6.5 Method of least Squares

Inconsistent system. But we want to find (x_1, x_2) that comes as close as passible to being a solution

$$x_{1} + x_{2} = 0$$

$$x_{1} + 2x_{2} = 1$$

$$x_{1} + 3x_{2} = 3$$

$$\begin{bmatrix} 1 & 1 \\ 1 & 2 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} x_{1} \\ x_{2} \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \\ 3 \end{bmatrix}$$

$$A \qquad \vec{X} \qquad \vec{b}$$
If we pick a $\vec{X} = \begin{bmatrix} x_{1} \\ x_{2} \end{bmatrix}$ and compute
$$A\vec{X} = \begin{bmatrix} 1 & 1 \\ 1 & 2 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} x_{1} \\ x_{2} \end{bmatrix},$$

We measure how close this is to solving the system by

$$\begin{split} & A\vec{X} - \vec{b} \qquad (\text{Residual Vector}) \\ & \|A\vec{X} - \vec{b}\| \qquad (\text{Residual error}) \\ & \text{God is to find an } \vec{X} \text{ so that } \|A\vec{X} - \vec{b}\| \\ & \text{is as small as possible.} \end{split}$$

<u>Finding(x_1, x_2)</u> to minimize $||A\vec{X} - \vec{b}||$

 $\begin{bmatrix} 1 & 1 \\ 1 & 2 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \\ 3 \end{bmatrix}$ $x_1 \begin{vmatrix} 1 \\ 1 \\ 1 \end{vmatrix} + x_2 \begin{vmatrix} 1 \\ 2 \\ 2 \end{vmatrix} = \begin{vmatrix} 0 \\ 1 \\ 3 \end{vmatrix}$ No solution for $x_1, x_2 \Rightarrow \begin{bmatrix} 0\\ 1\\ 2 \end{bmatrix}$ is not a linear $\begin{array}{c|c} 1 & 1 \\ combination of & 1 \\ 1 & 2 \\ 1 & 1 \\$ So $\begin{bmatrix} 0 \\ 1 \end{bmatrix}$ is not in span $\left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ 2 \end{bmatrix} \right\}$





 $\vec{b} - A\vec{X}^*$ orthogonal to plane

 $\Rightarrow \vec{b} - A\vec{X}^*$ orthogonal to every vector in plane

$$\Rightarrow \vec{b} - A\vec{X^*} \quad \text{is orthogonal to} \begin{bmatrix} 1\\1\\1 \end{bmatrix}, \begin{bmatrix} 1\\2\\3 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 1\\1\\1\\1 \end{bmatrix} \cdot (\vec{b} - A\vec{X^*}) = 0$$
$$\begin{bmatrix} 1\\2\\3 \end{bmatrix} \cdot (\vec{b} - A\vec{X^*}) = 0 \quad \vec{U} \cdot \vec{V} = 0$$
$$\vec{U}^T \vec{V} = 0$$

$$\Rightarrow [111](\vec{b} - A\vec{X}^*) = 0$$

$$[123](\vec{b} - A\vec{X}^*) = 0$$

$$\Rightarrow \frac{\begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 3 \end{bmatrix}}{A^T}(\vec{b} - A\vec{X}^*) = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\xrightarrow{A^T} A^T(\vec{b} - A\vec{X}^*) = 0$$

$$\Rightarrow A^T(\vec{b} - A\vec{X}^*) = 0$$

$$\Rightarrow A^T\vec{b} - A^TA\vec{X}^* = 0$$

The normal equation of a system

$$A\vec{X} = \vec{b}$$

is

$$A^T A \vec{X} = A^T \vec{b}.$$

A solution \vec{X}^* of the normal eq is called a least squares

solution of $A\vec{X} = \vec{b}$. $||A\vec{X}^* - \vec{b}||$ is

minimized. Also $A\vec{X^*}$ is the projection

of \vec{b} onto the span of the columns of A. (colA)

