21}^{(1)} a_1 \\ g_3 \end{bmatrix}$$

Another case

$$\delta = 0.1$$
  $\gamma = 1$   $\beta = 2$   $a_0 = 1$ 

$$f(t) = \sin 2t$$

