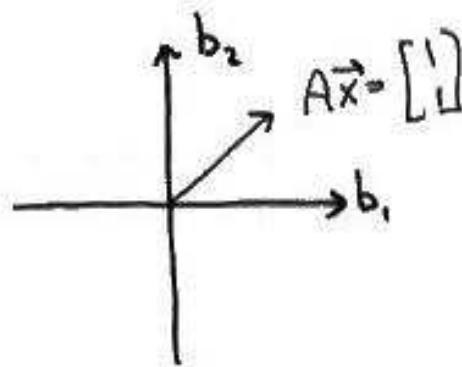
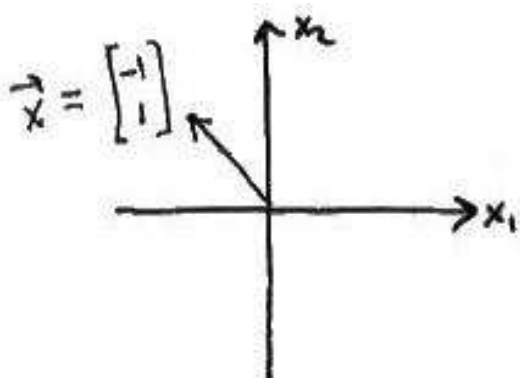


1.8 The Transformation Interpretation of $A\vec{x}$

EX
$$\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \begin{bmatrix} -1 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$
$$A \quad \vec{x} \quad = \quad \vec{b}$$

The matrix A has "transformed" $\begin{bmatrix} -1 \\ 1 \end{bmatrix}$ into $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$



Terminology

1. A transformation T from \mathfrak{R}^n to \mathfrak{R}^m is a rule that converts each \vec{X} in \mathfrak{R}^n into another vector in \mathfrak{R}^m $T : \mathfrak{R}^n \rightarrow \mathfrak{R}^m$
2. \mathfrak{R}^n is called the domain.
 \mathfrak{R}^m is called the codomain.
3. $T(\vec{X})$ is called the image of \vec{X} .
If we find all images, the resolutions set in \mathfrak{R}^m is called the range.
4. A matrix transformation is
$$T(\vec{X}) = A\vec{X}$$
for some matrix A .

EX

$$\begin{array}{ccc} T : \mathfrak{R}^2 & \rightarrow & \mathfrak{R}^2 \\ \uparrow & & \uparrow \\ \text{Domain} & & \text{codomain} \end{array} \quad \text{by } T(\vec{X}) = \begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix} \vec{X}$$

(a) Image of $\begin{bmatrix} 1 \\ 3 \end{bmatrix}$

$$T\left(\begin{bmatrix} 1 \\ 3 \end{bmatrix}\right) = \begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix} \begin{bmatrix} 1 \\ 3 \end{bmatrix} = \begin{bmatrix} 7 \\ 14 \end{bmatrix}$$

(b) Find all \vec{X} in the domain whose image is $\vec{0}$.

$$T(\vec{X}) = \vec{0}$$

$$\begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix} \begin{bmatrix} X_1 \\ X_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & 0 \\ 2 & 4 & 0 \end{bmatrix} \rightsquigarrow \begin{bmatrix} 1 & 2 & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad -2R_1 + R_2$$

$$\begin{array}{rcl} X_1 + 2X_2 & = & 0 \\ X_2 & \text{free} & \end{array} \Rightarrow \begin{array}{rcl} X_1 & = & -2X_2 \\ X_2 & = & X_2 \end{array}$$

$$\vec{X} = \begin{bmatrix} X_1 \\ X_2 \end{bmatrix} = \begin{bmatrix} -2X_2 \\ X_2 \end{bmatrix} = X_2 \begin{bmatrix} -2 \\ 1 \end{bmatrix}$$