Least Squares + Projections

1	2		$\left[\begin{array}{c}7\end{array}\right]$
2	1	$\begin{vmatrix} x_1 \\ x_2 \end{vmatrix} =$	3
[1 4	$\begin{bmatrix} x_2 \end{bmatrix}$	1

• Find the least squares solution by solving the normal equation.

$$A = \begin{bmatrix} 1 & 2 \\ 2 & 1 \\ -1 & 4 \\ 2 \times 3 \end{bmatrix} \quad \vec{b} = \begin{bmatrix} 7 \\ 3 \\ 1 \\ 1 \end{bmatrix}$$
$$A^{T}A = \begin{bmatrix} 1 & 2 & -1 \\ 2 & 1 & 4 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 2 & 1 \\ -1 & 4 \end{bmatrix} = \begin{bmatrix} 6 & 0 \\ 0 & 21 \end{bmatrix}$$
$$A^{T}\vec{b} = \begin{bmatrix} 1 & 2 & -1 \\ 2 & 1 & 4 \end{bmatrix} \begin{bmatrix} 7 \\ 3 \\ 1 \end{bmatrix} = \begin{bmatrix} 12 \\ 21 \end{bmatrix}$$

Normal equation $A^T A \vec{X} = A^T \vec{b}$

$$\begin{bmatrix} 6 & 0 \\ 0 & 21 \end{bmatrix} \begin{bmatrix} X_1 \\ X_2 \end{bmatrix} = \begin{bmatrix} 12 \\ 21 \end{bmatrix}$$
$$\begin{bmatrix} 6 & 0 & 12 \\ 0 & 21 & 21 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & 1 \end{bmatrix}$$

The least square solution is $x_1 = 2, x_2 = 1$.

How close is
$$\begin{bmatrix} 2\\1 \end{bmatrix}$$
 to being a solution of

$$\begin{bmatrix} 1 & 2\\2 & 1\\-1 & 4 \end{bmatrix} \begin{bmatrix} x_1\\x_2 \end{bmatrix} = \begin{bmatrix} 7\\3\\1 \end{bmatrix}$$
?
with $\begin{bmatrix} X_1\\X_2 \end{bmatrix} = \begin{bmatrix} 2\\1 \end{bmatrix}$
 $A\vec{X} = \begin{bmatrix} 1 & 2\\2 & 1\\-1 & 4 \end{bmatrix} \begin{bmatrix} 2\\1 \end{bmatrix} = \begin{bmatrix} 4\\5\\2 \end{bmatrix}$
 $\|A\vec{X} - \vec{b}\| = \|\begin{bmatrix} 4\\5\\2 \end{bmatrix} - \begin{bmatrix} 7\\3\\1 \end{bmatrix} \|$
 $= \|\begin{bmatrix} -3\\2\\1 \end{bmatrix} \|$
 $= \sqrt{9 + 4 + 1}$
 $= \sqrt{14} = 3.74$
Finally, $\begin{bmatrix} 4\\5\\2 \end{bmatrix}$ is the projection of $\begin{bmatrix} 7\\3\\1 \end{bmatrix}$ onto the span
 $\begin{bmatrix} 1\\2\\-1 \end{bmatrix}, \begin{bmatrix} 2\\1\\4 \end{bmatrix}.$

• A second approach based on the fact that the columns of A are orthogonal:



of \vec{b} onto the plane



$$\vec{b}_{\text{proj}} = \frac{12}{6} \begin{bmatrix} 1\\2\\-1 \end{bmatrix} + \frac{21}{21} \begin{bmatrix} 2\\1\\4 \end{bmatrix}$$
$$= 2\begin{bmatrix} 1\\2\\-1 \end{bmatrix} + 1\begin{bmatrix} 2\\1\\4 \end{bmatrix}$$
$$\swarrow \qquad \checkmark \qquad \checkmark$$
The least squares solution of $A\vec{X} = \vec{b}$ is $\vec{X} = \begin{bmatrix} 2\\1 \end{bmatrix}$

The projection
$$\vec{b}_{\text{proj}} = \begin{bmatrix} 4\\5\\2 \end{bmatrix}$$